3GPP TSG-RAN WG1 Meeting #110bis R1-220xxxx

e-Meeting, October 10th – 14th, 2022

**Agenda item:** 7.1

**Source:** Moderator (Qualcomm Incorporated)

**Title:** [110bis-e-NR-R15-08] - Discussion on timeline for group power control command

**Document for:** Discussion and Decision

# Background

This email discussion is to treat the following contribution (CR for Rel-16):

R1-2209934 Draft CR on Clarification on timelines for group power control command Qualcomm Incorporated

The contribution above proposes to define the timelines for group power control as . According to the proponents, based on the current specifications the UE has zero or negative time to decode a DCI and apply the TPC command. For completeness, the “reasons for change”, “summary of change” and actual CR change are shown below:

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| ***Reason for change:*** | Current specification does not clarify what is the required timeline for application of TPC commands carried over group DCIs (DCI format 2\_2 scrambled by TPC-PUCCH-RNTI or TPC-PUSCH-RNTI, or DCI format 2\_3 scrambled by TPC-SRS-RNTI).  For instance, if we conside the case of using 2\_2 for power control of CG-PUSCH, where the CG-PUSCH reads as follows (TS 38.213, 7.1.1):  - If a PUSCH transmission is configured by *ConfiguredGrantConfig*, is a number of symbols equal to the product of a number of symbols per slot, , and the minimum of the values provided by *k2* in *PUSCH-ConfigCommon* for active UL BWP of carrier of serving cell  *k2* is defined in TS 38.331 as follows:  PUSCH-TimeDomainResourceAllocation ::=  SEQUENCE {     k2                                      INTEGER(0..32)                                  OPTIONAL,   -- Need S     mappingType                             ENUMERATED {typeA, typeB},     startSymbolAndLength                    INTEGER (0..127) }  The minimum value for *k2* is zero, therefore can be zero. This leads to the UE having to apply the TPC command non-causally, which is non-implementable.  A similar issue is present in subclause 7.2.1 for PUCCH and 7.3.1 for SRS. |
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| ***Summary of change:*** | Clarify that the timeline between the reception of a TPC command and its application to a PUSCH is . This timeline is the same as the one defined in 11.1.1. |

11.3 Group TPC commands for PUCCH/PUSCH

**<Unchanged parts are omitted>**

The UE does not expect to apply a TPC command on a PUSCH or PUCCH transmission if the first symbol of the PUCCH or the PUSCH occurs within relative to a last symbol of a CORESET where the UE detects the DCI format 2\_2 carrying the TPC command. is the PUSCH preparation time for the corresponding UE processing capability [6, TS 38.214] assuming , and corresponds to the smallest SCS configuration between the SCS configuration of the PDCCH carrying the DCI format 2\_2 and the SCS configuration of the PUCCH or PUSCH.

11.4 SRS switching

**<Unchanged parts are omitted>**

The UE does not expect to apply a TPC command on an SRS transmission if the first symbol of the SRS occurs within relative to a last symbol of a CORESET where the UE detects the DCI format 2\_3 carrying the TPC command. is the PUSCH preparation time for the corresponding UE processing capability [6, TS 38.214] assuming , and corresponds to the smallest SCS configuration between the SCS configuration of the PDCCH carrying the DCI format 2\_3 and the SCS configuration of the SRS.

1. Discussion – Round 1

Please provide input by Tuesday 11th 23:59pm CET

**Q1: Do you agree that the current timelines for power control are not defined (potentially leading to unimplementable UEs) and, therefore, a CR is needed?**

* **If the answer is negative, please provide your understanding on the minimum time between end of the PDCCH carrying a DCI 2\_2 or 2\_3 and the first channel/signal the UE has to apply the power control to (in actual time).**

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| Company | Comment |
| Huawei, HiSilicon | No.  Because the concerned timelines were explicitly discussed and the following agreements were achieved in RAN1#93, along with TPs achieved in RAN1#94. It is not true to claim “not defined”.  The only issue is that for a special case with minimum configured k2=0, whether the Tproc,2 specified in TS 38.214 should be taken into account for the timeline of applying TPC to a configured PUSCH. Since the k2 is always subject to Tproc,2, zero k2 does not mean that a UE can response with zero symbol gap but a gap larger than Tproc,2. With this common understanding, for the issue above, Tproc,2 should be taken into account. A CR could be OK to clarify it only for the specific case with minimum k2=0. For the other cases, it is unclear for us why new UE behaviours causing NBC issues are needed.  **RAN1#93**  **Agreement:**  K value for non-scheduled UL transmission is the minimum of the common configured K2 values of the associated BWP.   * Applies for both PUSCH and SRS   **Working Assumption**  For PUCCH, K value for non-scheduled UL transmission is the minimum of the common configured K2 values  **Working Assumption**  For group common TPC   * If group TPC commands for PUSCH are received the K symbols before PUSCH transmission period i, the accumulation is updated according to all the group common TPC commands; * If group TPC commands for PUCCH are received the K symbols before PUCCH transmission period i, the accumulation is updated according to all the group common TPC commands; * If group TPC commands for SRS not tied with PUSCH are received the K symbols before SRS transmission period i, the accumulation is updated according to all the group common TPC commands;   Notes: How to capture the above is up to editor, especially for the time unit of i and K.  **RAN1#94**  **Agreement**  Following working assumption is confirmed  For PUCCH, K value for non-scheduled UL transmission is the minimum of the common configured K2 values  **Agreement**  The text in the paragraph on the PUSCH power control in {38.213: 7.1.1 UE behaviour}.   |  | | --- | | - If the PUSCH transmission is configured by higher layer parameter *ConfiguredGrantConfig*,  is a number of  symbols equal to the product of a number of symbols per slot, , and the minimum of the values provided by higher layer parameter *k2* in *PUSCH-ConfigCommon* and for UL BWP  of carrier  of serving cell |   **Agreement**  The text in the paragraph on the PUCCH power control in {38.213:7.2.1 UE behaviour}.   |  | | --- | | - If the PUCCH transmission is not in response to a detection by the UE of a DCI format 1\_0 or DCI format 1\_1,  is a number of  symbols equal to the product of a number of symbols per slot, , and the minimum of the values provided by higher layer parameter *k2* in *PUSCH-ConfigCommon* and for UL BWP  of carrier  of serving cell |   **Agreement**  The text in the paragraph on the SRS power control in {38.213: 7.3.1 UE behaviour}.   |  | | --- | | - if the SRS transmission is semi-persistent or periodic,  is a number of  symbols equal to the product of a number of symbols per slot, , and the minimum of the values provided by higher layer parameter *k2* in *PUSCH-ConfigCommon* and for UL BWP  of carrier  of serving cell | |
| CATT | We don’t see the need of this CR. The timeline of applying TPC command had been discussed in Rel-15 was based on the processing time between receiving TPC command and PUSCH/SRS transmission. There was no consensus during Rel-15 discussion to capture this timeline explicitly in the specification. Thus, we don’t need to re-open the discussion. |
| Qualcomm | Yes.  Regarding the comment from Huawei, we would like to highlight that *k2* is cell-specific, so there may be cases where the *k2* contains delays that a given UE may not support (e.g. if we have a mix of Cap1 and Cap2 devices).  Regarding the comment from CATT, is the understanding that the timeline is not explicitly captured, and the UE can decide when to apply the TPC command? |

**Q2: If the questions to Q1 is “YES”, do you have any comments on the CR? (e.g. value of processing time, how to capture the restriction, etc.)**

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1. Conclusions

TBD