Agenda Item: AH99

Source: Siemens

Title: CR 25.214-182/183: Clarification of initialisation of closed loop mode 1 and 2 during compressed mode

Document for: Discussion and approval

# Introduction

In the current specification TS 25.214 it is defined how UTRAN and UE shall initiate transmission in closed loop transmit diversity and how closed loop transmit diversity operates during compressed mode.

Unfortunately the combination of these two cases namely when the initialisation overlaps with a compressed mode gap is not covered explicitly. The feedback commands in uplink are not specified for this case. As a precise match of the UE and Node B is essential also for this case, we propose to also explicitly define this missing case. The proposed procedure is in line with the already defined procedures for initialisation and compressed mode alone.

# Proposal

It is proposed to update the specification text according to the attached CRs.

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# 7.2 Closed loop mode 1

UE uses the CPICH transmitted both from antenna 1 and antenna 2 to calculate the phase adjustment to be applied at UTRAN access point to maximise the UE received power. In each slot, UE calculates the optimum phase adjustment,  $\phi$ , for antenna 2, which is then quantized into  $\phi_{O}$  having two possible values as follows:

$$\phi_{\mathcal{Q}} = \begin{cases} \pi, & \text{if } \pi/2 < \phi - \phi_r(\mathbf{i}) \le 3\pi/2 \\ 0, & \text{otherwise} \end{cases}$$
(2)

where:

$$\phi_r(i) = \begin{cases} 0, & i = 0, 2, 4, 6, 8, 10, 12, 14 \\ \pi/2, & i = 1, 3, 5, 7, 9, 11, 13 \end{cases}$$
(3)

If  $\phi_Q = 0$ , a command '0' is send to UTRAN using the FSM<sub>ph</sub> field. Correspondingly, if  $\phi_Q = \pi$ , command '1' is send to UTRAN using the FSM<sub>ph</sub> field.

Due to rotation of the constellation at UE the UTRAN interprets the received commands according to table 9 which shows the mapping between phase adjustment,  $\phi_i$ , and received feedback command for each UL slot.

# Table 9: Phase adjustments, $\phi_{i}$ , corresponding to feedback commands for the slots *i* of the UL radio frame

Slot #		0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
FSM	0	0	π/2	0	π/2	0	π/2	0								
	1	π	-π/2	π	-π/2	π	-π/2	π								

The weight vector,  $w_{2i}$  is then calculated by sliding window averaging the received phases over 2 consecutive slots. Algorithmically,  $w_2$  is calculated as follows:

$$W_{2} = \frac{\sum_{i=n-1}^{n} \cos(\phi_{i})}{2} + j \frac{\sum_{i=n-1}^{n} \sin(\phi_{i})}{2}$$
(4)

where:

$$\phi_i \in \{0, \pi, \pi/2, -\pi/2\}$$
(5)

For antenna 1, the weight vector,  $w_{1}$ , is always:

$$W_1 = 1/\sqrt{2} \tag{6}$$

# 7.2.1 Mode 1 end of frame adjustment

In closed loop mode 1 at frame borders the sliding window averaging operation is slightly modified. Upon reception of the FB command for slot 0 of the next frame, the average is calculated based on the command for slot 13 of the previous frame and the command for slot 0 of the next frame, i.e.  $\phi_i$  from slot 14 is not used:

$$W_2 = \frac{\cos(\phi_{13}^{j-1}) + \cos(\phi_0^j)}{2} + j \frac{\sin(\phi_{13}^{j-1}) + \sin(\phi_0^j)}{2}$$
(7)

where:

-  $\phi_{13}^{j-1}$  = phase adjustment from frame j-1, slot 13.

-  $\phi_0^j$  = phase adjustment from frame j, slot 0.

# 7.2.2 Mode 1 normal initialisation

For the first frame of transmission UE determines the feedback commands in a normal way and sends them to UTRAN.

Before the first FB command is received, the UTRAN shall use the initial weight  $W_2 = \frac{1}{2}(1+j)$ .

Having received the first FB command the UTRAN calculates the  $w_2$  as follows:

$$W_2 = \frac{\cos(\pi/2) + \cos(\phi_0)}{2} + j\frac{\sin(\pi/2) + \sin(\phi_0)}{2}$$
(8)

where:

 $\phi_0$  = phase adjustment from slot 0 of the first frame.

# 7.2.3 Mode 1 operation during compressed mode

### 7.2.3.1 Downlink in compressed mode and uplink in normal mode

When downlink is in compressed mode but uplink is operating normally (i.e. not compressed) the UTRAN continues it's Tx diversity related functions in the same way as in non-compressed downlink mode.

In compressed downlink transmission there are uplink slots for which no new estimate of the phase adjustment is calculated. During these slots the following rules are applied in UE when determining the feedback command:

- 1) If no new estimate of phase adjustment,  $\phi_{i}$ , exist corresponding to the feedback command to be send in uplink slot *i*:
  - If 1 < *i* < 15:
    - the feedback command sent in uplink slot *i*-2 is used;
  - else if *i* = 0:
    - the feedback command sent in uplink slot 14 of previous frame is used;
  - else if *i* = 1:
    - the feedback command sent in uplink slot 13 of previous frame is used;
  - end if.
- 2) When transmission in downlink is started again in downlink slot  $N_{last}+1$  (if  $N_{last}+1 = 15$ , then slot 0 in the next frame) the UE must resume calculating new estimates of the phase adjustment. The feedback command corresponding to the first new estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot  $N_{last}+1$ .

# 7.2.3.2 Both downlink and uplink in compressed mode

During the uplink idle slots no FB commands are sent from UE to UTRAN. When transmission in downlink is started again in downlink slot  $N_{last}$ +1 (if  $N_{last}$ +1 = 15, then slot 0 in the next frame) the UE must resume calculating new estimates of the phase adjustment. The feedback command corresponding to the first new estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot  $N_{last}$ +1.

The UTRAN continues to update the weight vector,  $w_2$ , until the uplink enters the compressed mode and no more FB commands are received. When the transmission in downlink resumes in slot N<sub>last</sub>+1, the value of  $w_2$  calculated after receiving the last FB command before uplink entered the compressed mode is applied to antenna 2 signal.

After UE resumes transmission in uplink and sends the first FB command the new value of  $w_2$  is calculated as follows:

- $\quad S_1 = \{0, 2, 4, 6, 8, 10, 12 \ 14\}.$
- $S_2 = \{1, 3, 5, 7, 9, 11, 13\}.$
- i = number of uplink slot at which the transmission resumes.
- j = number of uplink slot at which the last FB command was send before uplink entered compressed mode.
- Do while  $(i \in S_1 \text{ and } j \in S_1)$  or  $(i \in S_2 \text{ and } j \in S_2)$ :
  - j = j-1;
  - if j < 0;
  - j = 14;
- end if;
- end do;
- calculate *w*<sub>2</sub> based on FB commands received in uplink slots i and j.

# 7.2.4 Mode 1 initialisation during compressed mode

When closed loop mode 1 is initialised during the downlink transmission gap of compressed mode there are slots for which no estimate of the phase adjustment is calculated and no previous feedback command is available.

In this case, if the UE is required to send feedback in the uplink, the FB command to the UTRAN shall be '0'.

When transmission in downlink is started again in slot  $N_{iast}+1$  (if  $N_{iast}+1 = 15$ , then slot 0 in the next frame), the

<u>UTRAN shall use the initial weight</u>  $W_2 = \frac{1}{2}(1 + j)$ . The UE must start calculating estimates of the phase adjustment.

The feedback command corresponding to the first estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot N<sub>last</sub>+1. Having received this feedback command the UTRAN calculates  $w_2$  as follows:

$$W_{2} = \frac{\cos(\phi_{i}) + \cos(\phi_{j})}{2} + j \frac{\sin(\phi_{i}) + \sin(\phi_{j})}{2}$$
(9)

where:

 $\phi_i$  = phase adjustment in uplink slot i, which is transmitted 1024 chips in offset from the downlink slot N<sub>last</sub>+1.

$$\phi_j = \frac{\pi}{2}$$
, if slot i is even ( $i \in \{0, 2, 4, 6, 8, 10, 12, 14\}$ ) and

 $\phi_j = 0$ , if slot i is odd ( $i \in \{1, 3, 5, 7, 9, 11, 13\}$ )

# 7.3 Closed loop mode 2

In closed loop mode 2 there are 16 possible combinations of phase and power adjustment from which the UE selects and transmits the FSM according to table 10 and table 11. As opposed to closed loop Mode 1, no constellation rotation is done at UE and no filtering of the received weights is performed at the UTRAN.

FSM <sub>po</sub>	Power_ant1	Power_ant2
0	0.2	0.8
1	0.8	0.2

### Table 10: FSM<sub>po</sub> subfield of closed loop mode 2 signalling message

#### Table 11: FSM<sub>ph</sub> subfield of closed loop mode 2 signalling message

FSM <sub>ph</sub>	Phase difference between antennas (radians)
000	π
001	-3π/4
011	-3π/4 -π/2
010	-π/4
110	0
111	$\pi/4$
101	π/2
100	3π/4

To obtain the best performance, progressive updating is performed at both the UE and the UTRAN Access point. The UE procedure shown below is an example of how to determine FSM at UE. Different implementation is allowed. Every slot time, the UE may refine its choice of FSM, from the set of weights allowed given the previously transmitted bits of the FSM. This is shown in figure 5, where, in this figure  $b_i$  (0 < i < 3) are the bits of the FSM (from table 10 and table 11) from the MSB to the LSB and m=0, 1, 2, 3 (the end of frame adjustment given subclause 7.3.1 is not shown here).

At the beginning of a FSM to be transmitted, the UE chooses the best FSM out of the 16 possibilities. Then the UE starts sending the FSM bits from the MSB to the LSB in the portion of FBI field of the uplink DPCCH during 4 (FSM message length) slots. Within the transmission of the FSM the UE refines its choice of FSM. This is defined in the following:

define the 4 bits of FSM, which are transmitted from slot number k to k+3, as {b<sub>3</sub>(k) b<sub>2</sub>(k+1) b<sub>1</sub>(k+2) b<sub>0</sub>(k+3)}, where k=0, 4, 8, 12. Define also the estimated received power criteria defined in Equation 1 for a given FSM as *P* ({x<sub>3</sub>, x<sub>2</sub> x<sub>1</sub> x<sub>0</sub>}), where { x<sub>3</sub> x<sub>2</sub> x<sub>1</sub> x<sub>0</sub> } is one of the 16 possible FSMs which defines an applied phase and power offset according to table 10 and table 11. The b<sub>i</sub>() and x<sub>i</sub> are 0 or 1.

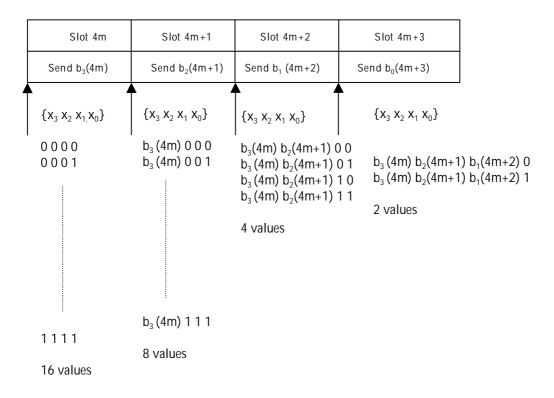
The bits transmitted during the m'th FSM of the frame, where m=0,1,2,3, are then given by:

 $b_3(4m) = X_3$  from the { $X_3 X_2 X_1 X_0$ } which maximises  $P({x_3 x_2 x_1 x_0})$  over all  $x_3, x_2, x_1, x_0$  (16 possible combinations);

 $b_2(4m+1)=X_2$  from the { $b_3(4m) X_2 X_1 X_0$ } which maximises  $P({b_3(4m) x_2 x_1 x_0})$  over all  $x_2, x_1, x_0$  (8 possible combinations);

 $b_1(4m+2)=X_1$  from the { $b_3(4m)$   $b_2(4m+1)$   $X_1$   $X_0$ } which maximises  $P({b_3(4m) b_2(4m+1) x_1 x_0})$  over all  $x_1, x_0$  (4 possible combinations);

 $b_0(4m+3)=X_0$  from the { $b_3(4m) b_2(4m+1) b_1(4m+2) X_0$ } which maximises  $P({b_3(4m) b_2(4m+1) b_1(4m+2) x_0})$  over  $x_0$  (2 possible combinations).



#### Figure 5: Progressive Refinement at the UE for closed loop mode 2

Every slot time the UTRAN constructs the FSM from the most recently received bits for each position in the word and applies the phase and amplitude (derived from power) as defined by table 10 and table 11. More precisely, the UTRAN operation can be explained as follows. The UTRAN maintains a register  $z = \{z_3 \ z_2 \ z_1 \ z_0\}$ , which is updated every slot time according to  $z_i = b_i(ns)$  (i=0:3, ns=0:14). Every slot time the contents of register z are used to determine the phase and power adjustments as defined by table 10 and table 11, with FSM<sub>ph</sub> =  $\{z_3 \ z_2 \ z_1\}$  and FSM<sub>po</sub>= $z_0$ .

Special procedures for initialisation and end of frame processing are described below.

The weight vector, w, is then calculated as:

$$\underline{W} = \begin{bmatrix} \sqrt{power\_ant1} \\ \sqrt{power\_ant2} \exp(j \ phase\_diff) \end{bmatrix}$$
(9)

# 7.3.1 Mode 2 end of frame adjustment

The FSM must be wholly contained within a frame. To achieve this an adjustment is made to the last FSM in the frame where the UE only sends the FSM<sub>ph</sub> subfield, and the UTRAN takes the power bit FSM<sub>po</sub> of the previous FSM.

# 7.3.2 Mode 2 normal initialisation

For the first frame of transmission using closed loop mode 2, the operation is as follows.

The UE starts sending the FSM message from slot 0 in the normal way. The UE may refine its choice of FSM in slots 1 to 3 from the set of weights allowed given the previously transmitted bits of the FSM.

Before the first FSM message is received and during the reception of the first three FSM bits, the UTRAN Access Point shall initialise its transmissions as follows. The power in both antennas is set to 0.5. The phase offset applied between the antennas is updated according to the number and value of FSM<sub>ph</sub> bits received as given in table 12.

FSM <sub>ph</sub>	Phase difference between antennas (radians)
	$\pi$ (normal initialisation)
	or held from previous setting (compressed mode recovery)
0	π
1	0
00-	π
01-	-π/2
11-	0
10-	π/2
000	π
001	-3π/4
011	-π/2
010	-π/4
110	0
111	$\pi/4$
101	π/2
100	3π/4

## Table 12: $FSM_{ph}$ normal initialisation for closed loop mode 2

This operation applies in both the soft handover and non soft handover cases.

# 7.3.3 Mode 2 operation during compressed mode

# 7.3.3.1 Downlink in compressed mode and uplink in normal mode

When the downlink is in compressed mode and the uplink is in normal mode, the closed loop mode 2 functions are described below.

When the UE is not listening to the CPICH from antennas 1 and 2 during the idle downlink slots, the UE sends the last FSM bits calculated before entering in the compressed mode.

For recovery after compressed mode, UTRAN Access Point sets the power in both antennas to 0.5 until a  $FSM_{po}$  bit is received. Until the first  $FSM_{ph}$  bit is received and acted upon, UTRAN uses the phase offset, which was applied before the transmission interruption (table 12).

Normal initialisation of  $FSM_{ph}$  (table 12) occurs if the uplink signalling information resumes at the beginning of a FSM period (that is if signalling resumes in slots 0,4,8,12).

If the uplink signalling does not resume at the beginning of a FSM period, the following operation is performed. In each of the remaining slots of the partial FSM period, and for the first slot of the next full FSM period, the UE sends the first (i.e. MSB) bit of the FSM<sub>ph</sub> message, and at the UTRAN access point the phase offset applied between the antennas is updated according to the number and value of FSM<sub>ph</sub> bits received as given in table 13. Initialisation then continues with the transmission by the UE of the remaining FSM<sub>ph</sub> bits and the UTRAN operation according to table 12.

FSM <sub>ph</sub>	Phase difference between antennas (radians)
-	held from previous setting
0	π
1	0

# 7.3.3.2 Both downlink and uplink in compressed mode

During both downlink and uplink compressed mode, the UTRAN and the UE performs the functions of recovery after compressed mode as described in the previous subclause 7.3.3.1.

# 7.3.4 Mode 2 initialisation during compressed mode

When closed loop mode 2 is initialised during the downlink transmission gap of compressed mode there are slots for which no FSM bit is calculated and no previous sent FSM bit is available.

In this case, if the UE is required to send feedback in the uplink, the FB command to the UTRAN shall be '0'.

The UTRAN and the UE perform the functions of recovery after the downlink transmission gap as described in the previous subclause 7.3.3.1. If no previous phase setting is available, UTRAN shall use the phase offset  $\pi$ , until the first FSM<sub>ph</sub> bit is received and acted upon.

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# 7.2 Closed loop mode 1

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S	Slot #		0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
FS	M	0	0	π/2	0	π/2	0	π/2	0								
		1	π	-π/2	π	-π/2	π	-π/2	π								

The weight vector,  $w_2$ , is then calculated by sliding window averaging the received phases over 2 consecutive slots. Algorithmically,  $w_2$  is calculated as follows:

$$W_{2} = \frac{\sum_{i=n-1}^{n} \cos(\phi_{i})}{2} + j \frac{\sum_{i=n-1}^{n} \sin(\phi_{i})}{2}$$
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In closed loop mode 1 at frame borders the sliding window averaging operation is slightly modified. Upon reception of the FB command for slot 0 of the next frame, the average is calculated based on the command for slot 13 of the previous frame and the command for slot 0 of the next frame, i.e.  $\phi_i$  from slot 14 is not used:

$$W_2 = \frac{\cos(\phi_{13}^{j-1}) + \cos(\phi_0^j)}{2} + j\frac{\sin(\phi_{13}^{j-1}) + \sin(\phi_0^j)}{2}$$
(7)

where:

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# 7.2.2 Mode 1 normal initialisation

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  - else if *i* = 1:
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  - end if.
- 2) When transmission in downlink is started again in downlink slot  $N_{last}$ +1 (if  $N_{last}$ +1 = 15, then slot 0 in the next frame) the UE must resume calculating new estimates of the phase adjustment. The feedback command corresponding to the first new estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot  $N_{last}$ +1.

# 7.2.3.2 Both downlink and uplink in compressed mode

During the uplink idle slots no FB commands are sent from UE to UTRAN. When transmission in downlink is started again in downlink slot  $N_{last}$ +1 (if  $N_{last}$ +1 = 15, then slot 0 in the next frame) the UE must resume calculating new estimates of the phase adjustment. The feedback command corresponding to the first new estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot  $N_{last}$ +1.

The UTRAN continues to update the weight vector,  $w_2$ , until the uplink enters the compressed mode and no more FB commands are received. When the transmission in downlink resumes in slot N<sub>last</sub>+1, the value of  $w_2$  calculated after receiving the last FB command before uplink entered the compressed mode is applied to antenna 2 signal.

After UE resumes transmission in uplink and sends the first FB command the new value of  $w_2$  is calculated as follows:

- $\quad S_1 = \{0, 2, 4, 6, 8, 10, 12 \ 14\}.$
- $S_2 = \{1, 3, 5, 7, 9, 11, 13\}.$
- i = number of uplink slot at which the transmission resumes.
- j = number of uplink slot at which the last FB command was send before uplink entered compressed mode.
- Do while  $(i \in S_1 \text{ and } j \in S_1)$  or  $(i \in S_2 \text{ and } j \in S_2)$ :
  - j = j-1;
  - if j < 0;
  - j = 14;
- end if;
- end do;
- calculate w<sub>2</sub> based on FB commands received in uplink slots i and j.

# 7.2.4 Mode 1 initialisation during compressed mode

When closed loop mode 1 is initialised during the downlink transmission gap of compressed mode there are slots for which no estimate of the phase adjustment is calculated and no previous feedback command is available.

In this case, if the UE is required to send feedback in the uplink, the FB command to the UTRAN shall be '0'.

When transmission in downlink is started again in slot  $N_{last}+1$  (if  $N_{last}+1 = 15$ , then slot 0 in the next frame), the

<u>UTRAN shall use the initial weight</u>  $W_2 = \frac{1}{2}(1+j)$ . The UE must start calculating estimates of the phase adjustment.

The feedback command corresponding to the first estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot N<sub>last</sub>+1. Having received this feedback command the UTRAN calculates  $w_2$  as follows:

$$W_{2} = \frac{\cos(\phi_{i}) + \cos(\phi_{j})}{2} + j \frac{\sin(\phi_{i}) + \sin(\phi_{j})}{2}$$
(9)

where:

 $\phi_i$  = phase adjustment in uplink slot i, which is transmitted 1024 chips in offset from the downlink slot N<sub>last</sub>+1.

$$\phi_j = \frac{\pi}{2}$$
, if slot i is even ( $i \in \{0, 2, 4, 6, 8, 10, 12, 14\}$ ) and

 $\underline{\phi_j = 0}, \text{ if slot i is odd (} i \in \{1, 3, 5, 7, 9, 11, 13\})$ 

# 7.3 Closed loop mode 2

In closed loop mode 2 there are 16 possible combinations of phase and power adjustment from which the UE selects and transmits the FSM according to table 10 and table 11. As opposed to closed loop Mode 1, no constellation rotation is done at UE and no filtering of the received weights is performed at the UTRAN.

FSM <sub>po</sub>	Power_ant1	Power_ant2
0	0.2	0.8
1	0.8	0.2

Table 10: FSM<sub>po</sub> subfield of closed loop mode 2 signalling message

#### Table 11: FSM<sub>ph</sub> subfield of closed loop mode 2 signalling message

FSM <sub>ph</sub>	Phase difference between antennas (radians)
000	π
001	-3π/4
011	-π/2
010	-π/4
110	0
111	$\pi/4$
101	π/2
100	3π/4

To obtain the best performance, progressive updating is performed at both the UE and the UTRAN Access point. The UE procedure shown below is an example of how to determine FSM at UE. Different implementation is allowed. Every slot time, the UE may refine its choice of FSM, from the set of weights allowed given the previously transmitted bits of the FSM. This is shown in figure 5, where, in this figure  $b_i$  (0 < i < 3) are the bits of the FSM (from table 10 and table 11) from the MSB to the LSB and m=0, 1, 2, 3 (the end of frame adjustment given subclause 7.3.1 is not shown here).

At the beginning of a FSM to be transmitted, the UE chooses the best FSM out of the 16 possibilities. Then the UE starts sending the FSM bits from the MSB to the LSB in the portion of FBI field of the uplink DPCCH during 4 (FSM message length) slots. Within the transmission of the FSM the UE refines its choice of FSM. This is defined in the following:

define the 4 bits of FSM, which are transmitted from slot number k to k+3, as {b<sub>3</sub>(k) b<sub>2</sub>(k+1) b<sub>1</sub>(k+2) b<sub>0</sub>(k+3)}, where k=0, 4, 8, 12. Define also the estimated received power criteria defined in Equation 1 for a given FSM as *P* ({x<sub>3</sub>, x<sub>2</sub> x<sub>1</sub> x<sub>0</sub>}), where { x<sub>3</sub> x<sub>2</sub> x<sub>1</sub> x<sub>0</sub> } is one of the 16 possible FSMs which defines an applied phase and power offset according to table 10 and table 11. The b<sub>i</sub>() and x<sub>i</sub> are 0 or 1.

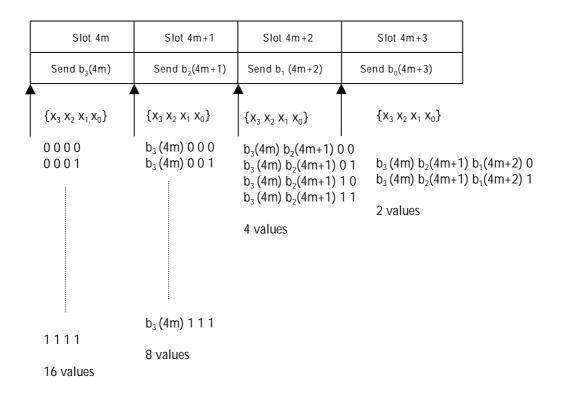
The bits transmitted during the m'th FSM of the frame, where m=0,1,2,3, are then given by:

 $b_3(4m) = X_3$  from the { $X_3 X_2 X_1 X_0$ } which maximises  $P({x_3 x_2 x_1 x_0})$  over all  $x_3, x_2, x_1, x_0$  (16 possible combinations);

 $b_2(4m+1)=X_2$  from the { $b_3(4m) X_2 X_1 X_0$ } which maximises  $P({b_3(4m) x_2 x_1 x_0})$  over all  $x_2, x_1, x_0$  (8 possible combinations);

 $b_1(4m+2)=X_1$  from the { $b_3(4m)$   $b_2(4m+1)$   $X_1$   $X_0$ } which maximises  $P({b_3(4m) b_2(4m+1) x_1 x_0})$  over all  $x_1, x_0$  (4 possible combinations);

 $b_0(4m+3)=X_0$  from the { $b_3(4m) b_2(4m+1) b_1(4m+2) X_0$ } which maximises  $P({b_3(4m) b_2(4m+1) b_1(4m+2) x_0})$  over  $x_0$  (2 possible combinations).



#### Figure 5: Progressive Refinement at the UE for closed loop mode 2

Every slot time the UTRAN constructs the FSM from the most recently received bits for each position in the word and applies the phase and amplitude (derived from power) as defined by table 10 and table 11. More precisely, the UTRAN operation can be explained as follows. The UTRAN maintains a register  $z = \{z_3 \ z_2 \ z_1 \ z_0\}$ , which is updated every slot time according to  $z_i = b_i(ns)$  (i=0:3, ns=0:14). Every slot time the contents of register z are used to determine the phase and power adjustments as defined by table 10 and table 11, with FSM<sub>ph</sub> =  $\{z_3 \ z_2 \ z_1\}$  and FSM<sub>po</sub>= $z_0$ .

Special procedures for initialisation and end of frame processing are described below.

The weight vector, <u>w</u>, is then calculated as:

$$\underline{W} = \begin{bmatrix} \sqrt{power\_ant1} \\ \sqrt{power\_ant2} \exp(j \ phase\_diff) \end{bmatrix}$$
(9)

# 7.3.1 Mode 2 end of frame adjustment

The FSM must be wholly contained within a frame. To achieve this an adjustment is made to the last FSM in the frame where the UE only sends the FSM<sub>ph</sub> subfield, and the UTRAN takes the power bit FSM<sub>po</sub> of the previous FSM.

# 7.3.2 Mode 2 normal initialisation

For the first frame of transmission using closed loop mode 2, the operation is as follows.

The UE starts sending the FSM message from slot 0 in the normal way. The UE may refine its choice of FSM in slots 1 to 3 from the set of weights allowed given the previously transmitted bits of the FSM.

Before the first FSM message is received and during the reception of the first three FSM bits, the UTRAN Access Point shall initialise its transmissions as follows. The power in both antennas is set to 0.5. The phase offset applied between the antennas is updated according to the number and value of FSM<sub>ph</sub> bits received as given in table 12.

FSM <sub>ph</sub>	Phase difference between antennas (radians)
	$\pi$ (normal initialisation)
	or held from previous setting (compressed mode recovery)
0	π
1	0
00-	π
01-	-π/2
11-	0
10-	π/2
000	π
001	-3π/4
011	-π/2
010	-π/4
110	0
111	$\pi/4$
101	π/2
100	3π/4

Table 12: FSM<sub>ph</sub> normal initialisation for closed loop mode 2

This operation applies in both the soft handover and non soft handover cases.

# 7.3.3 Mode 2 operation during compressed mode

# 7.3.3.1 Downlink in compressed mode and uplink in normal mode

When the downlink is in compressed mode and the uplink is in normal mode, the closed loop mode 2 functions are described below.

When the UE is not listening to the CPICH from antennas 1 and 2 during the idle downlink slots, the UE sends the last FSM bits calculated before entering in the compressed mode.

For recovery after compressed mode, UTRAN Access Point sets the power in both antennas to 0.5 until a  $FSM_{po}$  bit is received. Until the first  $FSM_{ph}$  bit is received and acted upon, UTRAN uses the phase offset, which was applied before the transmission interruption (table 12).

Normal initialisation of  $FSM_{ph}$  (table 12) occurs if the uplink signalling information resumes at the beginning of a FSM period (that is if signalling resumes in slots 0,4,8,12).

If the uplink signalling does not resume at the beginning of a FSM period, the following operation is performed. In each of the remaining slots of the partial FSM period, and for the first slot of the next full FSM period, the UE sends the first (i.e. MSB) bit of the FSM<sub>ph</sub> message, and at the UTRAN access point the phase offset applied between the antennas is updated according to the number and value of FSM<sub>ph</sub> bits received as given in table 13. Initialisation then continues with the transmission by the UE of the remaining FSM<sub>ph</sub> bits and the UTRAN operation according to table 12.

FSM <sub>ph</sub>	Phase difference between antennas (radians)
-	held from previous setting
0	π
1	0

# 7.3.3.2 Both downlink and uplink in compressed mode

During both downlink and uplink compressed mode, the UTRAN and the UE performs the functions of recovery after compressed mode as described in the previous subclause 7.3.3.1.

# 7.3.4 Mode 2 initialisation during compressed mode

When closed loop mode 2 is initialised during the downlink transmission gap of compressed mode there are slots for which no FSM bit is calculated and no previous sent FSM bit is available.

In this case, if the UE is required to send feedback in the uplink, the FB command to the UTRAN shall be '0'.

The UTRAN and the UE perform the functions of recovery after the downlink transmission gap as described in the previous subclause 7.3.3.1. If no previous phase setting is available, UTRAN shall use the phase offset  $\pi$ , until the first FSM<sub>ph</sub> bit is received and acted upon.