TSG-RAN Workin Stockholm, Swed November 21 – 2	ing Group 1 meeting #17 <b>TSC</b> den 24, 2000	GR1#17(00)1333
Agenda item:	4	
Source:	Vodafone Group, Ericsson	
Title:	Clarifications on the description of the radio link	establishment procedure
	(when no radio link exists)	
Document for:	Approval	

At the last meeting, many contributions were presented in order to make corrections and clarifications on issues related to the radio link initialisation (see [1-5]). However the radio link initialisation procedure itself (described in section 4.3.2.2 from TS 25.214) did not receive any further improvement. As pointed out on discussions on the reflector, the description of this procedure is not satisfactory yet, as there remains inconsistent and unclear points. This could lead to misinterpretation and consequently different implementations, which could undermine the performance of the network considerably. It is essential to provide a good description of this procedure in R99 (Rel 3) specifications. In the attached CR we suggest some improvements.

An LS to WG2 has been sent at the last meeting (Pusan, RAN1 #16) to request an extension of the uplink power control preamble length, which is currently 0 or 1 frame. In this CR, we assume that the extension of the PCP length values range has been approved in RAN2.

The main points developed in this CR are summarized as follows:

1) The support of PCP shall be mandatory at the UE (PCP length zero included).

2) The initial power used at both UE and UTRAN when starting transmission of DPCH is stated in the relevant steps of the procedure. References to WG2 and WG3 specs are provided (TS 25.331 and TS 25.433).

3) In step b) we delete the reference to DL DPDCH at the downlink chip and frame synchronisation stage as it shall be done on DPCCH only.

4) We correct the inconsistency regarding the termination of the UL power control preamble period. At the moment this period stops after the first DL TPC reverse. This is not consistent with the downlink toggling scheme applied on the DPCCH TPC commands. In the current state of the specs, the preamble period stops after 1 slot due to this toggling scheme. So we propose to remove the possibility to terminate PCP period when DL TPC reverses. The power control period would then terminate as specified by UTRAN in the PCP length info (power control info, TS 25.331).

5) In step a) we lay emphasis on the start of DPCCH transmission at UTRAN, and state that DPDCH transmission may be started as well if any data is to be sent on the downlink. Previously both transmissions starts were specified at the same level, as it may not be necessary to transmit DL DPDCH at the beginning of the procedure, we clarify that it 'may' be done but not 'shall' be done.

6) The TFCI word transmitted during the power control preamble period is changed from all-one to all-zero.

Note that some of the changes addressed in this document affect some sections that were already modified by two CRs from Philips [3] that were approved at last meeting in Pusan. Then, we have provided separately new CRs that reflects both changes.

### **REFERENCES:**

[1] R1-00-1274, Ericsson:	Radio link establishment and sync status reporting.
[2] R1-00-1293, Ericsson:	LS to WG2 on power control preamble length.
[3] R1-00-1197, Philips:	Clarifications of descriptions of power control preambles.
[4] R1-00-1215, Siemens:	TPC command generation on downlink during RLS initialisation.
[5] R1-00-1272, Siemens:	LS to WG3 on Radio Link Initialisation.

## 3GPP TSG RAN WG1#17 Stockholm, Sweden

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# 4 Synchronisation procedures

# 4.1 Cell search

During the cell search, the UE searches for a cell and determines the downlink scrambling code and common channel frame synchronisation of that cell. How cell search is typically done is described in Annex C.

# 4.2 Common physical channel synchronisation

The radio frame timing of all common physical channels can be determined after cell search. The P-CCPCH radio frame timing is found during cell search and the radio frame timing of all common physical channel are related to that timing as described in [1].

# 4.3 DPCCH/DPDCH synchronisation

# 4.3.1 Synchronisation primitives

### 4.3.1.1 General

For the dedicated channels, synchronisation primitives are used to indicate the synchronisation status of radio links, both in uplink and downlink. The definition of the primitives is given in the following subclauses.

### 4.3.1.2 Downlink synchronisation primitives

Layer 1 in the UE shall every radio frame check synchronisation status of the downlink dedicated channels. Synchronisation status is indicated to higher layers using the CPHY-Sync-IND and CPHY-Out-of-Sync-IND primitives.

Out-of-sync shall be reported using the CPHY-Out-of-Sync-IND primitive if either of the following criteria is fulfilled:

- The UE estimates the DPCCH quality over the last 200 ms period to be worse than a threshold Q<sub>out</sub>. This criterion shall never be fulfilled during the first 200 ms of the dedicated channel's existence. Q<sub>out</sub> is defined implicitly by the relevant tests in [7].
- The last 20 transport blocks, as observed on all TrCHs using CRC, are received with incorrect CRC. In addition, over the last 200 ms, no transport block has been received with correct CRC.

In-sync shall be reported using the CPHY-Sync-IND primitive if both of the following criteria are fulfilled:

- The UE estimates the DPCCH quality over the last 200 ms period to be better than a threshold Q<sub>in</sub>. This criterion shall always be fulfilled during the first 200 ms of the dedicated channel's existence. Q<sub>in</sub> is defined implicitly by the relevant tests in [7].
- At least one transport block, as observed on all TrCHs using CRC, is received with correct CRC. If there is no TrCH using CRC, this criterion is always fulfilled.

How the primitives are used by higher layers is described in [5].

### 4.3.1.3 Uplink synchronisation primitives

Layer 1 in the Node B shall every radio frame check synchronisation status of all radio link sets. Synchronisation status is indicated to the RL Failure/Restored triggering function using either the CPHY-Sync-IND or CPHY-Out-of-Sync-IND primitive. Hence, only one synchronisation status indication shall be given per radio link set.

The exact criteria for indicating in-sync/out-of-sync is not subject to specification, but could e.g. be based on received DPCCH quality or CRC checks. One example would be to have the same criteria as for the downlink synchronisation status primitives.

# 4.3.2 Radio link establishment

## 4.3.2.1 General

The establishment of a radio link can be divided into two cases:

- when there is no existing radio link, i.e. when at least one downlink dedicated physical channel and one uplink dedicated physical channel are to be set up;
- or when one or several radio links already exist, i.e. when at least one downlink dedicated physical channel is to be set up and an uplink dedicated physical channel already exists.

The two cases are described in subclauses 4.3.2.2 and 4.3.2.3 respectively.

In Node B, each radio link set can be in three different states: initial state, out-of-sync state and in-sync state. Transitions between the different states is shown in figure 1 below. The state of the Node B at the start of radio link establishment is described in the following subclauses. Transitions between initial state and in-sync state are described in subclauses 4.3.2.2 and 4.3.2.3 and transitions between the in-sync and out-of-sync states are described in subclause 4.3.3.2.



Figure 1: Node B radio link set states and transitions

### 4.3.2.2 No existing radio link

When one or several radio links are to be established and there is no existing radio link for the UE already, a dedicated physical channel is to be set up in uplink and at least one dedicated physical channel is to be set up in downlink. This corresponds to the case when a dedicated physical channel is initially set up on a frequency.

The radio link establishment is as follows:

- a) Node B considers the radio link sets which are to be set up to be in the initial state. UTRAN <u>shall</u> starts the transmission of <u>the</u> downlink DPCCH/<del>DPDCHs</del> and may start the transmission of DPDCH if any data is to be transmitted. The initial downlink DPCCH transmit power is set by higher layers [6].
- b) The UE establishes downlink chip and frame synchronisation of DPCCH/DPDCHs, using the P-CCPCH timing and timing offset information notified from UTRAN. Frame synchronisation can be confirmed using the frame synchronisation word. Downlink synchronisation status is reported to higher layers every radio frame according to subclause 4.3.1.2.
- c) If no activation time for uplink DPCCH/DPDCH has been signalled to the UE, uplink DPCCH/DPDCH transmission is shall started when higher layers consider the downlink physical channel established. If an activation time has been given, uplink DPCCH transmission shall not start before the downlink physical channel has been established and the activation time has been reached DPCCH/DPDCH transmission is started at the activation time or later, as soon as higher layers consider the downlink physical channel established. Physical channel establishment and activation time are defined in [5]. The initial uplink DPCCH transmit power is set by higher layers [5]. The total signalling response delay for the establishment of a new DPCH shall not exceed the requirements given in [8] sub-clause 7.3. If a power control preamble of non-zero length is used for initialisation of the DCH, The uplink DPDCH transmission shall not start before the end of the power control preamble. The length of the power control preamble is N<sub>pcp</sub> radio frames slots beginning at the start of uplink DPCCH transmission, where N<sub>pcp</sub> is a higher layer parameter set by UTRAN by the network (see section 5.1.2.4)[5]. Note that the transmission start delay between DPCCH and DPDCH may be cancelled using a power control

<u>preamble of 0 length.</u> The starting time for transmission of DPDCHs shall also satisfy the constraints on adding transport channels to a CCTrCH, as defined in [2] sub-clause 4.2.14.

d) UTRAN establishes uplink chip and frame synchronisation. Frame synchronisation can be confirmed using the frame synchronisation word. Radio link sets remain in the initial state until N\_INSYNC\_IND successive insync indications are received from layer 1, when Node B shall trigger the RL Restore procedure indicating which radio link set has obtained synchronis ation. When RL Restore has been triggered the radio link set shall be considered to be in the in-sync state. The parameter value of N\_INSYNC\_IND is configurable, see [6]. The RL Restore procedure may be triggered several times, indicating when synchronisation is obtained for different radio link sets.

### 4.3.2.3 One or several existing radio links

When one or several radio links are to be established and one or several radio links already exist, there is an existing DPCCH/DPDCH in the uplink, and at least one corresponding dedicated physical channel shall be set up in the downlink. This corresponds to the case when new radio links are added to the active set and downlink transmission starts for those radio links.

The radio link establishment is as follows:

- a) Node B considers new radio link sets to be set up to be in initial state. If a radio link is to be added to an existing radio link set this radio link set shall be considered to be in the state the radio link set was prior to the addition of the radio link, i.e. if the radio link set was in the in-sync state before the addition of the radio link it shall remain in that state.
- b) UTRAN starts the transmission of the downlink DPCCH/DPDCH at a frame timing such that the frame timing received at the UE will be within T<sub>0</sub>? 148 chips prior to the frame timing of the uplink DPCCH/DPDCH at the UE. Simultaneously, UTRAN establishes uplink chip and frame synchronisation of the new radio link. Frame synchronisation can be confirmed using the frame synchronization word. Radio link sets considered to be in the initial state shall remain in the initial state until N\_INSYNC\_IND successive in-sync indications are received from layer 1, when Node B shall trigger the RL Restore procedure indicating which radio link set has obtained synchronis ation. When RL Restore is triggered the radio link set shall be considered to be in the in-sync state. The parameter value of N\_INSYNC\_IND is configurable, see [6]. The RL Restore procedure may be triggered several times, indicating when synchronisation is obtained for different radio link sets.
- c) The UE establishes chip and frame synchronisation of the new radio link. Frame synchronisation can be confirmed using the frame synchronization word. Downlink synchronisation status shall be reported to higher layers every radio frame according to subclause 4.3.1.2.

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### 5.1.2.4 Transmit power control in DPCCH power control preamble

An UL DPCCH power control preamble is a period of UL DPCCH transmission prior to the start of the uplink DPDCH. A power control preamble may be used for initialisation of a DCH. Both the UL and The DL DPCCHs shall also be transmitted during the <u>an</u> uplink power control preamble. The UL DPDCH shall not commence before the end of the power control preamble.

The length of the power control preamble is a <u>UE specific higher layer parameter signalled by the network as defined in</u> [5], and can take the values 0 slots or 15 slots. The UL DPDCH shall not commence before the end of the power control preamble.

If the length of the power control preamble is greater than zero, the details of power control used during the power control preamble differ from the ordinary power control which is used afterwards. After the first slot of the power control preamble the change in uplink DPCCH transmit power shall initially be given by:

? ? <sub>DPCCH</sub> = ? <sub>TPC\_init</sub>? TPC\_cmd.

For PCA equal to 1 and 2, the value of ? TPC init is set to ? TPC-

During the power control preamble period Initially, TPC\_cmd is derived according to algorithm 1 as described in sub clause 5.1.2.2.1, regardless of the value of PCA.

Ordinary power control (see subclause 5.1.2.2), with the power control algorithm determined by the value of PCA and step size ? <sub>TPC</sub>, shall be used as soon as the sign of TPC\_emd reverses for the first time, or at after the end of the power control preamble <u>period</u> if the power control preamble ends first.

### 5.1.2.5 Setting of the uplink DPCCH/DPDCH power difference

#### 5.1.2.5.1 General

The uplink DPCCH and DPDCH(s) are transmitted on different codes as defined in subclause 4.2.1 of [3]. The gain factors  $?_c$  and  $?_d$  may vary for each TFC. There are two ways of controlling the gain factors of the DPCCH code and the DPDCH codes for different TFCs in normal (non-compressed) frames:

- ??  $?_c$  and  $?_d$  are signalled for the TFC, or
- ??  $?_c$  and  $?_d$  is computed for the TFC, based on the signalled settings for a reference TFC.

Combinations of the two above methods may be used to associate  $?_c$  and  $?_d$  values to all TFCs in the TFCS. The two methods are described in subclauses 5.1.2.5.2 and 5.1.2.5.3 respectively. Several reference TFCs may be signalled from higher layers.

The gain factors may vary on radio frame basis depending on the current TFC used. Further, the setting of gain factors is independent of the inner loop power control.

After applying the gain factors, the UE shall scale the total transmit power of the DPCCH and DPDCH(s), such that the DPCCH output power follows the changes required by the power control procedure with power adjustments of ? <sub>DPCCH</sub> dB, subject to the provisions of sub-clause 5.1.2.6.

The gain factors during compressed frames are based on the nominal power relation defined in normal frames, as specified in subclause 5.1.2.5.4.

#### 5.1.2.5.2 Signalled gain factors

When the gain factors  $?_c$  and  $?_d$  are signalled by higher layers for a certain TFC, the signalled values are used directly for weighting of DPCCH and DPDCH(s). The variable  $A_j$ , called the nominal power relation is then computed as:

$$A_j ? \frac{?_d}{?_c}.$$

# 5.1.3 PCPCH

### 5.1.3.1 General

The power control during the CPCH access procedure is described in clause 6.2. The inner loop power control for the PCPCH is described in the following sub-clauses.

### 5.1.3.2 Power control in the message part

The uplink transmit power control procedure simultaneously controls the power of a PCPCH control part and its corresponding PCPCH data part. The relative transmit power offset between the PCPCH control part and the PCPCH data part is determined by the network and is computed according to sub-clause 5.1.2.5 using the gain factors signalled to the UE using higher-layer signalling, with the difference that:

- ?<sub>c</sub> is the gain factor for the PCPCH control part (similar to DPCCH);
- $?_d$  is the gain factor for the PCPCH data part (similar to DPDCH).

The gain factors are applied as shown in sub clause 4.2.3.2 of 25.213.

The operation of the inner power control loop adjusts the power of the PCPCH control part and PCPCH data part by the same amount, provided there are no changes in gain factors.

Any change in the uplink PCPCH control part transmit power shall take place immediately before the start of the pilot field on the control part of the message part. The change in PCPCH control part power with respect to its value in the previous slot is derived by the UE and is denoted by ?<sub>PCPCH-CP</sub> (in dB).

During the operation of the uplink power control procedure the UE transmit power shall not exceed a maximum allowed value which is the lower out of the maximum output power of the terminal power class and a value which may be set by higher layer signalling.

Uplink power control shall be performed while the UE transmit power is below the maximum allowed output power.

The provisions for power control at the maximum allowed value and below the required minimum output power (as defined in [7]) are described in sub-clause 5.1.2.6.

The uplink inner-loop power control adjusts the UE transmit power in order to keep the received uplink signal-to-interference ratio (SIR) at a given SIR target, SIR<sub>target</sub>, which is set by the higher layer outer loop.

The network should estimate the signal-to-interference ratio SIR<sub>est</sub> of the received PCPCH . The network should then generate TPC commands and transmit the commands once per slot according to the following rule: if SIR<sub>est</sub> > SIR<sub>target</sub> then the TPC command to transmit is "0", while if SIR<sub>est</sub> < SIR<sub>target</sub> then the TPC command to transmit is "1".

The UE derives a TPC command, TPC\_cmd, for each slot. Two algorithms shall be supported by the UE for deriving a TPC\_cmd. Which of these two algorithms is used is determined by a higher-layer parameter,

"PowerControlAlgorithm", and is under the control of the UTRAN. If "PowerControlAlgorithm" indicates "algorithm1", then the layer 1 parameter PCA shall take the value 1 and if "PowerControlAlgorithm" indicates "algorithm2" then PCA shall take the value 2.

If PCA has the value 1, Algorithm 1, described in subclause 5.1.2.2.2, shall be used for processing TPC commands.

If PCA has the value 2, Algorithm 2, described in subclause 5.1.2.2.3, shall be used for processing TPC commands.

The step size  $?_{TPC}$  is a layer 1 parameter which is derived from the higher-layer parameter "TPC-StepSize" which is under the control of the UTRAN. If "TPC-StepSize" has the value "dB1", then the layer 1 parameter ?<sub>TPC</sub> shall take the value 1 dB and if "TPC-StepSize" has the value "dB2", then ?<sub>TPC</sub> shall take the value 2 dB.

After deriving the TPC command TPC\_cmd using one of the two supported algorithms, the UE shall adjust the transmit power of the uplink PCPCH control part with a step of  $?_{PCPCH-CP}$  (in dB) which is given by:

?<sub>PCPCH-CP</sub> = ?<sub>TPC</sub>? TPC\_cmd

### 5.1.3.3 Power control in the power control preamble

A <u>PCPCH</u> power control preamble may be used for initialisation of a <u>PCPCH</u> is a period when <u>Bb</u> oth the UL PCPCH control part and <u>the</u> associated DL DPCCH <u>shall beare</u> transmitted <u>during the uplink power control preamble prior to the</u> <u>start of the uplink PCPCH data part</u>. The uplink PCPCH data part shall not commence before the end of the power <u>control preamble</u>.

The length of the power control preamble is a higher layer parameter,  $L_{pc-preamble}$  (see section 6.2), and can take the value 0 slots or 8 slots. The uplink PCPCH data part shall not commence before the end of the power control preamble.

If  $L_{pc-preamble} > 0$ , the details of power control used during the power control preamble differ from the ordinary power control which is used afterwards. After the first slot of the power control preamble the change in uplink PCPCH control part transmit power shall initially be given by:

? PCPCH-CP = ? TPC-init ? TPC\_cmd

If the value of PCA is 1 then ? TPC-init is equal to the minimum value out of 3 dB and 2? TPC.

If the value of PCA is 2 then ? TPC-init is equal to 2dB.

TPC\_cmd is derived according to algorithm 1 as described in sub clause 5.1.2.2.2, regardless of the value of PCA.

Power control as defined for the message part (see sub-clause 5.1.3.2), with the power control algorithm determined by the value of PCA and step size ? <sub>TPC</sub>, shall be used as soon as the sign of TPC\_cmd reverses for the first time, or at the end of the power control preamble if the power control preamble ends first.

# 5.2 Downlink power control

The transmit power of the downlink channels is determined by the network. In general the ratio of the transmit power between different downlink channels is not specified and may change with time. However, regulations exist as described in the following subclauses.

Higher layer power settings shall be interpreted as setting of the total power, i.e. the sum of the power from the two antennas in case of transmit diversity.

## 5.2.1 DPCCH/DPDCH

#### 5.2.1.1 General

The downlink transmit power control procedure controls simultaneously the power of a DPCCH and its corresponding DPDCHs. The power control loop adjusts the power of the DPCCH and DPDCHs with the same amount, i.e. the relative power difference between the DPCCH and DPDCHs is not changed.

The relative transmit power offset between DPCCH fields and DPDCHs is determined by the network The TFCI, TPC and pilot fields of the DPCCH are offset relative to the DPDCHs power by PO1, PO2 and PO3 dB respectively. The power offsets may vary in time. The method for controlling the power offsets within UTRAN is specified in [6]

The power of CCC field in DL DPCCH for CPCH is the same as the power of the pilot field.

### 5.2.1.2 Ordinary transmit power control

### 5.2.1.2.1 UE behaviour

The UE shall generate TPC commands to control the network transmit power and send them in the TPC field of the uplink DPCCH. An example on how to derive the TPC commands in given in Annex B.2.

The UE shall check the downlink power control mode (DPC\_MODE) before generating the TPC command:

- if DPC\_MODE = 0 : the UE sends a unique TPC command in each slot and the TPC command generated is transmitted in the first available TPC field in the uplink DPCCH;

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## 5.2.1 Dedicated uplink physical channels

There are two types of uplink dedicated physical channels, the uplink Dedicated Physical Data Channel (uplink DPDCH) and the uplink Dedicated Physical Control Channel (uplink DPCCH).

The DPDCH and the DPCCH are I/Q code multiplexed within each radio frame (see [4]).

The uplink DPDCH is used to carry the DCH transport channel. There may be zero, one, or several uplink DPDCHs on each radio link.

The uplink DPCCH is used to carry control information generated at Layer 1. The Layer 1 control information consists of known pilot bits to support channel estimation for coherent detection, transmit power-control (TPC) commands, feedback information (FBI), and an optional transport-format combination indicator (TFCI). The transport-format combination indicator informs the receiver about the instantaneous transport format combination of the transport channels mapped to the simultaneously transmitted uplink DPDCH radio frame. There is one and only one uplink DPCCH on each radio link.

Figure 1 shows the frame structure of the uplink dedicated physical channels. Each radio frame of length 10 ms is split into 15 slots, each of length  $T_{slot} = 2560$  chips, corresponding to one power-control period.



Figure 1: Frame structure for uplink DPDCH/DPCCH

The parameter k in figure 1 determines the number of bits per uplink DPDCH slot. It is related to the spreading factor SF of the DPDCH as  $SF = 256/2^k$ . The DPDCH spreading factor may range from 256 down to 4. The spreading factor of the uplink DPCCH is always equal to 256, i.e. there are 10 bits per uplink DPCCH slot.

The exact number of bits of the uplink DPDCH and the different uplink DPCCH fields ( $N_{pilot}$ ,  $N_{TFCI}$ ,  $N_{FBI}$ , and  $N_{TPC}$ ) is given by table 1 and table 2. What slot format to use is configured by higher layers and can also be reconfigured by higher layers.

The channel bit and symbol rates given in table 1 and table 2 are the rates immediately before spreading. The pilot patterns are given in table 3 and table 4, the TPC bit pattern is given in table 5.

The FBI bits are used to support techniques requiring feedback from the UE to the UTRAN Access Point, including closed loop mode transmit diversity and site selection diversity transmission (SSDT). The structure of the FBI field is shown in figure 2 and described below.



Figure 2: Details of FBI field

The S field is used for SSDT signalling, while the D field is used for closed loop mode transmit diversity signalling. The S field consists of 0, 1 or 2 bits. The D field consists of 0 or 1 bit. The total FBI field size  $N_{FBI}$  is given by table 2. If total FBI field is not filled with S field or D field, FBI field shall be filled with "1". When  $N_{FBI}$  is 2bits, S field is 0bit and D field is 1 bit, left side field shall be filled with "1" and right side field shall be D field. Simultaneous use of SSDT power control and closed loop mode transmit diversity requires that the S field consists of 1 bit. The use of the FBI fields is described in detail in [5].

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Slot Format #i	Channel Bit Rate	Channel Symbol	SF	Bits/	Bits/	N <sub>data</sub>
	(kbps)	Rate (ksps)		Frame	Slot	
0	15	15	256	150	10	10
1	30	30	128	300	20	20
2	60	60	64	600	40	40
3	120	120	32	1200	80	80
4	240	240	16	2400	160	160
5	480	480	8	4800	320	320
6	960	960	4	9600	640	640

#### Table 1: DPDCH fields

There are two types of uplink dedicated physical channels; those that include TFCI (e.g. for several simultaneous services) and those that do not include TFCI (e.g. for fixed-rate services). These types are reflected by the duplicated rows of table 2. It is the UTRAN that determines if a TFCI should be transmitted and it is mandatory for all UEs to support the use of TFCI in the uplink. The mapping of TFCI bits onto slots is described in [3].

In compressed mode, DPCCH slot formats with TFCI fields are changed. There are two possible compressed slot formats for each normal slot format. They are labelled A and B and the selection between them is dependent on the number of slots that are transmitted in each frame in compressed mode.

Slot Form	Channel Bit Rate (kbps)	Channel Symbol Rate (ksps)	SF	Bits/ Frame	Bits/ Slot	Npilot	NTPC	NTFCI	N <sub>FBI</sub>	Transmitted slots per
at #I										radio frame
0	15	15	256	150	10	6	2	2	0	15
0A	15	15	256	150	10	5	2	3	0	10-14
0B	15	15	256	150	10	4	2	4	0	8-9
1	15	15	256	150	10	8	2	0	0	8-15
2	15	15	256	150	10	5	2	2	1	15
2A	15	15	256	150	10	4	2	3	1	10-14
2B	15	15	256	150	10	3	2	4	1	8-9
3	15	15	256	150	10	7	2	0	1	8-15
4	15	15	256	150	10	6	2	0	2	8-15
5	15	15	256	150	10	5	1	2	2	15
5A	15	15	256	150	10	4	1	3	2	10-14
5B	15	15	256	150	10	3	1	4	2	8-9

### Table 2: DPCCH fields

The pilot bit patterns are described in table 3 and table 4. The shadowed column part of pilot bit pattern is defined as FSW and FSWs can be used to confirm frame synchronization. (The value of the pilot bit pattern other than FSWs shall be "1".)

	N	pilot =	3		Npilo	t = 4			N	pilot =	5				Npilo	t = 6		
Bit#	0	1	2	0	1	2	3	0	1	2	3	4	0	1	2	3	4	5
Slot #0	1	1	1	1	1	1	1	1	1	1	1	0	1	1	1	1	1	0
1	0	0	1	1	0	0	1	0	0	1	1	0	1	0	0	1	1	0
2	0	1	1	1	0	1	1	0	1	1	0	1	1	0	1	1	0	1
3	0	0	1	1	0	0	1	0	0	1	0	0	1	0	0	1	0	0
4	1	0	1	1	1	0	1	1	0	1	0	1	1	1	0	1	0	1
5	1	1	1	1	1	1	1	1	1	1	1	0	1	1	1	1	1	0
6	1	1	1	1	1	1	1	1	1	1	0	0	1	1	1	1	0	0
7	1	0	1	1	1	0	1	1	0	1	0	0	1	1	0	1	0	0
8	0	1	1	1	0	1	1	0	1	1	1	0	1	0	1	1	1	0
9	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
10	0	1	1	1	0	1	1	0	1	1	0	1	1	0	1	1	0	1
11	1	0	1	1	1	0	1	1	0	1	1	1	1	1	0	1	1	1
12	1	0	1	1	1	0	1	1	0	1	0	0	1	1	0	1	0	0
13	0	0	1	1	0	0	1	0	0	1	1	1	1	0	0	1	1	1
14	0	0	1	1	0	0	1	0	0	1	1	1	1	0	0	1	1	1

Table 3: Pilot bit patterns for uplink DPCCH with N<sub>pilot</sub> = 3, 4, 5 and 6

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#### Table 4: Pilot bit patterns for uplink DPCCH with $N_{pilot} = 7$ and 8

		N <sub>pilot</sub> = 7								N <sub>pilot</sub> = 8					
Bit #	0	1	2	3	4	5	6	0	1	2	3	4	5	6	7
Slot #0	1	1	1	1	1	0	1	1	1	1	1	1	1	1	0
1	1	0	0	1	1	0	1	1	0	1	0	1	1	1	0
2	1	0	1	1	0	1	1	1	0	1	1	1	0	1	1
3	1	0	0	1	0	0	1	1	0	1	0	1	0	1	0
4	1	1	0	1	0	1	1	1	1	1	0	1	0	1	1
5	1	1	1	1	1	0	1	1	1	1	1	1	1	1	0
6	1	1	1	1	0	0	1	1	1	1	1	1	0	1	0
7	1	1	0	1	0	0	1	1	1	1	0	1	0	1	0
8	1	0	1	1	1	0	1	1	0	1	1	1	1	1	0
9	1	1	1	1	1	1	1	1	1	1	1	1	1	1	1
10	1	0	1	1	0	1	1	1	0	1	1	1	0	1	1
11	1	1	0	1	1	1	1	1	1	1	0	1	1	1	1
12	1	1	0	1	0	0	1	1	1	1	0	1	0	1	0
13	1	0	0	1	1	1	1	1	0	1	0	1	1	1	1
14	1	0	0	1	1	1	1	1	0	1	0	1	1	1	1

The relationship between the TPC bit pattern and transmitter power control command is presented in table 5.

Table 5:	TPC	Bit	Pattern
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TPC Bit	Pattern	Transmitter power control command				
N <sub>TPC</sub> = 1	N <sub>TPC</sub> = 2					
1	11	1				
0	00	0				

Multi-code operation is possible for the uplink dedicated physical channels. When multi-code transmission is used, several parallel DPDCH are transmitted using different channelization codes, see [4]. However, there is only one DPCCH per radio link.

An <u>uplink DPCCH</u> power control preamble <u>shall may</u> be used for initialisation of a DCH. Both the UL and DL DPCCHs shall be transmitted during the power control preamble. The length of the power control preamble is a UE specific higher layer parameter,  $N_{pcp}$  (see [5], section 5.1.2.4), signalled by the network [5]. The UL DPCCH shall take the same slot format in the power control preamble as afterwards, as given in table 2. When,  $N_{pcp} > 0$  the pilot patterns from slot #(15 -  $N_{pcp}$ ) to slot #14 of table 3 and table 4 shall be used. The timing of the power control preamble is described in [5], subclause 4.3.2.2. The TFCI field is filled with "04" bits.

# 5.3.2 Dedicated downlink physical channels

There is only one type of downlink dedicated physical channel, the Downlink Dedicated Physical Channel (downlink DPCH).

Within one downlink DPCH, dedicated data generated at Layer 2 and above, i.e. the dedicated transport channel (DCH), is transmitted in time-multiplex with control information generated at Layer 1 (known pilot bits, TPC commands, and an optional TFCI). The downlink DPCH can thus be seen as a time multiplex of a downlink DPDCH and a downlink DPCCH, compare subclause 5.2.1.

Figure 9 shows the frame structure of the downlink DPCH. Each frame of length 10 ms is split into 15 slots, each of length  $T_{slot} = 2560$  chips, corresponding to one power-control period.



One radio frame,  $T_f = 10 \text{ ms}$ 



The parameter k in figure 9 determines the total number of bits per downlink DPCH slot. It is related to the spreading factor SF of the physical channel as  $SF = 512/2^k$ . The spreading factor may thus range from 512 down to 4.

The exact number of bits of the different downlink DPCH fields ( $N_{pilot}$ ,  $N_{TPC}$ ,  $N_{TFCI}$ ,  $N_{data1}$  and  $N_{data2}$ ) is given in table 11. What slot format to use is configured by higher layers and can also be reconfigured by higher layers.

There are basically two types of downlink Dedicated Physical Channels; those that include TFCI (e.g. for several simultaneous services) and those that do not include TFCI (e.g. for fixed-rate services). These types are reflected by the duplicated rows of table 11. It is the UTRAN that determines if a TFCI should be transmitted and it is mandatory for all UEs to support the use of TFCI in the downlink. The mapping of TFCI bits onto slots is described in [3].

In compressed mode, a different slot format is used compared to normal mode. There are two possible compressed slot formats that are labelled A and B. Format B is used for compressed mode by spreading factor reduction and format A is used for all other transmission time reduction methods. The channel bit and symbol rates given in table 11 are the rates immediately before spreading.

Slot	Channel	Channel	SF	Bits/	DP	DPDCH DPCCH			Transmitted		
Format	Bit Rate	Symbol		Slot	Bits	/Slot	В	Bits/Slot		slots per	
#i	(kbps)	Rate						Dito/Olot		radio frame	
	、 i ,	(ksps)			N-	Ne	Nera Nera Ner		N <sub>Tr</sub>		
		· · /			INData1	INData2	INTPC	INTECI	Pilot		
0	15	7.5	512	10	0	4	2	0	4	15	
0A	15	7.5	512	10	0	4	2	0	4	8-14	
0B	30	15	256	20	0	8	4	0	8	8-14	
1	15	7.5	512	10	0	2	2	2	4	15	
1B	30	15	256	20	0	4	4	4	8	8-14	
2	30	15	256	20	2	14	2	0	2	15	
2A	30	15	256	20	2	14	2	0	2	8-14	
2B	60	30	128	40	4	28	4	0	4	8-14	
3	30	15	256	20	2	12	2	2	2	15	
ЗA	30	15	256	20	2	10	2	4	2	8-14	
3B	60	30	128	40	4	24	4	4	4	8-14	
4	30	15	256	20	2	12	2	0	4	15	
4A	30	15	256	20	2	12	2	0	4	8-14	
4B	60	30	128	40	4	24	4	0	8	8-14	
5	30	15	256	20	2	10	2	2	4	15	
5A	30	15	256	20	2	8	2	4	4	8-14	
5B	60	30	128	40	4	20	4	4	8	8-14	
6	30	15	256	20	2	8	2	0	8	15	
6A	30	15	256	20	2	8	2	0	8	8-14	
6B	60	30	128	40	4	16	4	0	16	8-14	
7	30	15	256	20	2	6	2	2	8	15	
7A	30	15	256	20	2	4	2	4	8	8-14	
7B	60	30	128	40	4	12	4	4	16	8-14	
8	60	30	128	40	6	28	2	0	4	15	
84	60	30	128	40	6	28	2	0	4	8-14	
8B	120	60	64	80	12	56	4	0	8	8-14	
90D	60	30	128	40	6	26	7	2	1	15	
ο <u>Δ</u>	60	30	120	40	6	20	2	2 1	4	8-1/	
0R	120	60	64	80	12	52	1		8	8-14	
3D 10	60	20	120	40	6	24	+ 2	4	0	15	
104	60	30	120	40	6	24	2	0	0	9.14	
10A 10D	120		64	40	10	24 40	2	0	0	0-14	
100	60	20	120	<u> </u>	12	40	4	0	10	0-14	
11	60	20	120	40	0	22	2	Z	0	0.14	
110	120		64	40	10	20	2	4	0	0-14	
10	120	60	64	80	12	44	4	4	10	0-14	
12	120	60	64	80	12	40	4	0	0	10	
12A 12D	120	120	04	00 160	12	40	4	10	0	0-14	
120	240	120	32	160	24	90	0	0*	10	0-14	
124	240	120	32	160	20	112	4	0	0	10	
13A 40D	240	120	32	160	20	104	4	10	0	0-14	
138	480	240	10	320	56	224	ð	10"	10	8-14	
14	480	240	10	320	56	232	ð	0" 16*	10		
14A	400	24U	01	320	00	ZZ4	0 10	10	10	0-14	
14B	900	400	Ø	640	112	404	01	01	3Z	0-14 1 <i>E</i>	
15	900	400	Ø	640	120	400 400	Ő O	0	10		
ACD	900	480	ŏ	040	120	480	ð 10	10"	10	8-14	
108	1920	900	4	1280	240	9/6	16	010	32	8-14	
10	1920	006	4	1200	∠4ŏ	1000	Ø	0	10	CI	
16A	1920	960	4	1280	248	992	g	16^	16	8-14	

#### Table 11: DPDCH and DPCCH fields

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\* If TFCI bits are not used, then DTX shall be used in TFCI field.

NOTE1: Compressed mode is only supported through spreading factor reduction for SF=512 with TFCI.

NOTE2: Compressed mode by spreading factor reduction is not supported for SF=4.

The pilot bit patterns are described in table 12. The shadowed column part of pilot bit pattern is defined as FSW and FSWs can be used to confirm frame synchronization. (The value of the pilot bit pattern other than FSWs shall be "11".) In table 12, the transmission order is from left to right.

In downlink compressed mode through spreading factor reduction, the number of bits in the TPC and Pilot fields are doubled. Symbol repetition is used to fill up the fields. Denote the bits in one of these fields in normal mode by  $x_1, x_2$ ,  $x_3, ..., x_X$ . In compressed mode the following bit sequence is sent in corresponding field:  $x_1, x_2, x_1, x_2, x_3, x_4, x_3, x_4, ..., x_X$ .

	N <sub>pilot</sub> = 2	N <sub>pilo</sub> (*	.t <b>= 4</b> 1)	N <sub>pilot</sub> = 8 (*2)				N <sub>pilot</sub> = 16 (*3)							
Symbol #	0	0	1	0	1	2	3	0	1	2	3	4	5	6	7
Slot #0	11	11	11	11	11	11	10	11	11	11	10	11	11	11	10
1	00	11	00	11	00	11	10	11	00	11	10	11	11	11	00
2	01	11	01	11	01	11	01	11	01	11	01	11	10	11	00
3	00	11	00	11	00	11	00	11	00	11	00	11	01	11	10
4	10	11	10	11	10	11	01	11	10	11	01	11	11	11	11
5	11	11	11	11	11	11	10	11	11	11	10	11	01	11	01
6	11	11	11	11	11	11	00	11	11	11	00	11	10	11	11
7	10	11	10	11	10	11	00	11	10	11	00	11	10	11	00
8	01	11	01	11	01	11	10	11	01	11	10	11	00	11	11
9	11	11	11	11	11	11	11	11	11	11	11	11	00	11	11
10	01	11	01	11	01	11	01	11	01	11	01	11	11	11	10
11	10	11	10	11	10	11	11	11	10	11	11	11	00	11	10
12	10	11	10	11	10	11	00	11	10	11	00	11	01	11	01
13	00	11	00	11	00	11	11	11	00	11	11	11	00	11	00
14	00	11	00	11	00	11	11	11	00	11	11	11	10	11	01

Table 12: Pilot bit patterns for downlink DPCCH with  $N_{pilot} = 2, 4, 8$  and 16

NOTE \*1: This pattern is used except slot formats 2B and 3B.

NOTE \*2: This pattern is used except slot formats 0B, 1B, 4B, 5B, 8B, and 9B.

NOTE \*3: This pattern is used except slot formats 6B, 7B, 10B, 11B, 12B, and 13B.

NOTE: For slot format *n*B where n = 0, ..., 15, the pilot bit pattern corresponding to  $N_{pilot}/2$  is to be used and symbol repetition shall be applied.

The relationship between the TPC symbol and the transmitter power control command is presented in table 13.

	Transmitter power		
N <sub>TPC</sub> = 2	N <sub>TPC</sub> = 4	N <sub>TPC</sub> = 8	control command
11	1111	11111111	1
00	0000	00000000	0

#### Table 13: TPC Bit Pattern

Multicode transmission may be employed in the downlink, i.e. the CCTrCH (see [3]) is mapped onto several parallel downlink DPCHs using the same spreading factor. In this case, the Layer 1 control information is transmitted only on the first downlink DPCH. DTX bits are transmitted during the corresponding time period for the additional downlink DPCHs, see figure 10.

In case there are several CCTrCHs mapped to different DPCHs transmitted to the same UE different spreading factors can be used on DPCHs to which different CCTrCHs are mapped. Also in this case, Layer 1 control information is only transmitted on the first DPCH while DTX bits are transmitted during the corresponding time period for the additional DPCHs.



Figure 10: Downlink slot format in case of multi-code transmission

A power control preamble may be used for initialisation of a DCH. The DL DPCH shall take the same slot format in the power control preamble as afterwards, as given in Table 11, with the restriction that DTX shall be used in the DL DPDCH fields in the power control preamble. The length of the power control preamble is a UE specific higher layer parameter,  $N_{pep}$  (see [5], section 5.1.2.4), signalled by the network. When  $N_{pep} > 0$ , the pilot patterns from slot #(15 -  $N_{pep}$ ) to slot #14 of table 12 shall be used. The TFCI field is filled with "1" bits.

### 5.3.2.1 STTD for DPCH

The pilot bit pattern for the DPCH channel transmitted on antenna 2 is given in table 14.

- For N<sub>pilot</sub> = 8, 16 the shadowed part indicates pilot bits that are obtained by STTD encoding the corresponding (shadowed) bits in Table 12. The non-shadowed pilot bit pattern is orthogonal to the corresponding (non-shadowed) pilot bit pattern in table 12.
- For  $N_{pilot} = 4$ , the diversity antenna pilot bit pattern is obtained by STTD encoding both the shadowed and non-shadowed pilot bits in table 12.
- For  $N_{pilot} = 2$ , the diversity antenna pilot pattern is obtained by STTD encoding the two pilot bits in table 12 with the last two bits (data or DTX) of the second data field (data2) of the slot. Thus for  $N_{pilot} = 2$  case, the last two bits of the second data field (data 2) after STTD encoding, follow the diversity antenna pilot bits in Table 14.

STTD encoding for the DPDCH, TPC, and TFCI fields is done as described in subclause 5.3.1.1.1. For the SF=512 DPCH, the first two bits in each slot, i.e. TPC bits, are not STTD encoded and the same bits are transmitted with equal power from the two antennas. The remaining four bits are STTD encoded.

For compressed mode through spreading factor reduction and for  $N_{pilot} > 4$ , symbol repetition shall be applied to the pilot bit patterns of table 14, in the same manner as described in 5.3.2. For slot formats 2B and 3B, i.e. compressed mode through spreading factor reduction and  $N_{pilot} = 4$ , the pilot bits transmitted on antenna 2 are STTD encoded, and thus the pilot bit pattern is as shown in the most right set of table 14.