**3GPP TSG-RAN WG4 Meeting # 102-e R4-22xxxxx**

**Electronic Meeting, 21st February – 3rd March, 2022**

**Agenda item:** 5.1.3

**Source:** Moderator (Intel Corporation)

**Title:** Email discussion summary for [102-e][205] Maintenance\_NR\_pos

**Document for:** Information

# Introduction

This email discussion handles the contributions submitted to agenda item 5.1.3.1 and 5.1.3.2 (additional papers of R4-2205441/42/43 are moved from AI 5.1.5.3 to this thread). The scope of this email discussion covers Rel-16 positioning enhancement maintenance, which specifies the UE and BS positioning measurement requirements for both Core and Perf. parts. There are 2 topics (Maintenance to RRM core requirements and maintenance to RRM perf. requirements) in this email discussion and multiple sub-topics within each of them. Note that since this discussion is mainly maintenance work, we will start to agree on CRs and mirror CRs in the first round. In the second round, only the projected contentious issues are discussed. There is no GTW time slot planned so far for this email discussion.

# Topic #1: Maintenance to RRM Core requirements

Topic #1 handles the issue identified to maintain RRM Core requirements for Rel-16 positioning. The previously approved WF related to this topic is in ***R4-2120266***.

## Companies’ contributions summary

|  |  |  |
| --- | --- | --- |
| **T-doc number** | **Company** | **Proposals / Observations** |
| R4-2203869 | CATT | Discussion on R16 NR positioning core requirement maintenance:**Proposal 1: If the PRS/SRS proximity condition is not met, UE can still measure and report the UE Rx-Tx time difference measurement, but the measurement requirements are not applicable.****Proposal 2: If the PRS/SRS proximity condition is not met, the accuracy requirements still apply.** **Proposal 3: When SRS is reconfigured without cell change during the measurement period, UE shall restart the UE Rx-Tx time difference measurement after the SRS reconfiguration on the target cell is complete.** |
| R4-2203870 | CATT | Draft CR on R16 NR positioning measurement requirements (R16) |
| R4-2203871 | CATT | Mirror CR to R4-2203870 |
| R4-2204461 | Qualcomm Incorporated | Remaining issues in NR positioning core requirements:**Proposal 1: When the PRS/SRS proximity condition is not met, UE Rx-Tx time difference measurement requirements do not apply and UE behavior is left to implementation.** |
| R4-2204652 | vivo | Remaining issues on measurement requirements for Rel-16 NR positioning:**Proposal 1: UE still measures and reports UE Rx-Tx measurement if PRS/SRS proximity condition is not met.****Proposal 2: Both UE Rx-Tx measurement period and measurement accuracy requirements apply if PRS/SRS proximity condition is not met.****Proposal 3: When SRS is reconfigured without cell change during the measurement period, UE shall restart the UE Rx-Tx time difference measurement after the SRS reconfiguration on the target cell is complete.** |
| R4-2204654 | vivo | Draft CR to 38.133 correction to NR positioning measurement requirements (R16) |
| R4-2204655 | vivo | Mirror CR to R4-2204654 |
| R4-2205351 | Huawei, HiSilicon | Discussion on remaining issues for positioning measurement requirements:**Proposal 1: UE Rx-Tx measurement requirements, including measurement period requirements and measurement accuracy requirements, do not apply when PRS/SRS proximity condition is not met.****Proposal 2: When SRS is reconfigured without cell change during the measurement period, UE shall restart the UE Rx-Tx time difference measurement after the SRS reconfiguration on the target cell is complete.** |
| R4-2205352 | Huawei, HiSilicon | CR on positioning measurement requirements R16 (R16) |
| R4-2205353 | Huawei, HiSilicon | Mirror CR to R4-2205352 |
| R4-2206031 | Ericsson | On UE positioning measurement requirements:Observation 1: When PRS/SRS proximity condition is not met then the UE not meeting measurement requirement may lead to worse positioning accuracy.Observation 2: When PRS/SRS proximity condition is not met some UE implementation may still meet the measurement and accuracy requirements.**Proposal for UE behaviour:****Proposal 1: If SRS and PRS proximity condition is not met then it is up to the UE whether to transmit the UE Rx-Tx measurement results to LMF.****Proposals for requirements:****Proposal 2: If the SRS and PRS proximity condition is not met then the UE is not expected to meet the UE Rx-Tx time difference measurement requirements.****Proposal 3: If the SRS and PRS proximity condition is not met then the UE is not expected to meet the UE Rx-Tx time difference accuracy requirements.** |
| R4-2206032 | Ericsson | Updates to measurement requirements for UE positioning measurements in TS 38.133 (R16) |
| R4-2206033 | Ericsson | Mirror CR to R4-2206032 |

## Open issues summary

### Sub-topic 1-1

In previous meeting, the SRS/PRS proximity condition was agreed, and the proximity condition was described as below:

|  |
| --- |
| Agreements in RAN4#98bis-e (R4-2105851): * The measurement requirements is applicable only if any SRS transmission is within [-X, X] msec of at least one DL PRS resource of each of the TRPs in the assistance data.
	+ Accuracy requirements are independent of PRS and SRS separation
	+ X = FFS between 160ms or 80ms
	+ FFS if UE still measures and reports UE Rx-Tx measurement or not if PRS/SRS proximity condition is not met
 |

**Issue 1-1-1: If the SRS and PRS proximity condition is not met, how does RAN4 specify the UE measurement and report requirements (Core)?**

* Option 1: UE Rx-Tx measurement requirements, including measurement period requirements **do not apply.**
	+ It is UE implementation whether the UE transmit the UE Rx-Tx measurement results to LMF or not
* Option 2: UE Rx-Tx measurement requirements still **apply,** and the UE still measures and reports UE Rx-Tx measurement
* Option 3: UE Rx-Tx measurement requirements **do not** **apply,** but the UE still measures and reports UE Rx-Tx measurement
* Recommended WF
	+ Discuss between option 1 and option 2
	+ Agree on option 1

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

**Issue 1-1-2: If the SRS and PRS proximity condition is not met, what about accuracy requirements (Perf.)?**

* Option 1: UE Rx-Tx measurement accuracy requirements **do not apply.**
* Option 2: UE Rx-Tx measurement accuracy requirements still **apply**
* Recommended WF
	+ Discuss between option 1 and option 2
	+ Agree on option 1

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

### Sub-topic 1-2

In RAN4#101-e, it was agreed that if serving cell change, i.e. PSCell or SCell addition or release, causes SRS reconfiguration, UE shall re-start the Rx-Tx measurement. The scenario is that SRS was configured on old SCell, and then cell change occurs where the old SCell is released and new SCell is added. UE should re-start the measurement after SRS is configured on the new SCell.

|  |
| --- |
| Issue 1-2-2: Measurement period requirements with cell change impacting SRSWhen PSCell or SCell addition or release causes SRS reconfiguration during the measurement period, UE shall restart the UE Rx-Tx time difference measurement after the SRS reconfiguration on the target cell is complete.FFS: When SRS is reconfigured without cell change during the measurement period, UE shall restart the UE Rx-Tx time difference measurement after the SRS reconfiguration on the target cell is complete. |

**Issue 1-2-1: When SRS is reconfigured without cell change during the measurement period, UE shall restart the UE Rx-Tx time difference measurement after the SRS reconfiguration on the target cell is complete.**

* Recommended WF
	+ Agree on the below statement
		- When SRS is reconfigured without cell change during the measurement period, UE shall restart the UE Rx-Tx time difference measurement after the SRS reconfiguration on the target cell is complete.

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

## Companies views’ collection for 1st round

### Open issues

 ***Companies are encouraged to provide comments to each of the sub-topics in the above section.***

### CRs/TPs comments collection

|  |  |
| --- | --- |
| **CR/TP number** | **Comments collection** |
| R4-2203870R4-2203871CATT | Company 1:  |
| Company 2: |
|  |
| R4-2204654R4-2204655vivo |  |
|  |
|  |
| R4-2205352R4-2205353Huawei |  |
|  |
|  |
| R4-2206032R4-2206033Ericsson |  |
|  |
|  |

## Summary for 1st round

### Open issues

|  |  |
| --- | --- |
|  | **Status summary**  |
| **Sub-topic#1-1** | *Tentative agreements:**Candidate options:*  |
| **Sub-topic#1-2** | *Background clarification:**Tentative agreements:**Candidate options:* *Recommendations for 2nd round: Agree on the above tentative agreements.* |
|  |  |

*Recommendations on WF/LS assignment*

|  |  |  |
| --- | --- | --- |
|  | **WF/LS t-doc Title**  | **Assigned Company,****WF or LS lead** |
| #1 |  |  |

### CRs/TPs

|  |  |
| --- | --- |
| **CR/TP number** | **CRs/TPs Status update recommendation**  |
| R4-2203870R4-2203871CATT |  |
| R4-2204654R4-2204655vivo |  |
| R4-2205352R4-2205353Huawei |  |
| R4-2206032R4-2206033Ericsson |  |

## Discussion on 2nd round (if applicable)

### Sub-topic 1-1

### Sub-topic 1-2

## Summary on 2nd round (if applicable)

*Moderator tries to summarize discussion status for 2nd round and provided recommendation on CRs/TPs/WFs/LSs Status update suggestion*

|  |  |
| --- | --- |
| **CR/TP/LS/WF number** | **T-doc Status update recommendation**  |
|  |  |
|  |  |

# Topic #2: Maintenance to RRM Perf. requirements

Performance part maintenance of the R16 positioning requirements corrections is covered in Topic #2. Please see the below details. The previously approved WF related to this topic is in ***R4-2120270***.

## Companies’ contributions summary

|  |  |  |
| --- | --- | --- |
| **T-doc number** | **Company** | **Proposals / Observations** |
| R4-2203872 | CATT | Discussion on R16 NR positioning performance maintenance:**Proposal 1: The PRS RSRP accuracy requirements in extreme condition are X dB larger than that in normal condition, and X is:** * + - **3dB for absolute accuracy for FR1.**
		- **3dB for absolute accuracy for FR2.**
		- **1dB for relative accuracy for FR1.**
		- **3dB for relative accuracy for FR2.**

**Proposal 2: For the PRS RSRP accuracy requirements in extreme condition, define a single value for each SINR side condition independent of PRS configuration.** **Proposal 3: UE Rx-Tx measurement accuracy requirements shall apply if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.****Proposal 4: No need to define additional test cases for UE based positioning.** |
| R4-2203873 | CATT | Draft CR on R16 NR positioning accuracy requirements (R16) |
| R4-2203874 | CATT | Mirror CR to R4-2203873 |
| R4-2203875 | CATT | Draft CR on SRS configuration for R16 positioning test case (R16) |
| R4-2203876 | CATT | Mirror CR to R4-2203875 |
| R4-2204407 | Intel Corporation | Discussion on Rel-16 NR positioning measurement accuracy requirements:**Proposal 1: The maximum frequency drift between the measured TRPs can be dependent the maximum time offsets among the measured TRPs/cells (e.g. 2\* expectedRSTD).****Proposal 2: Applicability of accuracy requirements under TA adjustment if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment can be:*** + - **UE Rx-Tx measurement accuracy requirements shall apply for a serving cell even if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.**
		- **the UE Rx-Tx measurement accuracy requirements shall not apply for a neighbor cell if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.**
 |
| R4-2204462 | Qualcomm Incorporated | On UE measurement accuracy requirements for NR positioning:**Proposal 1: For UE Rx-Tx measurement accuracy requirements in FR1, add group delay calibration margins listed in the table below.**

|  |  |
| --- | --- |
| **Min(PRS BW, SRS BW) (MHz)** | **Margin (Tc)** |
| ≥ 5 | 160 |
| ≥ 10 | 80 |
| ≥ 20 | 40 |
| ≥ 50 | 16 |
| ≥ 100 | 8 |

**Proposal 2: For UE Rx-Tx measurement accuracy requirements in FR2, add group delay calibration margins listed in the table below.**

|  |  |
| --- | --- |
| **Min(PRS BW, SRS BW) (MHz)** | **Margin (Tc)** |
| ≥ 20 | 80 |
| ≥ 50 | 32 |
| ≥ 100 | 16 |
| ≥ 200 | 8 |

**Proposal 3: For RSTD measurement accuracy requirements in FR1 when the reference and target PRS resources are in the same PFL (single PFL case), add group delay calibration margins listed in the table below.**

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 5 | 160 |
| ≥ 10 | 80 |
| ≥ 20 | 40 |
| ≥ 50 | 16 |
| ≥ 100 | 8 |

**Proposal 4: For RSTD measurement accuracy requirements in FR2 when the reference and target PRS resources are in the same PFL (single PFL case), add group delay calibration margins listed in the table below.**

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 20 | 80 |
| ≥ 50 | 32 |
| ≥ 100 | 16 |
| ≥ 200 | 8 |

**Proposal 5: For PRS-RSTD measurements in FR1 with neighbor and reference PRS resources in different PFLs, the value of the group delay calibration margin is FFS.****Proposal 6: For PRS-RSTD measurements in FR2 with neighbor and reference PRS resources in different PFLs, the value of the group delay calibration margin is FFS.****Proposal 7a: Add a frequency margin of 32 Tc for RSTD that applies for a maximum time offset of 160 msec between the PRS resource instances used to calculate the RSTD measurement for the case of a single PFL.****Proposal 7b: Add a frequency margin of 50 Tc for RSTD that applies for a maximum time offset of 1 second between the PRS resource instances used to calculate the RSTD measurement for the case of multiple PFLs.****Proposal 8: No need to define PRS-RSRP accuracy requirements for extreme conditions.****Proposal 9: UE Rx-Tx measurement accuracy requirements shall apply if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.** |
| R4-2204653 | vivo | Remaining issues on measurement accuracy requirements for Rel-16 NR positioning:**Proposal 1: Frequency drift margin for the RSTD accuracy requirements is 0.5Ts (32Tc) in both FR1 and FR2.** **Proposal 2: The margin for PRS-RSRP accuracy requirements under extreme conditions are:*** + - **3dB for absolute accuracy for FR1.**
		- **3dB for absolute accuracy for FR2.**
		- **1.5dB for relative accuracy for FR1.**
		- **3dB for relative accuracy for FR2.**

**Proposal 3: UE Rx-Tx measurement accuracy requirements shall apply if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.** |
| R4-2204656 | vivo | Draft CR to 38.133 correction to NR positioning accuracy requirements |
| R4-2204657 | vivo | Mirror CR to R4-2204656 |
| R4-2205354 | Huawei, HiSilicon | Discussion on accuracy requirements for positioning measurement:**Proposal 1: Add the following group delay calibration margin for RSTD accuracy for single PFL case.****Table 1: Calibration margin for RSTD FR1 single PFL case**

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 5 | [40] |
| ≥ 10 | [32] |
| ≥ 20 | [32] |
| ≥ 50 | [16] |
| ≥ 100 | [16] |

**Table 2: Calibration margin for RSTD FR2 single PFL case**

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 20 | [32] |
| ≥ 50 | [32] |
| ≥ 100 | [16] |
| ≥ 200 | [16] |

**Proposal 2: For RSTD accuracy requirements, define the frequency drift margin as +/-32Tc based on maximum offset of 160ms. FFS whether and how to handle larger time offset.** **Proposal 3: RAN4 does not define PRS-RSRP accuracy requirements for extreme condition in Rel-16.****Proposal 4: Add the following group delay calibration margin for UE Rx-Tx accuracy.****Table 3: Calibration margin for UE Rx-Tx FR1**

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 5 | [96] |
| ≥ 10 | [80] |
| ≥ 20 | [72] |
| ≥ 50 | [32] |
| ≥ 100 | [24] |

**Table 4: Calibration margin for UE Rx-Tx FR2**

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 20 | [72] |
| ≥ 50 | [32] |
| ≥ 100 | [24] |
| ≥ 200 | [24] |

**Proposal 5: Applicability of Rx-Tx accuracy requirements with autonomous timing adjustment is defined as:*** + - **UE Rx-Tx measurement accuracy requirements shall apply for a cell, which is also the downlink reference cell (defined in section 7.1.1) for SRS transmission even if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.**
		- **UE Rx-Tx measurement accuracy requirements shall not apply for a cell, which is not the downlink reference cell (defined in section 7.1.1) for SRS transmission, if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.**
 |
| R4-2205355 | Huawei, HiSilicon | CR on accuracy requirements for positioning measurement R16 (R16) |
| R4-2205356 | Huawei, HiSilicon | Mirror CR to R4-2205355 |
| R4-2205357 | Huawei, HiSilicon | CR to introduce posSRS RMC for positioning test cases R16 (R16) |
| R4-2205358 | Huawei, HiSilicon | Mirror CR to R4-2205358 |
| R4-2206034 | Ericsson | On UE positioning accuracy measurements:Observation 1: It may not be uncommon that the UE operates in extreme conditions e.g. at 14C or 36C.Observation 2: PRS-RSRP may significantly drift or vary in the extreme conditions.**Proposal 1: Specify PRS-RSRP accuracies in extreme conditions.****Proposal 2: Support PRS-RSRP accuracies in extreme conditions as in the WF i.e.: PRS RSRP measurement requirements in extreme condition are X dB larger than that in normal condition, and X is:*** + - **3dB for absolute accuracy for FR1.**
		- **3dB for absolute accuracy for FR2.**
		- **1.5 dB for relative accuracy for FR1.**
		- **3dB for relative accuracy for FR2.**

Observation 3: The UL autonomous timing adjustment, which is based on the DL timing, follows the DL timing change in the reference cell, resulting in the UE transmit timing changes in the same direction in which the DL timing changes in the reference cell.Observation 4: The UE can be configured to perform UE Rx-Tx measurements on multiple cells (multi-RTT).Observation 5: In one multi-RTT measurement scenario, the UE may transmit SRS on reference cell (e.g. PCell) while perform PRS also on the reference cell (e.g. PCell). In this case the changes in SRS timing due to autonomous timing adjustment follows the PRS timing change in the reference cell.Observation 6: In another multi-RTT measurement scenario, the UE may transmit SRS on reference cell (e.g. PCell) while perform PRS on another serving cell (e.g. SCell). In this case the changes in SRS timing due to autonomous timing adjustment is not related to PRS timing in the SCell.Observation 7: In another multi-RTT measurement scenario, the UE may transmit SRS on reference cell (e.g. PCell) while perform PRS on a neighbor cell (non-serving cell). In this case as well the changes in SRS timing due to autonomous timing adjustment is not related to PRS timing in the neighbor cell.**Proposal 3: Applicability of accuracy requirements under TA adjustment if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment is specified to cover all supported single RTT and multi-RTT measurement scenarios.****Proposal 4: Applicability of accuracy requirements under TA adjustment if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment is specified based on Option 2 in the WF [1] i.e:*** + - **UE Rx-Tx measurement accuracy requirements shall apply for a cell, which is also the downlink reference cell (defined in section 7.1.1) for SRS transmission even if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.**
		- **the UE Rx-Tx measurement accuracy requirements shall not apply for a cell, which is not the downlink reference cell (defined in section 7.1.1) for SRS transmission, if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.**
 |
| R4-2206035 | Ericsson | Updates to accuracy requirements for UE positioning measurements in TS 38.133 (R16) |
| R4-2206036 | Ericsson | Mirror CR to R4-2206035 |
| R4-2205441 | Rohde & Schwarz | On UE-based DL-TDOA support:Observation 1: Measurement delay requirements are agnostic of UE-assisted or UE-based positioning method.Observation 2: The UE needs the base station antenna location and the RTD value for a UE-based location fix.**Proposal 1: To enable measurement delay testing for UE-based DL-TDOA, add to the test case a table containing a model of the base station locations and the RTD value between them compliant to the current test configurations. For UE-based the UE location fix reporting delay is evaluated.** The UE location in the table below is based on the time offset between PRS signals defined for the test case in A.6.6.12.1/2 in [4]. It is just shown for information purposed and it will not be provided to the UE.

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
|  | **East [m]** | **North [m]** | **Up [m]** | **RTD** |
| **NR Cell 1** | 0 | 0 | 20 | 0 (Ref) |
| **NR Cell 2** | 3000 | 0 | 15 | 0 |
| **NR Cell 3** | 1500 | 2598 | 25 | 0 |
| **UENote 1** | 1500 | 399 | 0 | N/A |
| Note 1: The UE coordinates are derived from the time delays between PRS signals. They are for information and are not part of the assistance data.Note 2: The HDOP of the proposed model is 1.03. |

Observation 3: The accuracy of the RSTD measurements cannot be evaluated directly from the UE-based reports.**Proposal 2: To enable measurement accuracy testing for UE-based DL-TDOA, infer RSTD measurement accuracy from location fix reporting accuracy using the equation** $E\_{fix}=E\_{RSTD}⋅HDOP$**Proposal 3: Add a third cell to RSTD measurement accuracy test cases to enable RSTD accuracy testing for UE-based DL-TDOA.****Proposal 4: For the measurement accuracy test case, re-use the same positioning scenario as for measurement delay test case (Proposal 1).**Submitted to AI 5.1.5.3 |
| R4-2205442 | Rohde & Schwarz | Draft CR to TS 38.133: Additions to RSTD test cases for UE-based DL-TDOA support (R16)Submitted to AI 5.1.5.3 |
| R4-2205443 | Rohde & Schwarz | Mirror CR to R4-2205441Submitted to AI 5.1.5.3 |

## Open issues summary

### Sub-topic 2-1 RSTD measurements

For RSTD, if reference cell and neighbour cell are measured with different Rx paths or at different times, the measurements will experience different calibration errors which cannot be cancelled out. As a result, a margin to account for the ‘relative’ calibration error is needed.

**Issue 2-1-1: Group delay calibration margin for RSTD measurement accuracy in FR1**

* Proposals for single PFL
	+ Option 1:

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 5 | 160 |
| ≥ 10 | 80 |
| ≥ 20 | 40 |
| ≥ 50 | 16 |
| ≥ 100 | 8 |

* + Option 2:

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 5 | [40] |
| ≥ 10 | [32] |
| ≥ 20 | [32] |
| ≥ 50 | [16] |
| ≥ 100 | [16] |

* Recommended WF
	+ Compromised values are needed so moderator proposes the below values with brackets

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 5 | [100] |
| ≥ 10 | [56] |
| ≥ 20 | [36] |
| ≥ 50 | [16] |
| ≥ 100 | [12] |

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

**Issue 2-1-2: Group delay calibration margin for RSTD measurement accuracy in FR2**

* Proposals for single PFL
	+ Option 1:

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 20 | 80 |
| ≥ 50 | 32 |
| ≥ 100 | 16 |
| ≥ 200 | 8 |

* + Option 2:

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 20 | [32] |
| ≥ 50 | [32] |
| ≥ 100 | [16] |
| ≥ 200 | [16] |

* Recommended WF
	+ Compromised values are needed so moderator proposes the below value with brackets

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 10 | [56] |
| ≥ 20 | [32] |
| ≥ 100 | [16] |
| ≥ 200 | [12] |

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

**Issue 2-1-3: Frequency drift margin for RSTD measurement accuracy requirements**

|  |
| --- |
| **Frequency drift margin for RSTD** * RAN4 will define a single value for the frequency drift margin based on a single value of the maximum time offset
* FFS on the exact value
 |

* Proposals
	+ Option 1: The maximum frequency drift between the measured TRPs can be dependent the maximum time offsets among the measured TRPs/cells (e.g. 2\* expectedRSTD)
	+ Option 2:
		- Add a frequency margin of 32 Tc for RSTD that applies for a maximum time offset of 160 msec between the PRS resource instances used to calculate the RSTD measurement for the case of a single PFL.
		- Add a frequency margin of 50 Tc for RSTD that applies for a maximum time offset of 1 second between the PRS resource instances used to calculate the RSTD measurement for the case of multiple PFLs.
	+ Option 3: Frequency drift margin for the RSTD accuracy requirements is 0.5Ts (32Tc) in both FR1 and FR2.
	+ Option 4: For RSTD accuracy requirements, define the frequency drift margin as +/-32Tc based on maximum offset of 160ms. FFS whether and how to handle larger time offset
* Recommended WF
	+ Option 5: Specify frequency drift margin for RSTD accuracy requirements assuming one single maximum timing offset, which is [160ms] across FR1 and FR2: [32Tc].

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

### Sub-topic 2-2 Rx – Tx measurements

For UE Rx-Tx, one of the differences is that the group delay of both Rx path and Tx path need to be compensated, so the calibration error from both paths need to be accounted. For both Rx – Tx and RSTD, group delay is dependent on BW and frequency range.

**Issue 2-2-1: Group delay calibration margin for Rx-Tx measurement accuracy in FR1**

* Proposals for single PFL
	+ Option 1:

|  |  |
| --- | --- |
| **Min(PRS BW, SRS BW) (MHz)** | **Margin (Tc)** |
| ≥ 5 | 160 |
| ≥ 10 | 80 |
| ≥ 20 | 40 |
| ≥ 50 | 16 |
| ≥ 100 | 8 |

* + Option 2:

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 5 | [96] |
| ≥ 10 | [80] |
| ≥ 20 | [72] |
| ≥ 50 | [32] |
| ≥ 100 | [24] |

* Recommended WF
	+ Compromised values are needed so moderator proposes the below values with brackets

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 5 | [128] |
| ≥ 10 | [80] |
| ≥ 20 | [56] |
| ≥ 50 | [24] |
| ≥ 100 | [16] |

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

**Issue 2-2-2: Group delay calibration margin for Rx - Tx measurement accuracy in FR2**

* Proposals for single PFL
	+ Option 1:

|  |  |
| --- | --- |
| **Min(PRS BW, SRS BW) (MHz)** | **Margin (Tc)** |
| ≥ 20 | 80 |
| ≥ 50 | 32 |
| ≥ 100 | 16 |
| ≥ 200 | 8 |

* + Option 2:

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 20 | [72] |
| ≥ 50 | [32] |
| ≥ 100 | [24] |
| ≥ 200 | [24] |

* Recommended WF
	+ Compromised values are needed so moderator proposes the below value with brackets

|  |  |
| --- | --- |
| **PRS BW (MHz)** | **Margin (Tc)** |
| ≥ 10 | [76] |
| ≥ 20 | [32] |
| ≥ 100 | [20] |
| ≥ 200 | [16] |

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

**Issue 2-2-3: Applicability of Rx-Tx accuracy requirements with autonomous timing adjustment**

* Proposals
	+ Option 1: UE Rx-Tx measurement accuracy requirements shall apply if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.
	+ Option 2: Applicability of accuracy requirements under TA adjustment if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment can be:
		- UE Rx-Tx measurement accuracy requirements shall apply for a serving cell even if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.
		- the UE Rx-Tx measurement accuracy requirements shall not apply for a neighbor cell if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.
	+ Option 3: Applicability of Rx-Tx accuracy requirements with autonomous timing adjustment is defined as:
		- UE Rx-Tx measurement accuracy requirements shall apply for a cell, which is also the downlink reference cell (defined in section 7.1.1) for SRS transmission even if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.
		- UE Rx-Tx measurement accuracy requirements shall not apply for a cell, which is not the downlink reference cell (defined in section 7.1.1) for SRS transmission, if the uplink transmission timing changes during the UE Rx-Tx measurement period due to autonomous adjustment.
* Recommended WF
	+ Agree on Option 3

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

### Sub-topic 2-3 RSRP measurements

**Issue 2-3-1: PRS-RSRP accuracy under extreme condition**

* Proposals
	+ Option 1: The PRS RSRP accuracy requirements in extreme condition are X dB larger than that in normal condition, and X is one single value for each SNR side condition across different PRS configurations:
		- 3dB for absolute accuracy for FR1.
		- 3dB for absolute accuracy for FR2.
		- 1dB for relative accuracy for FR1.
		- 3dB for relative accuracy for FR2.
	+ Option 2: The margin for PRS-RSRP accuracy requirements under extreme conditions are:
		- 3dB for absolute accuracy for FR1.
		- 3dB for absolute accuracy for FR2.
		- 1.5dB for relative accuracy for FR1.
		- 3dB for relative accuracy for FR2.
	+ Option 3: No need to define PRS-RSRP accuracy requirements for extreme conditions in Rel-16.
* Recommended WF
	+ Agree on Option 2

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

### Sub-topic 2-4 UE based DL-TDOA test cases

There are two positioning modes, UE-assisted and UE-based. Current test requirement definition assumes UE-assisted support. However, UE-assisted and UE-based are both optional features. A UE could decide to support only UE-based DL-TDOA and not support UE-assisted. In such a scenario, DL-TDOA requirements would remain untested for this UE. Previous agreements are copied below.

|  |  |
| --- | --- |
| **Sub-topic#3-1** | **Test cases for the UE-based positioning measurement delay reporting*** + FFS on test case for UE based positioning measurement delay reporting : RAN4 to add UE-based DL-TDOA reporting delay test case requirements based on the existing RSTD reporting delay test cases, but adding the needed pre-requisites.
 |
| **Sub-topic #3-2** | **Test cases for the UE-based positioning measurement accuracy requirements*** + FFS on test case for UE based positioning measurement accuracy requirements : RAN4 to consider the definition of DL-TDOA accuracy test case requirements for UEs supporting UE-based DL-TDOA based on one of the following alternatives:
		- Alternative 1: considering the worst case RSTD absolute accuracy from TS 38.133 section 10.1.23 (e.g. Expected RSTD - K for the serving cell, Expected RSTD + K for all neighbor cells, where K is the accuracy limit for the corresponding PRS configuration), calculate the total positioning error that results based on multilateration algorithm.
		- Alternative 2: consider the E911 requirements as basis and define a positioning accuracy error of +-50m
 |
| **Sub-topic#3-3** | **TC of RSTD accuracy with dual PFLs*** FFS: Option 1 (Huawei):
* RAN4 to remove the test cases for RSTD accuracy with dual PFLs
 |

**Issue 2-4-1: Measurement delay test cases**

* Proposals
	+ Option 1: To enable measurement delay testing for UE-based DL-TDOA,add to the test case a table containing a model of the base station locations and the RTD value between them compliant to the current test configurations. For UE-based the UE location fix reporting delay is evaluated.
	+ Option 2: No need to define additional test cases for UE based positioning.
* Recommended WF
	+ Discuss upon Option 1.

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

**Issue 2-4-2: Measurement accuracy test cases**

* Proposals
	+ Option 1: specify UE-based DL-TDOA measurement accuracy test cases
		- To enable measurement accuracy testing for UE-based DL-TDOA, infer RSTD measurement accuracy from location fix reporting accuracy using the equation E\_fix=E\_RSTD⋅HDOP
		- Add a third cell to RSTD measurement accuracy test cases to enable RSTD accuracy testing for UE-based DL-TDOA
		- Re-use the same positioning scenario as for measurement delay test case mentioned in issue 2-4-1
	+ Option 2: No need to define additional test cases for UE based positioning.
* Recommended WF
	+ Discuss upon Option 1.

Companies are encouraged to provide comments per sub-topic directly below the summary.

|  |  |
| --- | --- |
| **Company** | **Comments**  |
|  |  |
|  |  |
|  |  |

## Companies views’ collection for 1st round

### Open issues

 ***Companies are encouraged to provide comments to each of the sub-topics in the above section.***

### CRs/TPs comments collection

|  |  |
| --- | --- |
| **CR/TP number** | **Comments collection** |
| R4-2203873R4-2203874CATT | Company 1:  |
|  |
|  |
| R4-2203875R4-2203876CATT |  |
|  |
|  |
| R4-2204656R4-2204657vivo |  |
|  |
|  |
| R4-2205355R4-2205356Huawei |  |
|  |
|  |
| R4-2205357R4-2205358Huawei |  |
|  |
|  |
| R4-2206035R4-2206036Ericsson |  |
|  |
|  |
| R4-2205442R4-2205443R&S |  |
|  |
|  |

## Summary for 1st round

### Open issues

|  |  |
| --- | --- |
|  | **Status summary**  |
| **Sub-topic#2-1-1** | *Tentative agreements:**Candidate options:**Recommendations for 2nd round:* . |
| **Sub-topic#2-1-2** | *Tentative agreements:**Candidate options:**Recommendations for 2nd round:*. |
| **Sub-topic#2-1-3** | *Tentative agreements:**Candidate options:**Recommendations for 2nd round:*. |
| **Sub-topic#2-2-1** | *Tentative agreements:**Candidate options:**Recommendations for 2nd round:**.* |
| **Sub-topic#2-2-2** | *Tentative agreements:**Candidate options:**Recommendations for 2nd round:*. |
| **Sub-topic#2-2-3** | *Tentative agreements:**Candidate options:**Recommendations for 2nd round:*. |
| **Sub-topic#2-3-1** | *Tentative agreements:**Candidate options:**Recommendations for 2nd round:*. |
| **Sub-topic#2-4-1** | *Tentative agreements:**Candidate options:**Recommendations for 2nd round:*. |
| **Sub-topic#2-4-2** | *Tentative agreements:**Candidate options:**Recommendations for 2nd round:*. |

*Suggestion on WF/LS assignment*

|  |  |  |
| --- | --- | --- |
|  | **WF/LS t-doc Title**  | **Assigned Company,****WF or LS lead** |
| #1 |  |  |

### CRs/TPs

|  |  |
| --- | --- |
| **CR/TP number** | **CRs/TPs Status update recommendation**  |
|  |  |
|  |  |
|  |  |
|  |  |
|  |  |

## Discussion on 2nd round (if applicable)

### Sub-topic 2-1

### Sub-topic 2-2

## Summary on 2nd round (if applicable)

*Moderator tries to summarize discussion status for 2nd round and provided recommendation on CRs/TPs/WFs/LSs Status update suggestion*

|  |  |
| --- | --- |
| **CR/TP/LS/WF number** | **T-doc Status update recommendation**  |
| XXX | *Based on 2nd round of comments collection, moderator can recommend the next steps such as “agreeable”, “to be revised”* |

|  |  |
| --- | --- |
| **CR/TP number** | **CRs/TPs Status update recommendation**  |
|  |  |
|  |  |
|  |  |

# Recommendations for Tdocs

## 1st round

**New tdocs**

|  |  |  |
| --- | --- | --- |
| **Title** | **Source** | **Comments** |
|  |  |  |
|  |  |  |
|  |  |  |

**Existing tdocs**

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Tdoc number** | **Title** | **Source** | **Recommendation**  | **Comments** |
| R4-210xxxx | CR on … | XXX | Agreeable, Revised, Merged, Postponed, Not Pursued |  |
|  |  |  |  |  |
|  |  |  |  |  |
|  |  |  |  |  |

Notes:

1. Please include the summary of recommendations for all tdocs across all sub-topics incl. existing and new tdocs.
2. For the Recommendation column please include one of the following:
	1. CRs/TPs: Agreeable, Revised, Merged, Postponed, Not Pursued
	2. Other documents: Agreeable, Revised, Noted
3. For new LS documents, please include information on To/Cc WGs in the comments column
4. Do not include hyper-links in the documents

## 2nd round

|  |  |  |  |  |
| --- | --- | --- | --- | --- |
| **Tdoc number** | **Title** | **Source** | **Recommendation**  | **Comments** |
|  |  |  |  |  |
|  |  |  |  |  |
|  |  |  |  |  |
|  |  |  |  |  |

Notes:

1. Please include the summary of recommendations for all tdocs across all sub-topics.
2. For the Recommendation column please include one of the following:
	1. CRs/TPs: Agreeable, Revised, Merged, Postponed, Not Pursued
	2. Other documents: Agreeable, Revised, Noted
3. Do not include hyper-links in the documents

Annex

Contact information

|  |  |  |
| --- | --- | --- |
| **Company** | **Name** | **Email address** |
|  |  |  |
|  |  |  |

Note:

1. Please add your contact information in above table once you make comments on this email thread.
2. If multiple delegates from the same company make comments on single email thread, please add you name as suffix after company name when make comments i.e. Company A (XX, XX)