### RP-010334

# TSG-RAN Meeting #12 Stockholm, Sweden, 12-15, June, 2001

Title: Agreed CRs (R99 and Rel-4 Category A) to TS 25.214

Source: TSG-RAN WG1

Agenda item: 8.1.3

No.	Spec	CR	Rev	R1 T-doc	Subject		Cat	W / I Code	$V\_old$	V_new
1	25.214	165	1	R1-01-0554	Limited power raise: aligning of terminology with TS25.433	R99	D	TEI	3.6.0	3.7.0
2	25.214	166	1	R1-01-0554	Limited power raise: aligning of terminology with TS25.433	REL-4	Α	TEI4	4.0.0	4.1.0
3	25.214	184	1	R1-01-0617	Correction of IPDL burst parameters	R99	F	TEI	3.6.0	3.7.0
4	25.214	167	1	R1-01-0617	Correction of IPDL burst parameters	REL-4	Α	LCS1-UEpos	4.0.0	4.1.0
5	25.214	168	1	R1-01-0614	Correction of synchronisation primitives	R99	F	TEI	3.6.0	3.7.0
6	25.214	169	1	R1-01-0614	Correction of synchronisation primitives	REL-4	Α	TEI4	4.0.0	4.1.0
7	25.214	176	1	R1-01-0615	Clarification on TPC command generation on downlink during RL initialisation	R99	F	TEI	3.6.0	3.7.0
8	25.214	177	1	R1-01-0615	Clarification on TPC command generation on downlink during RL initialisation	REL-4	A	TEI4	4.0.0	4.1.0
9	25.214	180	2	R1-01-0666	Clarification of synchronisation procedures	R99	F	TEI	3.6.0	3.7.0
10	25.214	181	2	R1-01-0666	Clarification of synchronisation procedures	REL-4	Α	TEI4	4.0.0	4.1.0
11	25.214	182	-	R1-01-0517	Clarification of initialisation of closed loop mode 1 and 2 during compressed mode	R99	F	TEI	3.6.0	3.7.0
12	25.214	183	-	R1-01-0517	Clarification of initialisation of closed loop mode 1 and 2 during compressed mode	REL-4	A	TEI4	4.0.0	4.1.0
13	25.214	185	-	R1-01-0658	DL maximum power level in compressed mode	R99	F	TEI	3.6.0	4.0.0
14	25.214	186	-	R1-01-0658	DL maximum power level in compressed mode	REL-4	Α	TEI4	4.0.0	4.1.0

## 3GPP TSG RAN Meeting #12 Stockholm, Sweden, 12-15, June, 2001

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Proposed change affects: # (U)SIM ME/UE Radio Access Network X Core Network															
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- 1) Fill out the above form. The symbols above marked **#** contain pop-up help information about the field that they are closest to.
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# R1-01-0554

# 5.2 Downlink power control

The transmit power of the downlink channels is determined by the network. In general the ratio of the transmit power between different downlink channels is not specified and may change with time. However, regulations exist as described in the following subclauses.

Higher layer power settings shall be interpreted as setting of the total power, i.e. the sum of the power from the two antennas in case of transmit diversity.

# 5.2.1 DPCCH/DPDCH

### 5.2.1.1 General

The downlink transmit power control procedure controls simultaneously the power of a DPCCH and its corresponding DPDCHs. The power control loop adjusts the power of the DPCCH and DPDCHs with the same amount, i.e. the relative power difference between the DPCCH and DPDCHs is not changed.

The relative transmit power offset between DPCCH fields and DPDCHs is determined by the network The TFCI, TPC and pilot fields of the DPCCH are offset relative to the DPDCHs power by PO1, PO2 and PO3 dB respectively. The power offsets may vary in time. The method for controlling the power offsets within UTRAN is specified in [6]

The power of CCC field in DL DPCCH for CPCH is the same as the power of the pilot field.

### 5.2.1.2 Ordinary transmit power control

#### 5.2.1.2.1 UE behaviour

The UE shall generate TPC commands to control the network transmit power and send them in the TPC field of the uplink DPCCH. An example on how to derive the TPC commands in given in Annex B.2.

The UE shall check the downlink power control mode (DPC\_MODE) before generating the TPC command:

- if DPC\_MODE = 0 : the UE sends a unique TPC command in each slot and the TPC command generated is transmitted in the first available TPC field in the uplink DPCCH;
- if DPC\_MODE = 1 : the UE repeats the same TPC command over 3 slots and the new TPC command is transmitted such that there is a new command at the beginning of the frame.

The DPC\_MODE parameter is a UE specific parameter controlled by the UTRAN.

The UE shall not make any assumptions on how the downlink power is set by UTRAN, in order to not prohibit usage of other UTRAN power control algorithms than what is defined in subclause 5.2.1.2.2.

#### 5.2.1.2.2 UTRAN behaviour

Upon receiving the TPC commands UTRAN shall adjust its downlink DPCCH/DPDCH power accordingly. For  $DPC\_MODE = 0$ , UTRAN shall estimate the transmitted TPC command  $TPC_{est}$  to be 0 or 1, and shall update the power every slot. If  $DPC\_MODE = 1$ , UTRAN shall estimate the transmitted TPC command  $TPC_{est}$  over three slots to be 0 or 1, and shall update the power every three slots.

After estimating the *k*:th TPC command, UTRAN shall adjust the current downlink power P(k-1) [dB] to a new power P(k) [dB] according to the following formula:

$$P(k) = P(k - 1) + P_{TPC}(k) + P_{bal}(k),$$

where  $P_{TPC}(k)$  is the *k*:th power adjustment due to the inner loop power control, and  $P_{bal}(k)$  [dB] is a correction according to the downlink power control procedure for balancing radio link powers towards a common reference power. The power balancing procedure and control of the procedure is described in [6].

 $P_{TPC}(k)$  is calculated according to the following.

If the value of Limited Power RaiseIncrease Used parameter is 'Not used', then

$$P_{\text{TPC}}(k) = \begin{cases} +\Delta_{\text{TPC}} & \text{if } \text{TPC}_{\text{est}}(k) = 1\\ -\Delta_{\text{TPC}} & \text{if } \text{TPC}_{\text{est}}(k) = 0 \end{cases}, \text{ [dB].} \quad (1)$$

If the value of *Limited Power RaiseIncrease Used* parameter is 'Used', then the *k*:th inner loop power adjustment shall be calculated as:

$$P_{TPC}(k) = \begin{cases} +\Delta_{TPC} & \text{if } \text{TPC}_{\text{est}}(k) = 1 \text{ and } \Delta_{sum}(k) + \Delta_{TPC} < \text{Power_Raise_Limit} \\ 0 & \text{if } \text{TPC}_{\text{est}}(k) = 1 \text{ and } \Delta_{sum}(k) + \Delta_{TPC} \ge \text{Power_Raise_Limit} , \text{[dB]} \quad (2) \\ -\Delta_{TPC} & \text{if } \text{TPC}_{\text{est}}(k) = 0 \end{cases}$$

where

$$\Delta_{sum}(k) = \sum_{i=k-\text{DL}_{Power}_{Averaging}_{Vindow}_{Size}}^{k-1} P_{TPC}(i)$$

is the temporary sum of the last DL\_Power\_Averaging\_Window\_Size inner loop power adjustments (in dB).

For the first (*DL\_Power\_Averaging\_Window\_Size* – 1) adjustments after the activation of the limited power raiseincrease method, formula (1) shall be used instead of formula (2). *Power\_Raise\_Limit* and *DL\_Power\_Averaging\_Window\_Size* are parameters configured in the UTRAN.

The power control step size  $\Delta_{TPC}$  can take four values: 0.5, 1, 1.5 or 2 dB. It is mandatory for UTRAN to support  $\Delta_{TPC}$  of 1 dB, while support of other step sizes is optional.

In addition to the above described formulas on how the downlink power is updated, the restrictions below apply.

In case of congestion (commanded power not available), UTRAN may disregard the TPC commands from the UE.

The average power of transmitted DPDCH symbols over one timeslot shall not exceed Maximum\_DL\_Power (dB), nor shall it be below Minimum\_DL\_Power (dB). Transmitted DPDCH symbol means here a complex QPSK symbol before spreading which does not contain DTX. Maximum\_DL\_Power (dB) and Minimum\_DL\_Power (dB) are power limits for one channelisation code, relative to the primary CPICH power [6].

### 3GPP TSG RAN Meeting #12 Stockholm, Sweden, 12-15, June, 2001

#### CR-Form-v4 CHANGE REQUEST Current version: 4.0.0 Ħ 25.214 CR 166 ₩ rev ж ж 1 For **HELP** on using this form, see bottom of this page or look at the pop-up text over the **#** symbols. Proposed change affects: # (U)SIM ME/UE Radio Access Network X Core Network Title: æ Limited power raise: aligning of terminology with TS25.433 Source: TSG RAN WG1 æ Date: # 15.05.2001 Work item code: 第 TEI4 Category: Ж Α Release: # REL-4 Use one of the following categories: Use one of the following releases: (GSM Phase 2) F (correction) 2 A (corresponds to a correction in an earlier release) R96 (Release 1996) B (addition of feature), R97 (Release 1997) **C** (functional modification of feature) R98 (Release 1998) **D** (editorial modification) R99 (Release 1999) Detailed explanations of the above categories can (Release 4) REL-4 be found in 3GPP TR 21.900. REL-5 (Release 5) RAN WG3 uses a term "limited power increase" in TS25.433. As this parameter Reason for change: **X** was originally added to TS25.214 to be in line with TS25.433 the name should be aligned. Summary of change: # "Limited power raise" is changed into "Limited power increase" throughtout TS25.214 Consequences if ж not approved: Clauses affected: Ж 5.2.1.2.2 Other specs ж Other core specifications ж affected: Test specifications **O&M** Specifications Other comments: ж

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28

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where

$$\Delta_{sum}(k) = \sum_{i=k-\text{DL}_{vower}_{vower}_{vower}_{vower}_{vower}_{vower}(i)} P_{TPC}(i)$$

is the temporary sum of the last DL\_Power\_Averaging\_Window\_Size inner loop power adjustments (in dB).

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CHANGE REQUEST											
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For <u>HELP</u> on using this form, see bottom of this page or look at the pop-up text over the <b>#</b> symbols.											
Proposed change affects: # (U)SIM ME/UE X Radio Access Network X Core Network											
Title: Ж	Correc	tion of IPD	L burst para	ameters							
Source: ೫	TSG F	AN WG1									
Work item code: Ж	LCS1-L	IEpos					Date: ೫	15. N	May 200 <sup>-</sup>	1	
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Summary of chang	<b>je:</b> # <mark>Co</mark>	rrection in t	he definitio	n of the II	DL bu	rst mo	ode parame	ters.			
Consequences if not approved:	ж Wı	ong calcula	ation of star	ting point	s of IPE	DL bur	sts.				
Clauses affected:	ж <mark>8</mark>	2; 8.3									
Other specs Affected:	¥	Other core Test speci O&M Spec	e specificati ifications cifications	ons a	f						
Other comments:	ж										

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# 8.2 Parameters of IPDL

The following parameters are signalled to the UE via higher layers:

IP_Status:	This is a logic value that indicates if the idle periods are arranged in continuous or burst mode.
IP_Spacing:	The number of 10 ms radio frames between the start of a radio frame that contains an idle period and the next radio frame that contains an idle period. Note that there is at most one idle period in a radio frame.
IP_Length:	The length of the idle periods, expressed in symbols of the CPICH.
IP_Offset:	A cell specific offset that can be used to synchronise idle periods from different sectors within a Node B.
Seed:	Seed for the pseudo random number generator.
Additionally in the case of	burst mode operation the following parameters are also communicated to the UE.
Burst_Start:	<u>Specifies the start of the first burst of idle periods. 256×Burst_Start is</u> <u>T</u> the SFN where the first burst of idle periods starts.
Burst_Length:	The number of idle periods in a burst of idle periods.
Burst_Freq:	Specifies the time between the start of a burst and the start of the next burst. 256×Burst_Freq is <u>T</u> the number of radio frames of the primary CPICH between the start of a burst and the start of the next burst.

# 8.3 Calculation of idle period position

In burst mode, the first burst starts in the radio frame with SFN =  $256 \times Burst\_Start$ . The *n*:th burst starts in the radio frame with SFN =  $256 \times Burst\_Start + n \times 256 \times Burst\_Freq$ . The sequence of bursts according to this formula continues up to and including the radio frame with SFN = 4095. At the start of the radio frame with SFN = 0, the burst sequence is terminated (no idle periods are generated) and at SFN =  $256 \times Burst\_Start$  the burst sequence is restarted with the first burst followed by the second burst etc., as described above.

Continuous mode is equivalent to burst mode, with only one burst spanning the whole SFN cycle of 4096 radio frames, this burst starting in the radio frame with SFN = 0.

Assume that IP\_Position(x) is the position of idle period number x within a burst, where x = 1, 2, ..., and IP\_Position(x) is measured in number of CPICH symbols from the start of the first radio frame of the burst.

The positions of the idle periods within each burst are then given by the following equation:

 $IP_Position(x) = (x \times IP_Spacing \times 150) + (rand(x \mod 64) \mod (150 - IP_Length)) + IP_Offset;$ 

where rand(n) is a pseudo random generator defined as follows:

rand(0) = Seed;

 $rand(n) = (106 \times rand(n-1) + 1283) modulo 6075, n = 1, 2, 3, ....$ 

Note that *x* is reset to x = 1 for the first idle period in every burst.

Figure 6 below illustrates the idle periods for the burst mode case.



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	CHANGE REQUEST
X	25.214 CR 168 <sup># rev</sup> 1 <sup># Current version: 3.6.0 <sup>#</sup></sup>
For <u>HELP</u> on u	using this form, see bottom of this page or look at the pop-up text over the X symbols.
Proposed change	affects: # (U)SIM ME/UE X Radio Access Network X Core Network
Title: ೫	Correction of synchronisation primitives
Source: #	TSG RAN WG1
Work item code: भ	CTEI Date: # 2001-05-23
Category: ₩	<b>FRelease:</b> %R99Use one of the following categories:Use one of the following releases: <b>F</b> (correction)2 <b>A</b> (corresponds to a correction in an earlier release)R96 <b>B</b> (addition of feature),R97 <b>C</b> (functional modification of feature)R98 <b>D</b> (editorial modification)R99 <b>D</b> (tealignment of the above categories canREL-4 <b>b</b> found in 3GPP TR 21.900.REL-5
Boocon for obong	Poth in sums and out of sums can be reported simultaneously. Handling of zero
Reason for change	length CRC in the sync primitives is ambiguous. The different transport format detection cases when TFCI is absent need clarification; the current description puts too much restrictions on the use of BTFD.
Summary of chang	<b>ge: #</b> Synchronisation primitives are corrected to allow either in-sync or out-of-sync to be reported at the same time. Clarification about zero-length CRC is added. Handling of different transport format detection cases in absence of TFCI is clarified.
Consequences if not approved:	# Ambiguity for reporting synchronisation primitives in numerous cases and too much restrictions are put on the use of BTFD.
Clauses affected:	¥ 4.3.1.2
Other specs affected:	%       Other core specifications       %         Test specifications       O&M Specifications
Other comments:	The CR has been produced based on the proposals in R1-01-0468, R1-01-0498 and R1-01-0505.

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3) With "track changes" disabled, paste the entire CR form (use CTRL-A to select it) into the specification just in front of the clause containing the first piece of changed text. Delete those parts of the specification which are not relevant to the change request.

# 4.3 DPCCH/DPDCH synchronisation

## 4.3.1 Synchronisation primitives

#### 4.3.1.1 General

For the dedicated channels, synchronisation primitives are used to indicate the synchronisation status of radio links, both in uplink and downlink. The definition of the primitives is given in the following subclauses.

### 4.3.1.2 Downlink synchronisation primitives

Layer 1 in the UE shall every radio frame check synchronisation status of the downlink dedicated channels. Synchronisation status is indicated to higher layers using the CPHY-Sync-IND and CPHY-Out-of-Sync-IND primitives.

The criteria for reporting synchronisation status are defined in two different phases.

The first phase starts when higher layers initiate physical dedicated channel establishment (as described in [5]) and lasts until 160 ms after the downlink dedicated channel is considered established by higher layers (physical channel establishment is defined in [5]). During this time out-of-sync shall not be reported and in-sync shall be reported using the CPHY-Sync-IND primitive if the following criterion is fulfilled:

- The UE estimates the DPCCH quality over the previous 40 ms period to be better than a threshold Q<sub>in</sub>. This criterion shall be assumed not to be fulfilled before 40 ms of DPCCH quality measurements have been collected. Q<sub>in</sub> is defined implicitly by the relevant tests in [7].

The second phase starts 160 ms after the downlink dedicated channel is considered established by higher layers. During this phase both out-of-sync and in-sync are reported as follows.

Out-of-sync shall be reported using the CPHY-Out-of-Sync-IND primitive if <u>either any</u> of the following criteria <u>are is</u> fulfilled:

- The UE estimates the DPCCH quality over the previous 160 ms period to be worse than a threshold Q<sub>out</sub>. Q<sub>out</sub> is defined implicitly by the relevant tests in [7].
- The 20 most recently received transport blocks with a <u>non-zero length</u> CRC attached, as observed on all TrCHs using <u>non-zero length</u> CRC, have been received with incorrect CRC. In addition, over the previous 160 ms, all transport blocks with a <u>non-zero length</u> CRC attached have been received with incorrect CRC. In case <del>of</del> no TFCI is used this criterion shall <u>not</u> be considered for the TrCH(s) not using guided detection if they do not use <u>aonly for TrCHs using non-zero length</u> CRC in all transport formats. If no transport blocks with a non-zero length CRC in all transport formats. If no transport blocks with a non-zero length CRC in all transport formats. If no transport blocks with a non-zero length CRC attached are received over the previous 160 ms this criterion shall not be fulfilled.

In-sync shall be reported using the CPHY-Sync-IND primitive if both of the following criteria are fulfilled:

- The UE estimates the DPCCH quality over the previous 160 ms period to be better than a threshold Q<sub>in</sub>. Q<sub>in</sub> is defined implicitly by the relevant tests in [7].
- At least one transport block with a <u>non-zero length</u> CRC attached, as observed on all TrCHs using <u>non-zero length</u> CRC, is received in a TTI ending in the current frame with correct CRC. If no transport blocks are received, or no transport block has a <u>non-zero length</u> CRC attached <u>in a TTI ending in the current frame and in addition over the previous 160 ms at least one transport block with a non-zero length CRC attached has been received with a correct CRC<sub>7</sub> this criterion shall be assumed to be fulfilled.-<u>If no transport blocks with a non-zero length CRC attached are received over the previous 160 ms this criterion shall also be assumed to be fulfilled. In case of-no TFCI is used this criterion shall <u>not</u> be considered for the TrCH(s) not using guided detection if they do not use <u>aonly for TrCHs using non-zero length</u> CRC in all transport formats.</u></u>

How the primitives are used by higher layers is described in [5]. The above definitions may lead to radio frames where neither the in-sync nor the out-of-sync primitives are reported.

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	CHANGE REQUEST											
ж	25.214 CR 169 <sup># rev</sup> 1 <sup>#</sup> Current version	<sup>on:</sup> <b>4.0.0</b> <sup>#</sup>										
For <u>HELP</u> on	ing this form, see bottom of this page or look at the pop-up text o	over the # symbols.										
Proposed change	ffects: # (U)SIM ME/UE X Radio Access Network	X Core Network										
Title:	Correction of synchronisation primitives											
Source:	TSG RAN WG1											
Work item code:	TEI4 Date: #	2001-05-23										
Category: 3	A       Release: %         Jse one of the following categories:       Use one of the following categories:         F (correction)       2         A (corresponds to a correction in an earlier release)       R96         B (addition of feature),       R97         C (functional modification of feature)       R98         D (editorial modification)       R99         Detailed explanations of the above categories can       REL-4         pe found in 3GPP TR 21.900.       REL-5	REL-4 he following releases: (GSM Phase 2) (Release 1996) (Release 1997) (Release 1998) (Release 1999) (Release 4) (Release 5)										
Reason for chang	Both in-sync and out-of-sync can be reported simultaneous length CRC in the sync primitives is ambiguous. The difference detection cases when TFCI is absent need clarification; the puts too much restrictions on the use of BTFD.	sly. Handling of zero- ent transport format e current description										
Summary of char	Synchronisation primitives are corrected to allow either in- be reported at the same time. Clarification about zero-leng Handling of different transport format detection cases in ab clarified.	sync or out-of-sync to th CRC is added. osence of TFCI is										
Consequences if not approved:	# Ambiguity for reporting synchronisation primitives in numer much restrictions are put on the use of BTFD.	rous cases and too										
Clauses affected:	<b>#</b> 4.3.1.2											
Other specs affected:	%Other core specifications%Test specifications0&M Specifications											
Other comments:	* The CR has been produced based on the proposals in R1- and R1-01-0505.	-01-0468, R1-01-0498										

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- 1) Fill out the above form. The symbols above marked **#** contain pop-up help information about the field that they are closest to.
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# 4.3 DPCCH/DPDCH synchronisation

## 4.3.1 Synchronisation primitives

#### 4.3.1.1 General

For the dedicated channels, synchronisation primitives are used to indicate the synchronisation status of radio links, both in uplink and downlink. The definition of the primitives is given in the following subclauses.

### 4.3.1.2 Downlink synchronisation primitives

Layer 1 in the UE shall every radio frame check synchronisation status of the downlink dedicated channels. Synchronisation status is indicated to higher layers using the CPHY-Sync-IND and CPHY-Out-of-Sync-IND primitives.

The criteria for reporting synchronisation status are defined in two different phases.

The first phase starts when higher layers initiate physical dedicated channel establishment (as described in [5]) and lasts until 160 ms after the downlink dedicated channel is considered established by higher layers (physical channel establishment is defined in [5]). During this time out-of-sync shall not be reported and in-sync shall be reported using the CPHY-Sync-IND primitive if the following criterion is fulfilled:

- The UE estimates the DPCCH quality over the previous 40 ms period to be better than a threshold Q<sub>in</sub>. This criterion shall be assumed not to be fulfilled before 40 ms of DPCCH quality measurements have been collected. Q<sub>in</sub> is defined implicitly by the relevant tests in [7].

The second phase starts 160 ms after the downlink dedicated channel is considered established by higher layers. During this phase both out-of-sync and in-sync are reported as follows.

Out-of-sync shall be reported using the CPHY-Out-of-Sync-IND primitive if <u>either any</u> of the following criteria <u>are is</u> fulfilled:

- The UE estimates the DPCCH quality over the previous 160 ms period to be worse than a threshold Q<sub>out</sub>. Q<sub>out</sub> is defined implicitly by the relevant tests in [7].
- The 20 most recently received transport blocks with a <u>non-zero length</u> CRC attached, as observed on all TrCHs using <u>non-zero length</u> CRC, have been received with incorrect CRC. In addition, over the previous 160 ms, all transport blocks with a <u>non-zero length</u> CRC attached have been received with incorrect CRC. In case <del>of</del> no TFCI is used this criterion shall <u>not</u> be considered for the TrCH(s) not using guided detection if they do not use a <del>only for TrCHs using <u>non-zero length</u> CRC in all transport formats. If no transport blocks with a non-zero length CRC in all transport formats. If no transport blocks with a non-zero length CRC attached are received over the previous 160 ms this criterion shall not be assumed to be fulfilled.</del>

In-sync shall be reported using the CPHY-Sync-IND primitive if both of the following criteria are fulfilled:

- The UE estimates the DPCCH quality over the previous 160 ms period to be better than a threshold Q<sub>in</sub>. Q<sub>in</sub> is defined implicitly by the relevant tests in [7].
- At least one transport block with a <u>non-zero length</u> CRC attached, as observed on all TrCHs using <u>non-zero length</u> CRC, is received in a TTI ending in the current frame with correct CRC. If no transport blocks are received, or no transport block has a <u>non-zero length</u> CRC attached <u>in a TTI ending in the current frame and in</u> addition over the previous 160 ms at least one transport block with a non-zero length CRC attached has been received with a correct CRC, this criterion shall be assumed to be fulfilled. If no transport blocks with a non-zero length CRC attached are received over the previous 160 ms this criterion shall also be assumed to be fulfilled. In case of no TFCI is used this criterion shall <u>not</u> be considered for the TrCH(s) not using guided detection if they do not use aonly for TrCHs using <u>non-zero length</u> CRC in all transport formats.

How the primitives are used by higher layers is described in [5]. The above definitions may lead to radio frames where neither the in-sync nor the out-of-sync primitives are reported.

¥	<b>25.214</b> CR <b>176 #</b> rev <b>1 #</b> Current version: <b>3.6.0 #</b>
For <u>HELP</u> on u	using this form, see bottom of this page or look at the pop-up text over the $#$ symbols.
Proposed change	affects: # (U)SIM ME/UE Radio Access Network X Core Network
Title: ೫	Clarification on TPC command generation on downlink during RL initialisation
Source: #	TSG RAN WG1
Work item code: ೫	TEI Date: 米 05-03-2001
Category: ೫	F Release: ೫ R99
	Use one of the following categories:Use one of the following releases:F (correction)2A (corresponds to a correction in an earlier release)R96B (Addition of feature),R97C (Functional modification of feature)R98D (Editorial modification)R99D tetailed explanations of the above categories canREL-4be found in 3GPP TR 21.900.REL-5
Bosson for change	a: <sup>9</sup> The surrent description of TPC command generation is upclear "01" does not
Reason for change	correspond to an already defined command or TPC bit pattern for one slot. In case there are more than 2 TPC bits in the downlink DPCH slot it is not clear what TPC bits the node B should send. Further a "1" command is refered to, it should be clarified whether it refers to the actual TPC bits or to the transmitter power control command as defined in table 13 of 25.211 (section 5.3.2).
Summary of chang	<b>ge: #</b> It is clarified that the TPC pattern defined in 5.1.2.2.1.2 refers to the transmitter power control command and not to the TPC bits to be sent in the downlink DPCH.
Consequences if not approved:	# TPC command generation on downlink during radio link initialisation is ambiguous leading to potential different implementations by different vendors when the objective of this pattern was to harmonise the behaviours of node Bs during radio link initialisation.
Clauses affected:	¥ 5.1.2.2.1.2
Other specs affected:	%       Other core specifications       %         Test specifications       0&M Specifications
Other comments:	¥

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- 2) Obtain the latest version for the release of the specification to which the change is proposed. Use the MS Word "revision marks" feature (also known as "track changes") when making the changes. All 3GPP specifications can be downloaded from the 3GPP server under <u>ftp://www.3gpp.org/specs/</u> For the latest version, look for the directory name with the latest date e.g. 2000-09 contains the specifications resulting from the September 2000 TSG meetings.
- 3) With "track changes" disabled, paste the entire CR form (use CTRL-A to select it) into the specification just in front of the clause containing the first piece of changed text. Delete those parts of the specification which are not relevant to the change request.

#### 5.1.2.2.1.2 TPC command generation on downlink during RL initialisation

When commanded by higher layers the TPC commands sent on a downlink radio link from Node Bs that have not yet achieved uplink synchronisation shall follow a pattern as follows:

12

If higher layers indicate by "First RLS indicator" that the radio link is part of the first radio link set sent to the UE and the value 'n' obtained from the parameter "DL TPC pattern 01 count" passed by higher layers is different from 0 then :

- a value 'n' is obtained from the parameter "DL TPC pattern 01 count" passed by higher layers,

- the TPC pattern shall consist of n instances of <u>"01"</u> the pair of TPC commands (<u>"0"</u>, <u>"1"</u>), <u>plus followed by</u> one instance of <u>TPC command</u> <u>"1"</u>, where (<u>"0"</u>, <u>"1"</u>) indicates the TPC commands to be transmitted in 2 consecutive <u>slots</u>,
- the TPC pattern continuously repeat but shall be forcibly re-started at the beginning of each frame where CFN mod 4 = 0.

else

- The TPC pattern shall consist <u>only of all TPC commands</u> "1".

The TPC pattern shall terminate once uplink synchronisation is achieved.

	CHANGE REQUEST
ж	<b>25.214</b> CR <b>177 #</b> rev <b>1 #</b> Current version: <b>4.0.0 #</b>
For <u>HELP</u> on u	sing this form, see bottom of this page or look at the pop-up text over the $#$ symbols.
Proposed change	affects: # (U)SIM ME/UE Radio Access Network X Core Network
Title: Ж	Clarification on TPC command generation on downlink during RL initialisation
Source: भ	TSG RAN WG1
Work item code: %	TEI4 Date: 육 05-03-2001
Category: ж	A Release: # REL-4
	Use one of the following categories:Use one of the following releases:F (correction)2A (corresponds to a correction in an earlier release)R96B (Addition of feature),R97C (Functional modification of feature)R98D (Editorial modification)R99D tetailed explanations of the above categories canREL-4be found in 3GPP TR 21.900.REL-5
Reason for change	: # The current description of TPC command generation is unclear "01" does not
	correspond to an already defined command or TPC bit pattern for one slot. In case there are more than 2 TPC bits in the downlink DPCH slot, it is not clear what TPC bits the node B should send. Further a "1" command is referred to, it should be clarified whether it refers to the actual TPC bits or to the transmitter power control command as defined in table 13 of 25.211 (section 5.3.2).
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Consequences if not approved:	# TPC command generation on downlink during radio link initialisation is ambiguous leading to potential different implementations by different vendors when the objective of this pattern was to harmonise the behaviours of node Bs during radio link initialisation.
Clauses affected:	¥ 5.1.2.2.1.2
Other specs affected:	%Other core specifications%Test specifications0&M Specifications
Other comments:	¥

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- a value 'n' is obtained from the parameter "DL TPC pattern 01 count" passed by higher layers,

- the TPC pattern shall consist of n instances of <u>"01"</u> the pair of TPC commands (<u>"0"</u>, <u>"1"</u>), <u>plus followed by</u> one instance of <u>TPC command</u> <u>"1"</u>, where (<u>"0"</u>, <u>"1"</u>) indicates the TPC commands to be transmitted in 2 consecutive <u>slots</u>,
- the TPC pattern continuously repeat but shall be forcibly re-started at the beginning of each frame where CFN mod 4 = 0.

else

- The TPC pattern shall consist <u>only of all TPC commands</u> "1".

The TPC pattern shall terminate once uplink synchronisation is achieved.

			CHAI	NGE R	EQ	JES <sup>-</sup>	Г			CR-Form-v4
æ	25	<mark>.214</mark>	CR 180	ж	rev	<b>2</b> <sup>#</sup>	Current	version:	3.6.0	ж
For <u>HELP</u> on u	ising	this for	rm, see bottom	of this pa	ge or l	ook at ti	he pop-up	text over	r the X syr	mbols.
Proposed change	affec	ts: ¥	(U)SIM	ME/UE	X	Radio A	Access Net	work X	Core Ne	etwork
Title: ដ	Cla	arificatio	<mark>on of synchror</mark>	nisation pro	ocedur	es				
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Reason for change	а. ¥	Sync	chronisation pr	ocoduros	as das	cribed i	n section 1	3 25 21	1 currently	1
Reason for change	<i>с.</i> Ф	cons spec exist term	ider only the e ified for the re- ing procedures s of synchronis	stablishm configurati s can be u sation.	ent and ion cas sed ar	d radio l ses. The id how t	ink addition CR clarifie he UE and	a cases a es in whi UTRAN	and nothin ch case th I should be	g is ie ehave in
<ul> <li>Summary of change: #</li> <li>The synchronisation procedures "no existing radio link" (section 4.3.2.2) or several existing radio links" (section 4.3.2.3) are renamed "synchronisation procedures" and "uplink synchronisation procedure".</li> <li>the "synchronisation procedure A" applies when the first radio link is and when one or several existing radio links are reconfigured on a di frequency and on another cell when the timing cannot be maintained applies in some cases of intra-cell reconfiguration which are listed be change in the P-CPICH or S-CPICH usage for channel estition are listed on previous radio link is kept unchanged. It also applies in case radio link is moved to another cell in the same node B.</li> <li>The rest of the text is clarified and aligned with RRC specifications.</li> <li>Merge with CR25.214-174 (R1-01-0498) for the changes contained in section.</li> </ul>									and "one ation setup ifferent d. It also elow : imation ed and at se the	
not approved:	<i>е</i> њ	Sync When clear y UTRA	the phase ref whether the U	concernec erence is o E will stop ect from th	transn e UE	radio lin ed e.g. f	rom P-CPI	uration c CH to S- hat kind	CPICH, it	is not our the
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# 4.3 DPCCH/DPDCH synchronisation

## 4.3.1 Synchronisation primitives

#### 4.3.1.1 General

For the dedicated channels, synchronisation primitives are used to indicate the synchronisation status of radio links, both in uplink and downlink. The definition of the primitives is given in the following subclauses.

#### 4.3.1.2 Downlink synchronisation primitives

Layer 1 in the UE shall every radio frame check synchronisation status of the downlink dedicated channels. Synchronisation status is indicated to higher layers using the CPHY-Sync-IND and CPHY-Out-of-Sync-IND primitives.

The criteria for reporting synchronisation status are defined in two different phases.

The first phase lasts until 160 ms after the downlink dedicated channel is considered established by higher layers (physical channel establishment is defined in [5]). During this time out-of-sync shall not be reported and in-sync shall be reported using the CPHY-Sync-IND primitive if the following criterion is fulfilled:

- The UE estimates the DPCCH quality over the previous 40 ms period to be better than a threshold Q<sub>in</sub>. This criterion shall be assumed not to be fulfilled before 40 ms of DPCCH quality measurements have been collected. Q<sub>in</sub> is defined implicitly by the relevant tests in [7].

The second phase starts 160 ms after the downlink dedicated channel is considered established by higher layers. During this phase both out-of-sync and in-sync are reported as follows.

Out-of-sync shall be reported using the CPHY-Out-of-Sync-IND primitive if either of the following criteria are fulfilled:

- The UE estimates the DPCCH quality over the previous 160 ms period to be worse than a threshold Q<sub>out</sub>. Q<sub>out</sub> is defined implicitly by the relevant tests in [7].
- The 20 most recently received transport blocks with a CRC attached, as observed on all TrCHs using CRC, have been received with incorrect CRC. In addition, over the previous 160 ms, all transport blocks with a CRC attached have been received with incorrect CRC.

In-sync shall be reported using the CPHY-Sync-IND primitive if both of the following criteria are fulfilled:

- The UE estimates the DPCCH quality over the previous 160 ms period to be better than a threshold  $Q_{in}$ .  $Q_{in}$  is defined implicitly by the relevant tests in [7].
- At least one transport block with a CRC attached, as observed on all TrCHs using CRC, is received in a TTI ending in the current frame with correct CRC. If no transport blocks are received, or no transport block has a CRC attached, this criterion shall be assumed to be fulfilled.

How the primitives are used by higher layers is described in [5]. The above definitions may lead to radio frames where neither the in-sync nor the out-of-sync primitives are reported.

#### 4.3.1.3 Uplink synchronisation primitives

Layer 1 in the Node B shall every radio frame check synchronisation status of all radio link sets. Synchronisation status is indicated to the RL Failure/Restored triggering function using either the CPHY-Sync-IND or CPHY-Outof-Sync-IND primitive. Hence, only one synchronisation status indication shall be given per radio link set.

The exact criteria for indicating in-sync/out-of-sync is not subject to specification, but could e.g. be based on received DPCCH quality or CRC checks. One example would be to have the same criteria as for the downlink synchronisation status primitives.

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# 4.3.2 Radio link establishment and reconfiguration

#### 4.3.2.1 General

The establishment of a radio link can be divided into two cases Two synchronisation procedures are defined in order to obtain radio link synchronisation between UE and UTRAN:

<u>- Synchronisation procedure A: it shall be used -when there is no existing the first radio link(s) is established</u> and there is no existing radio link for the UE i.e. when at least one downlink dedicated physical channel and one uplink dedicated physical channel are to be set up on a frequency. This procedure shall also be used when synchronised reconfiguration (i.e. when activation times are given) is applied to one or several existing radio links and any of the following conditions are true as a result of the reconfiguration procedure.:

- the frequency of the dedicated physical channels is changed and the timing is re-initialised as defined in [5] or;

- the primary or secondary CPICH usage for channel estimation in the UE is changed or;

- the radio link(s) is moved to another cell on the same frequency and the timing is re-initialised as defined in [5];

or Synchronisation procedure B : it shall be used\_when one or several radio links <u>already exist\_are added to the active set and downlink transmission starts for those radio links</u>, i.e. when there is an existing DPCCH/DPDCH in the uplink, and at least one corresponding dedicated physical channel shall be set up in the downlink.at least one downlink dedicated physical channel is to be set up and an uplink dedicated physical channel already exists. This procedure shall also be used when synchronised radio link reconfiguration (i.e. when activation times are given) is applied to one or several existing radio links and the radio link(s) is moved to another cell on the same frequency and the timing is maintained.

All other synchronised radio link reconfigurations, i.e. when activation times are given, do not require any synchronisation procedures in UE or UTRAN:

Unsynchronised radio link reconfigurations, i.e. when no activation times are given, should not to require any specific synchronisation procedures in UE or UTRAN.

The two cases synchronisation procedures are described in subclauses 4.3.2.2-3 and 4.3.2.3-4 respectively.

#### 4.3.2.2 Node B radio link set state machine

In Node B, each radio link set can be in three different states: initial state, out-of-sync state and in-sync state. Transitions between the different states is shown in figure 1 below. The state of the Node B at the start of radio link establishment is described in the following subclauses. Transitions between initial state and in-sync state are described in subclauses 4.3.2.2 and 4.3.2.3 and transitions between the in-sync and out-of-sync states are described in subclause 4.3.3.2.



#### Figure 1: Node B radio link set states and transitions

# 4.3.2.2<u>3</u> No existing radio Synchronisation procedure Alink

When one or several radio links are to be established and there is no existing radio link for the UE already, a dedicated physical channel is to be set up in uplink and at least one dedicated physical channel is to be set up in downlink. This corresponds to the case when a dedicated physical channel is initially set up on a frequency.

The synchronisation establishment procedure, which begins at the time indicated by higher layers (either immediately at receipt of upper layer signalling, or at an indicated activation time), radio link establishment is as follows:

- a) a) Each NNode B involved in the procedure considerssets the all itsthe radio link sets which are to be setup for this UE which are to be set up to be in the initial state.
- b) -UTRAN shall start the transmission of the downlink DPCCH. and may start the transmission of DPDCH if any data is to be transmitted. If an activation time has been given downlink transmission shall not start before the activation time has been reached. The initial downlink DPCCH transmit power is set by higher layers [6] except in case of radio link reconfiguration. Downlink TPC commands are generated as described in 5.1.2.2.1.2.
- c) The UE establishes downlink chip and frame synchronisation of DPCCH, using the P-CCPCH timing and timing offset information notified from UTRAN. Frame synchronisation can be confirmed using the frame synchronisation word. Downlink synchronisation status is reported to higher layers every radio frame according to subclause 4.3.1.2.
- The UE shall not transmit on uplink until higher layers consider the downlink physical channel established. If d)<del>c)</del> no activation time for uplink DPCCH has been signalled to the UE, uplink DPCCH transmission shall start when higher layers consider the downlink physical channel established. If an activation time has been given, uplink DPCCH transmission shall not start before the downlink physical channel has been established and the activation time has been reached. Physical channel establishment and activation time are defined in [5]. The initial uplink DPCCH transmit power is set by higher layers [5]. In case of radio link reconfiguration the uplink DPCCH power is kept unchanged between before and after the reconfiguration except for inner loop power control adjustments.- The total signalling response delay for the establishment of a new DPCH shall not exceed the requirements given in [8] sub-clause 7.3. A power control preamble shall be applied as indicated by higher layers. The uplink DPDCH transmission shall not start before the end of the power control preamble. The length of the power control preamble is N<sub>pcp</sub> radio frames beginning at the start of uplink DPCCH transmission, where  $N_{pcp}$  is a higher layer parameter set by UTRAN [5]. Note that the transmission start delay between DPCCH and DPDCH may be cancelled using a power control preamble of 0 length. The starting time for transmission of DPDCHs shall also satisfy the constraints on adding transport channels to a CCTrCH, as defined in [2] subclause 4.2.14.
- e) d)-UTRAN establishes uplink chip and frame synchronisation. Frame synchronisation can be confirmed using the frame synchronisation word. Radio link sets remain in the initial state until N\_INSYNC\_IND successive insync indications are received from layer 1, when Node B shall trigger the RL Restore procedure indicating which radio link set has obtained synchronisation. When RL Restore has been triggered the radio link set shall be considered to be in the in-sync state. The parameter value of N\_INSYNC\_IND is configurable, see [6]. The RL Restore procedure may be triggered several times, indicating when synchronisation is obtained for different radio link sets.

Note: The total signalling response delay for the establishment of a new DPCH shall not exceed the requirements given in [8] sub-clause 7.3.

# 4.3.2.34 Synchronisation procedure BOne or several existing radio links

When one or several radio links are to be established and one or several radio links already exist, there is an existing DPCCH/DPDCH in the uplink, and at least one corresponding dedicated physical channel shall be set up in the downlink. This corresponds to the case when new radio links are added to the active set and downlink transmission starts for those radio links.

The synchronisation procedure B, which begins at the time indicated by higher layers (either immediately at receipt of upper layer signalling, or at an indicated activation time)radio link establishment is as follows:

- <u>a)</u> <u>a)</u>-<u>The following applies to aeach Node B involved in the procedure:</u>
  - -\_\_\_<u>Node B considers nN</u>ew radio link sets to be are set up to be in initial state.

- <u>If a one or several radio links is to beare</u> added to an existing radio link set, this radio link set shall be considered to be in the state the radio link set was prior to the addition of the radio link, i.e. if the radio link set was in the in-sync state before the addition of the radio link it shall remain in that state.
- b) UTRAN starts the transmission of the downlink DPCCH/DPDCH for each new radio link at a frame timing such that the frame timing received at the UE will be within  $T_0 \pm 148$  chips prior to the frame timing of the uplink DPCCH/DPDCH at the UE. Simultaneously, UTRAN establishes uplink chip and frame synchronisation of the each new radio link. Frame synchronisation can be confirmed using the frame synchronization word. Radio link sets considered to be in the initial state shall remain in the initial state until N\_INSYNC\_IND successive in-sync indications are received from layer 1, when Node B shall trigger the RL Restore procedure indicating which radio link set has obtained synchronisation. When RL Restore is triggered the radio link set shall be considered to be in the in-sync state. The parameter value of N\_INSYNC\_IND is configurable, see [6]. The RL Restore procedure may be triggered several times, indicating when synchronisation is obtained for different radio link sets.
- c) The UE establishes chip and frame synchronisation of the each new radio link. Layer 1 in the UE keeps reporting downlink synchronisation status to higher layers every radio frame according to the second phase of subclause 4.3.1.2. Frame synchronisation can be confirmed using the frame synchronization word. Downlink synchronisation status shall be reported to higher layers every radio frame according to subclause 4.3.1.2.

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- 1) Fill out the above form. The symbols above marked **#** contain pop-up help information about the field that they are closest to.
- 2) Obtain the latest version for the release of the specification to which the change is proposed. Use the MS Word "revision marks" feature (also known as "track changes") when making the changes. All 3GPP specifications can be downloaded from the 3GPP server under <u>ftp://ftp.3gpp.org/specs/</u> For the latest version, look for the directory name with the latest date e.g. 2001-03 contains the specifications resulting from the March 2001 TSG meetings.
- 3) With "track changes" disabled, paste the entire CR form (use CTRL-A to select it) into the specification just in front of the clause containing the first piece of changed text. Delete those parts of the specification which are not relevant to the change request.

# 4.3 DPCCH/DPDCH synchronisation

## 4.3.1 Synchronisation primitives

#### 4.3.1.1 General

For the dedicated channels, synchronisation primitives are used to indicate the synchronisation status of radio links, both in uplink and downlink. The definition of the primitives is given in the following subclauses.

#### 4.3.1.2 Downlink synchronisation primitives

Layer 1 in the UE shall every radio frame check synchronisation status of the downlink dedicated channels. Synchronisation status is indicated to higher layers using the CPHY-Sync-IND and CPHY-Out-of-Sync-IND primitives.

The criteria for reporting synchronisation status are defined in two different phases.

The first phase lasts until 160 ms after the downlink dedicated channel is considered established by higher layers (physical channel establishment is defined in [5]). During this time out-of-sync shall not be reported and in-sync shall be reported using the CPHY-Sync-IND primitive if the following criterion is fulfilled:

- The UE estimates the DPCCH quality over the previous 40 ms period to be better than a threshold Q<sub>in</sub>. This criterion shall be assumed not to be fulfilled before 40 ms of DPCCH quality measurements have been collected. Q<sub>in</sub> is defined implicitly by the relevant tests in [7].

The second phase starts 160 ms after the downlink dedicated channel is considered established by higher layers. During this phase both out-of-sync and in-sync are reported as follows.

Out-of-sync shall be reported using the CPHY-Out-of-Sync-IND primitive if either of the following criteria are fulfilled:

- The UE estimates the DPCCH quality over the previous 160 ms period to be worse than a threshold Q<sub>out</sub>. Q<sub>out</sub> is defined implicitly by the relevant tests in [7].
- The 20 most recently received transport blocks with a CRC attached, as observed on all TrCHs using CRC, have been received with incorrect CRC. In addition, over the previous 160 ms, all transport blocks with a CRC attached have been received with incorrect CRC.

In-sync shall be reported using the CPHY-Sync-IND primitive if both of the following criteria are fulfilled:

- The UE estimates the DPCCH quality over the previous 160 ms period to be better than a threshold  $Q_{in}$ .  $Q_{in}$  is defined implicitly by the relevant tests in [7].
- At least one transport block with a CRC attached, as observed on all TrCHs using CRC, is received in a TTI ending in the current frame with correct CRC. If no transport blocks are received, or no transport block has a CRC attached, this criterion shall be assumed to be fulfilled.

How the primitives are used by higher layers is described in [5]. The above definitions may lead to radio frames where neither the in-sync nor the out-of-sync primitives are reported.

#### 4.3.1.3 Uplink synchronisation primitives

Layer 1 in the Node B shall every radio frame check synchronisation status of all radio link sets. Synchronisation status is indicated to the RL Failure/Restored triggering function using either the CPHY-Sync-IND or CPHY-Outof-Sync-IND primitive. Hence, only one synchronisation status indication shall be given per radio link set.

The exact criteria for indicating in-sync/out-of-sync is not subject to specification, but could e.g. be based on received DPCCH quality or CRC checks. One example would be to have the same criteria as for the downlink synchronisation status primitives.

4

# 4.3.2 Radio link establishment and reconfiguration

#### 4.3.2.1 General

The establishment of a radio link can be divided into two cases Two synchronisation procedures are defined in order to obtain radio link synchronisation between UE and UTRAN:

- Synchronisation procedure A: it shall be used -when there is no existing the first radio link(s) is established and there is no existing radio link for the UE i.e. when at least one downlink dedicated physical channel and one uplink dedicated physical channel are to be set up on a frequency. This procedure shall also be used when synchronised reconfiguration (i.e. when activation times are given) is applied to one or several existing radio links and any of the following conditions are true as a result of the reconfiguration procedure.:

- the frequency of the dedicated physical channels is changed and the timing is re-initialised as defined in [5] or;

- the primary or secondary CPICH usage for channel estimation in the UE is changed or;

- the radio link(s) is moved to another cell on the same frequency and the timing is re-initialised as defined in [5];

or Synchronisation procedure B : it shall be used\_when one or several radio links <u>already exist\_are added to the active set and downlink transmission starts for those radio links</u>, i.e. when there is an existing DPCCH/DPDCH in the uplink, and at least one corresponding dedicated physical channel shall be set up in the downlink.at least one downlink dedicated physical channel is to be set up and an uplink dedicated physical channel already exists. This procedure shall also be used when synchronised radio link reconfiguration (i.e. when activation times are given) is applied to one or several existing radio links and the radio link(s) is moved to another cell on the same frequency and the timing is maintained.

All other synchronised radio link reconfigurations, i.e. when activation times are given, do not require any synchronisation procedures in UE or UTRAN:

Unsynchronised radio link reconfigurations, i.e. when no activation times are given, should not to require any specific synchronisation procedures in UE or UTRAN.

The two cases synchronisation procedures are described in subclauses 4.3.2.2-3 and 4.3.2.3-4 respectively.

#### 4.3.2.2 Node B radio link set state machine

In Node B, each radio link set can be in three different states: initial state, out-of-sync state and in-sync state. Transitions between the different states is shown in figure 1 below. The state of the Node B at the start of radio link establishment is described in the following subclauses. Transitions between initial state and in-sync state are described in subclauses 4.3.2.2 and 4.3.2.3 and transitions between the in-sync and out-of-sync states are described in subclause 4.3.3.2.



#### Figure 1: Node B radio link set states and transitions

# 4.3.2.2<u>3</u> No existing radio Synchronisation procedure Alink

When one or several radio links are to be established and there is no existing radio link for the UE already, a dedicated physical channel is to be set up in uplink and at least one dedicated physical channel is to be set up in downlink. This corresponds to the case when a dedicated physical channel is initially set up on a frequency.

The synchronisation establishment procedure, which begins at the time indicated by higher layers (either immediately at receipt of upper layer signalling, or at an indicated activation time), radio link establishment is as follows:

- a) a) Each NNode B involved in the procedure considerssets the all itsthe radio link sets which are to be setup for this UE which are to be set up to be in the initial state.
- b) -UTRAN shall start the transmission of the downlink DPCCH. and may start the transmission of DPDCH if any data is to be transmitted. If an activation time has been given downlink transmission shall not start before the activation time has been reached. The initial downlink DPCCH transmit power is set by higher layers [6] except in case of radio link reconfiguration. Downlink TPC commands are generated as described in 5.1.2.2.1.2.
- c) The UE establishes downlink chip and frame synchronisation of DPCCH, using the P-CCPCH timing and timing offset information notified from UTRAN. Frame synchronisation can be confirmed using the frame synchronisation word. Downlink synchronisation status is reported to higher layers every radio frame according to subclause 4.3.1.2.
- The UE shall not transmit on uplink until higher layers consider the downlink physical channel established. If d)<del>c)</del> no activation time for uplink DPCCH has been signalled to the UE, uplink DPCCH transmission shall start when higher layers consider the downlink physical channel established. If an activation time has been given, uplink DPCCH transmission shall not start before the downlink physical channel has been established and the activation time has been reached. Physical channel establishment and activation time are defined in [5]. The initial uplink DPCCH transmit power is set by higher layers [5]. In case of radio link reconfiguration the uplink DPCCH power is kept unchanged between before and after the reconfiguration except for inner loop power control adjustments.- The total signalling response delay for the establishment of a new DPCH shall not exceed the requirements given in [8] sub-clause 7.3. A power control preamble shall be applied as indicated by higher layers. The uplink DPDCH transmission shall not start before the end of the power control preamble. The length of the power control preamble is N<sub>pcp</sub> radio frames beginning at the start of uplink DPCCH transmission, where  $N_{pcp}$  is a higher layer parameter set by UTRAN [5]. Note that the transmission start delay between DPCCH and DPDCH may be cancelled using a power control preamble of 0 length. The starting time for transmission of DPDCHs shall also satisfy the constraints on adding transport channels to a CCTrCH, as defined in [2] subclause 4.2.14.
- e) d)-UTRAN establishes uplink chip and frame synchronisation. Frame synchronisation can be confirmed using the frame synchronisation word. Radio link sets remain in the initial state until N\_INSYNC\_IND successive insync indications are received from layer 1, when Node B shall trigger the RL Restore procedure indicating which radio link set has obtained synchronisation. When RL Restore has been triggered the radio link set shall be considered to be in the in-sync state. The parameter value of N\_INSYNC\_IND is configurable, see [6]. The RL Restore procedure may be triggered several times, indicating when synchronisation is obtained for different radio link sets.

Note: The total signalling response delay for the establishment of a new DPCH shall not exceed the requirements given in [8] sub-clause 7.3.

# 4.3.2.34 Synchronisation procedure BOne or several existing radio links

When one or several radio links are to be established and one or several radio links already exist, there is an existing DPCCH/DPDCH in the uplink, and at least one corresponding dedicated physical channel shall be set up in the downlink. This corresponds to the case when new radio links are added to the active set and downlink transmission starts for those radio links.

The synchronisation procedure B, which begins at the time indicated by higher layers (either immediately at receipt of upper layer signalling, or at an indicated activation time)radio link establishment is as follows:

- <u>a)</u> <u>a)</u>-<u>The following applies to aeach Node B involved in the procedure:</u>
  - -\_\_\_<u>Node B considers nN</u>ew radio link sets to be are set up to be in initial state.

- <u>If a one or several radio links is to beare</u> added to an existing radio link set, this radio link set shall be considered to be in the state the radio link set was prior to the addition of the radio link, i.e. if the radio link set was in the in-sync state before the addition of the radio link it shall remain in that state.
- b) UTRAN starts the transmission of the downlink DPCCH/DPDCH for each new radio link at a frame timing such that the frame timing received at the UE will be within  $T_0 \pm 148$  chips prior to the frame timing of the uplink DPCCH/DPDCH at the UE. Simultaneously, UTRAN establishes uplink chip and frame synchronisation of the each new radio link. Frame synchronisation can be confirmed using the frame synchronization word. Radio link sets considered to be in the initial state shall remain in the initial state until N\_INSYNC\_IND successive in-sync indications are received from layer 1, when Node B shall trigger the RL Restore procedure indicating which radio link set has obtained synchronisation. When RL Restore is triggered the radio link set shall be considered to be in the in-sync state. The parameter value of N\_INSYNC\_IND is configurable, see [6]. The RL Restore procedure may be triggered several times, indicating when synchronisation is obtained for different radio link sets.
- c) The UE establishes chip and frame synchronisation of the each new radio link. Layer 1 in the UE keeps reporting downlink synchronisation status to higher layers every radio frame according to the second phase of subclause 4.3.1.2. Frame synchronisation can be confirmed using the frame synchronization word. Downlink synchronisation status shall be reported to higher layers every radio frame according to subclause 4.3.1.2.

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- 3) With "track changes" disabled, paste the entire CR form (use CTRL-A to select it) into the specification just in front of the clause containing the first piece of changed text. Delete those parts of the specification which are not relevant to the change request.

# 7.2 Closed loop mode 1

UE uses the CPICH transmitted both from antenna 1 and antenna 2 to calculate the phase adjustment to be applied at UTRAN access point to maximise the UE received power. In each slot, UE calculates the optimum phase adjustment,  $\phi$ , for antenna 2, which is then quantized into  $\phi_Q$  having two possible values as follows:

$$\phi_{Q} = \begin{cases} \pi, & \text{if } \pi/2 < \phi - \phi_{r}(i) \le 3\pi/2 \\ 0, & \text{otherwise} \end{cases}$$
(2)

where:

$$\phi_r(i) = \begin{cases} 0, & i = 0, 2, 4, 6, 8, 10, 12, 14 \\ \pi/2, & i = 1, 3, 5, 7, 9, 11, 13 \end{cases}$$
(3)

If  $\phi_Q = 0$ , a command '0' is send to UTRAN using the FSM<sub>ph</sub> field. Correspondingly, if  $\phi_Q = \pi$ , command '1' is send to UTRAN using the FSM<sub>ph</sub> field.

Due to rotation of the constellation at UE the UTRAN interprets the received commands according to table 9 which shows the mapping between phase adjustment,  $\phi_i$ , and received feedback command for each UL slot.

# Table 9: Phase adjustments, $\phi_i$ , corresponding to feedback commands for the slots *i* of the UL radio frame

Slot #	£	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
FSM	0	0	π/2	0	π/2	0	π/2	0								
	1	π	-π/2	π	-π/2	π	-π/2	π								

The weight vector,  $w_2$ , is then calculated by sliding window averaging the received phases over 2 consecutive slots. Algorithmically,  $w_2$  is calculated as follows:

$$w_{2} = \frac{\sum_{i=n-1}^{n} \cos(\phi_{i})}{2} + j \frac{\sum_{i=n-1}^{n} \sin(\phi_{i})}{2}$$
(4)

where:

$$\phi_i \in \{0, \pi, \pi / 2, -\pi / 2\}$$
(5)

For antenna 1, the weight vector,  $w_1$ , is always:

$$w_1 = 1/\sqrt{2} \tag{6}$$

### 7.2.1 Mode 1 end of frame adjustment

In closed loop mode 1 at frame borders the sliding window averaging operation is slightly modified. Upon reception of the FB command for slot 0 of the next frame, the average is calculated based on the command for slot 13 of the previous frame and the command for slot 0 of the next frame, i.e.  $\phi_i$  from slot 14 is not used:

$$w_2 = \frac{\cos(\phi_{13}^{j-1}) + \cos(\phi_0^j)}{2} + j\frac{\sin(\phi_{13}^{j-1}) + \sin(\phi_0^j)}{2}$$
(7)

where:

-  $\phi_{13}^{j-1}$  = phase adjustment from frame j-1, slot 13.

-  $\phi_0^{j}$  = phase adjustment from frame j, slot 0.

### 7.2.2 Mode 1 normal initialisation

For the first frame of transmission UE determines the feedback commands in a normal way and sends them to UTRAN.

Before the first FB command is received, the UTRAN shall use the initial weight  $w_2 = \frac{1}{2}(1+j)$ .

Having received the first FB command the UTRAN calculates the  $w_2$  as follows:

$$w_2 = \frac{\cos(\pi/2) + \cos(\phi_0)}{2} + j \frac{\sin(\pi/2) + \sin(\phi_0)}{2}$$
(8)

where:

 $\phi_0$  = phase adjustment from slot 0 of the first frame.

### 7.2.3 Mode 1 operation during compressed mode

#### 7.2.3.1 Downlink in compressed mode and uplink in normal mode

When downlink is in compressed mode but uplink is operating normally (i.e. not compressed) the UTRAN continues it's Tx diversity related functions in the same way as in non-compressed downlink mode.

In compressed downlink transmission there are uplink slots for which no new estimate of the phase adjustment is calculated. During these slots the following rules are applied in UE when determining the feedback command:

- 1) If no new estimate of phase adjustment,  $\phi_i$ , exist corresponding to the feedback command to be send in uplink slot *i*:
  - If 1 < *i* < 15:
    - the feedback command sent in uplink slot *i*-2 is used;
  - else if i = 0:
    - the feedback command sent in uplink slot 14 of previous frame is used;
  - else if i = 1:
    - the feedback command sent in uplink slot 13 of previous frame is used;
  - end if.
- 2) When transmission in downlink is started again in downlink slot  $N_{last}+1$  (if  $N_{last}+1 = 15$ , then slot 0 in the next frame) the UE must resume calculating new estimates of the phase adjustment. The feedback command corresponding to the first new estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot  $N_{last}+1$ .

#### 7.2.3.2 Both downlink and uplink in compressed mode

During the uplink idle slots no FB commands are sent from UE to UTRAN. When transmission in downlink is started again in downlink slot  $N_{last}+1$  (if  $N_{last}+1 = 15$ , then slot 0 in the next frame) the UE must resume calculating new estimates of the phase adjustment. The feedback command corresponding to the first new estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot  $N_{last}+1$ .

The UTRAN continues to update the weight vector,  $w_2$ , until the uplink enters the compressed mode and no more FB commands are received. When the transmission in downlink resumes in slot N<sub>last</sub>+1, the value of  $w_2$  calculated after receiving the last FB command before uplink entered the compressed mode is applied to antenna 2 signal.

After UE resumes transmission in uplink and sends the first FB command the new value of  $w_2$  is calculated as follows:

- $S_1 = \{0, 2, 4, 6, 8, 10, 12 \ 14\}.$
- $S_2 = \{1, 3, 5, 7, 9, 11, 13\}.$
- i = number of uplink slot at which the transmission resumes.
- j = number of uplink slot at which the last FB command was send before uplink entered compressed mode.
- Do while  $(i \in S_1 \text{ and } j \in S_1)$  or  $(i \in S_2 \text{ and } j \in S_2)$ :
  - j = j-1;
  - if j < 0;
  - j = 14;
- end if;
- end do;
- calculate w<sub>2</sub> based on FB commands received in uplink slots i and j.

# 7.2.4 Mode 1 initialisation during compressed mode

When closed loop mode 1 is initialised during the downlink transmission gap of compressed mode there are slots for which no estimate of the phase adjustment is calculated and no previous feedback command is available.

In this case, if the UE is required to send feedback in the uplink, the FB command to the UTRAN shall be '0'.

When transmission in downlink is started again in slot  $N_{last}+1$  (if  $N_{last}+1 = 15$ , then slot 0 in the next frame), the

<u>UTRAN shall use the initial weight</u>  $w_2 = \frac{1}{2}(1+j)$ . The UE must start calculating estimates of the phase adjustment.

The feedback command corresponding to the first estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot N<sub>last</sub>+1. Having received this feedback command the UTRAN calculates  $w_2$  as follows:

$$w_{2} = \frac{\cos(\phi_{i}) + \cos(\phi_{j})}{2} + j \frac{\sin(\phi_{i}) + \sin(\phi_{j})}{2}$$
(9)

where:

 $\phi_i$  = phase adjustment in uplink slot i, which is transmitted 1024 chips in offset from the downlink slot N<sub>last</sub>+1.

$$\phi_j = \frac{\pi}{2}$$
, if slot i is even ( $i \in \{0, 2, 4, 6, 8, 10, 12, 14\}$ ) and

 $\underline{\phi_j = 0, \text{ if slot i is odd } (i \in \{1, 3, 5, 7, 9, 11, 13\})}$ 

# 7.3 Closed loop mode 2

In closed loop mode 2 there are 16 possible combinations of phase and power adjustment from which the UE selects and transmits the FSM according to table 10 and table 11. As opposed to closed loop Mode 1, no constellation rotation is done at UE and no filtering of the received weights is performed at the UTRAN.

FSM <sub>po</sub>	Power_ant1	Power_ant2
0	0.2	0.8
1	0.8	0.2

#### Table 10: FSM<sub>po</sub> subfield of closed loop mode 2 signalling message

#### Table 11: FSM<sub>ph</sub> subfield of closed loop mode 2 signalling message

FSM <sub>ph</sub>	Phase difference between antennas (radians)
000	π
001	-3π/4
011	-π/2
010	-π/4
110	0
111	$\pi/4$
101	π/2
100	3π/4

To obtain the best performance, progressive updating is performed at both the UE and the UTRAN Access point. The UE procedure shown below is an example of how to determine FSM at UE. Different implementation is allowed. Every slot time, the UE may refine its choice of FSM, from the set of weights allowed given the previously transmitted bits of the FSM. This is shown in figure 5, where, in this figure  $b_i$  (0 < i < 3) are the bits of the FSM (from table 10 and table 11) from the MSB to the LSB and m=0, 1, 2, 3 (the end of frame adjustment given subclause 7.3.1 is not shown here).

At the beginning of a FSM to be transmitted, the UE chooses the best FSM out of the 16 possibilities. Then the UE starts sending the FSM bits from the MSB to the LSB in the portion of FBI field of the uplink DPCCH during 4 (FSM message length) slots. Within the transmission of the FSM the UE refines its choice of FSM. This is defined in the following:

define the 4 bits of FSM, which are transmitted from slot number k to k+3, as {b<sub>3</sub>(k) b<sub>2</sub>(k+1) b<sub>1</sub>(k+2) b<sub>0</sub>(k+3)}, where k=0, 4, 8, 12. Define also the estimated received power criteria defined in Equation 1 for a given FSM as *P* ({x<sub>3</sub>, x<sub>2</sub> x<sub>1</sub> x<sub>0</sub>}), where { x<sub>3</sub> x<sub>2</sub> x<sub>1</sub> x<sub>0</sub> } is one of the 16 possible FSMs which defines an applied phase and power offset according to table 10 and table 11. The b<sub>i</sub>() and x<sub>i</sub> are 0 or 1.

The bits transmitted during the m'th FSM of the frame, where m=0,1,2,3, are then given by:

 $b_3(4m)=X_3$  from the { $X_3 X_2 X_1 X_0$ } which maximises *P* ({ $x_3 x_2 x_1 x_0$ }) over all  $x_3, x_2, x_1, x_0$  (16 possible combinations);

 $b_2(4m+1)=X_2$  from the { $b_3(4m) X_2 X_1 X_0$ } which maximises *P* ({ $b_3(4m) x_2 x_1 x_0$ }) over all  $x_2,x_1,x_0$  (8 possible combinations);

 $b_1(4m+2)=X_1$  from the { $b_3(4m)$   $b_2(4m+1)$   $X_1$   $X_0$ } which maximises *P* ({ $b_3(4m)$   $b_2(4m+1)$   $x_1$   $x_0$ }) over all  $x_1, x_0$  (4 possible combinations);

 $b_0(4m+3)=X_0$  from the { $b_3(4m) b_2(4m+1) b_1(4m+2) X_0$ } which maximises  $P({b_3(4m) b_2(4m+1) b_1(4m+2) x_0})$  over  $x_0 (2$  possible combinations).



#### Figure 5: Progressive Refinement at the UE for closed loop mode 2

Every slot time the UTRAN constructs the FSM from the most recently received bits for each position in the word and applies the phase and amplitude (derived from power) as defined by table 10 and table 11. More precisely, the UTRAN operation can be explained as follows. The UTRAN maintains a register  $\mathbf{z} = \{z_3 \ z_2 \ z_1 \ z_0\}$ , which is updated every slot time according to  $z_i = b_i(ns)$  (i=0:3, ns=0:14). Every slot time the contents of register  $\mathbf{z}$  are used to determine the phase and power adjustments as defined by table 10 and table 11, with FSM<sub>ph</sub> =  $\{z_3 \ z_2 \ z_1\}$  and FSM<sub>po</sub>= $z_0$ .

Special procedures for initialisation and end of frame processing are described below.

The weight vector,  $\underline{w}$ , is then calculated as:

$$\underline{w} = \begin{bmatrix} \sqrt{power\_ant1} \\ \sqrt{power\_ant2} \exp(j \ phase\_diff) \end{bmatrix}$$
(9)

### 7.3.1 Mode 2 end of frame adjustment

The FSM must be wholly contained within a frame. To achieve this an adjustment is made to the last FSM in the frame where the UE only sends the FSM<sub>ph</sub> subfield, and the UTRAN takes the power bit  $FSM_{po}$  of the previous FSM.

### 7.3.2 Mode 2 normal initialisation

For the first frame of transmission using closed loop mode 2, the operation is as follows.

The UE starts sending the FSM message from slot 0 in the normal way. The UE may refine its choice of FSM in slots 1 to 3 from the set of weights allowed given the previously transmitted bits of the FSM.

Before the first FSM message is received and during the reception of the first three FSM bits, the UTRAN Access Point shall initialise its transmissions as follows. The power in both antennas is set to 0.5. The phase offset applied between the antennas is updated according to the number and value of  $FSM_{ph}$  bits received as given in table 12.

<b>FSM</b> <sub>ph</sub>	Phase difference between antennas (radians)
	$\pi$ (normal initialisation)
	or held from previous setting (compressed mode recovery)
0	π
1	0
00-	π
01-	-π/2
11-	0
10-	π/2
000	π
001	-3π/4
011	-π/2
010	-π/4
110	0
111	π/4
101	π/2
100	3π/4

Table 12: FSM<sub>ph</sub> normal initialisation for closed loop mode 2

This operation applies in both the soft handover and non soft handover cases.

# 7.3.3 Mode 2 operation during compressed mode

### 7.3.3.1 Downlink in compressed mode and uplink in normal mode

When the downlink is in compressed mode and the uplink is in normal mode, the closed loop mode 2 functions are described below.

When the UE is not listening to the CPICH from antennas 1 and 2 during the idle downlink slots, the UE sends the last FSM bits calculated before entering in the compressed mode.

For recovery after compressed mode, UTRAN Access Point sets the power in both antennas to 0.5 until a  $FSM_{po}$  bit is received. Until the first  $FSM_{ph}$  bit is received and acted upon, UTRAN uses the phase offset, which was applied before the transmission interruption (table 12).

Normal initialisation of  $FSM_{ph}$  (table 12) occurs if the uplink signalling information resumes at the beginning of a FSM period (that is if signalling resumes in slots 0,4,8,12).

If the uplink signalling does not resume at the beginning of a FSM period, the following operation is performed. In each of the remaining slots of the partial FSM period, and for the first slot of the next full FSM period, the UE sends the first (i.e. MSB) bit of the FSM<sub>ph</sub> message, and at the UTRAN access point the phase offset applied between the antennas is updated according to the number and value of FSM<sub>ph</sub> bits received as given in table 13. Initialisation then continues with the transmission by the UE of the remaining FSM<sub>ph</sub> bits and the UTRAN operation according to table 12.

Table 13: FSM <sub>p</sub>	h subfield of closed	loop mode 2 in	compressed mode	e recovery period
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FSM <sub>ph</sub>	Phase difference between antennas (radians)
-	held from previous setting
0	π
1	0

### 7.3.3.2 Both downlink and uplink in compressed mode

During both downlink and uplink compressed mode, the UTRAN and the UE performs the functions of recovery after compressed mode as described in the previous subclause 7.3.3.1.

# 7.3.4 Mode 2 initialisation during compressed mode

When closed loop mode 2 is initialised during the downlink transmission gap of compressed mode there are slots for which no FSM bit is calculated and no previous sent FSM bit is available.

In this case, if the UE is required to send feedback in the uplink, the FB command to the UTRAN shall be '0'.

The UTRAN and the UE perform the functions of recovery after the downlink transmission gap as described in the previous subclause 7.3.3.1. If no previous phase setting is available, UTRAN shall use the phase offset  $\pi$ , until the first FSM<sub>ph</sub> bit is received and acted upon.

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#### How to create CRs using this form:

Comprehensive information and tips about how to create CRs can be found at: <u>http://www.3gpp.org/3G\_Specs/CRs.htm</u>. Below is a brief summary:

- 1) Fill out the above form. The symbols above marked **#** contain pop-up help information about the field that they are closest to.
- 2) Obtain the latest version for the release of the specification to which the change is proposed. Use the MS Word "revision marks" feature (also known as "track changes") when making the changes. All 3GPP specifications can be downloaded from the 3GPP server under <u>ftp://ftp.3gpp.org/specs/</u> For the latest version, look for the directory name with the latest date e.g. 2001-03 contains the specifications resulting from the March 2001 TSG meetings.
- 3) With "track changes" disabled, paste the entire CR form (use CTRL-A to select it) into the specification just in front of the clause containing the first piece of changed text. Delete those parts of the specification which are not relevant to the change request.

# 7.2 Closed loop mode 1

UE uses the CPICH transmitted both from antenna 1 and antenna 2 to calculate the phase adjustment to be applied at UTRAN access point to maximise the UE received power. In each slot, UE calculates the optimum phase adjustment,  $\phi$ , for antenna 2, which is then quantized into  $\phi_Q$  having two possible values as follows:

$$\phi_{Q} = \begin{cases} \pi, & \text{if } \pi/2 < \phi - \phi_{r}(i) \le 3\pi/2 \\ 0, & \text{otherwise} \end{cases}$$
(2)

where:

$$\phi_r(i) = \begin{cases} 0, & i = 0, 2, 4, 6, 8, 10, 12, 14 \\ \pi/2, & i = 1, 3, 5, 7, 9, 11, 13 \end{cases}$$
(3)

If  $\phi_Q = 0$ , a command '0' is send to UTRAN using the FSM<sub>ph</sub> field. Correspondingly, if  $\phi_Q = \pi$ , command '1' is send to UTRAN using the FSM<sub>ph</sub> field.

Due to rotation of the constellation at UE the UTRAN interprets the received commands according to table 9 which shows the mapping between phase adjustment,  $\phi_i$ , and received feedback command for each UL slot.

# Table 9: Phase adjustments, $\phi_i$ , corresponding to feedback commands for the slots *i* of the UL radio frame

Slot #		0	1	2	3	4	5	6	7	8	9	10	11	12	13	14
FSM	0	0	π/2	0	π/2	0	π/2	0								
	1	π	-π/2	π	-π/2	π	-π/2	π								

The weight vector,  $w_2$ , is then calculated by sliding window averaging the received phases over 2 consecutive slots. Algorithmically,  $w_2$  is calculated as follows:

$$w_{2} = \frac{\sum_{i=n-1}^{n} \cos(\phi_{i})}{2} + j \frac{\sum_{i=n-1}^{n} \sin(\phi_{i})}{2}$$
(4)

where:

$$\phi_i \in \{0, \pi, \pi / 2, -\pi / 2\}$$
(5)

For antenna 1, the weight vector,  $w_1$ , is always:

$$w_1 = 1/\sqrt{2} \tag{6}$$

### 7.2.1 Mode 1 end of frame adjustment

In closed loop mode 1 at frame borders the sliding window averaging operation is slightly modified. Upon reception of the FB command for slot 0 of the next frame, the average is calculated based on the command for slot 13 of the previous frame and the command for slot 0 of the next frame, i.e.  $\phi_i$  from slot 14 is not used:

$$w_2 = \frac{\cos(\phi_{13}^{j-1}) + \cos(\phi_0^j)}{2} + j\frac{\sin(\phi_{13}^{j-1}) + \sin(\phi_0^j)}{2}$$
(7)

where:

-  $\phi_{13}^{j-1}$  = phase adjustment from frame j-1, slot 13.

-  $\phi_0^{j}$  = phase adjustment from frame j, slot 0.

## 7.2.2 Mode 1 normal initialisation

For the first frame of transmission UE determines the feedback commands in a normal way and sends them to UTRAN.

Before the first FB command is received, the UTRAN shall use the initial weight  $w_2 = \frac{1}{2}(1+j)$ .

Having received the first FB command the UTRAN calculates the  $w_2$  as follows:

$$w_2 = \frac{\cos(\pi/2) + \cos(\phi_0)}{2} + j\frac{\sin(\pi/2) + \sin(\phi_0)}{2} \tag{8}$$

where:

 $\phi_0$  = phase adjustment from slot 0 of the first frame.

## 7.2.3 Mode 1 operation during compressed mode

#### 7.2.3.1 Downlink in compressed mode and uplink in normal mode

When downlink is in compressed mode but uplink is operating normally (i.e. not compressed) the UTRAN continues it's Tx diversity related functions in the same way as in non-compressed downlink mode.

In compressed downlink transmission there are uplink slots for which no new estimate of the phase adjustment is calculated. During these slots the following rules are applied in UE when determining the feedback command:

- 1) If no new estimate of phase adjustment,  $\phi_i$ , exist corresponding to the feedback command to be send in uplink slot *i*:
  - If 1 < *i* < 15:
    - the feedback command sent in uplink slot *i*-2 is used;
  - else if i = 0:
    - the feedback command sent in uplink slot 14 of previous frame is used;
  - else if i = 1:
    - the feedback command sent in uplink slot 13 of previous frame is used;
  - end if.
- 2) When transmission in downlink is started again in downlink slot  $N_{last}+1$  (if  $N_{last}+1 = 15$ , then slot 0 in the next frame) the UE must resume calculating new estimates of the phase adjustment. The feedback command corresponding to the first new estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot  $N_{last}+1$ .

#### 7.2.3.2 Both downlink and uplink in compressed mode

During the uplink idle slots no FB commands are sent from UE to UTRAN. When transmission in downlink is started again in downlink slot  $N_{last}+1$  (if  $N_{last}+1 = 15$ , then slot 0 in the next frame) the UE must resume calculating new estimates of the phase adjustment. The feedback command corresponding to the first new estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot  $N_{last}+1$ .

The UTRAN continues to update the weight vector,  $w_2$ , until the uplink enters the compressed mode and no more FB commands are received. When the transmission in downlink resumes in slot N<sub>last</sub>+1, the value of  $w_2$  calculated after receiving the last FB command before uplink entered the compressed mode is applied to antenna 2 signal.

After UE resumes transmission in uplink and sends the first FB command the new value of  $w_2$  is calculated as follows:

- $S_1 = \{0, 2, 4, 6, 8, 10, 12 \ 14\}.$
- $S_2 = \{1, 3, 5, 7, 9, 11, 13\}.$
- i = number of uplink slot at which the transmission resumes.
- j = number of uplink slot at which the last FB command was send before uplink entered compressed mode.
- Do while  $(i \in S_1 and j \in S_1)$  or  $(i \in S_2 and j \in S_2)$ :
  - j = j-1;
  - if j < 0;
  - j = 14;
- end if;
- end do;
- calculate w<sub>2</sub> based on FB commands received in uplink slots i and j.

### 7.2.4 Mode 1 initialisation during compressed mode

When closed loop mode 1 is initialised during the downlink transmission gap of compressed mode there are slots for which no estimate of the phase adjustment is calculated and no previous feedback command is available.

In this case, if the UE is required to send feedback in the uplink, the FB command to the UTRAN shall be '0'.

When transmission in downlink is started again in slot  $N_{last}+1$  (if  $N_{last}+1 = 15$ , then slot 0 in the next frame), the

<u>UTRAN shall use the initial weight</u>  $w_2 = \frac{1}{2}(1+j)$ . The UE must start calculating estimates of the phase adjustment.

The feedback command corresponding to the first estimate of  $\phi_i$  must be send in the uplink slot which is transmitted 1024 chips in offset from the downlink slot N<sub>last</sub>+1. Having received this feedback command the UTRAN calculates  $w_2$  as follows:

$$w_{2} = \frac{\cos(\phi_{i}) + \cos(\phi_{j})}{2} + j \frac{\sin(\phi_{i}) + \sin(\phi_{j})}{2}$$
(9)

where:

 $\phi_i = \text{phase adjustment in uplink slot i}$ , which is transmitted 1024 chips in offset from the downlink slot  $N_{\text{last}}+1$ .

$$\phi_j = \frac{\pi}{2}$$
, if slot i is even ( $i \in \{0, 2, 4, 6, 8, 10, 12, 14\}$ ) and

 $\underline{\phi_j = 0, \text{ if slot i is odd } (i \in \{1, 3, 5, 7, 9, 11, 13\})}$ 

# 7.3 Closed loop mode 2

In closed loop mode 2 there are 16 possible combinations of phase and power adjustment from which the UE selects and transmits the FSM according to table 10 and table 11. As opposed to closed loop Mode 1, no constellation rotation is done at UE and no filtering of the received weights is performed at the UTRAN.

FSM <sub>po</sub>	Power_ant1	Power_ant2
0	0.2	0.8
1	0.8	0.2

#### Table 10: FSM<sub>po</sub> subfield of closed loop mode 2 signalling message

#### Table 11: FSM<sub>ph</sub> subfield of closed loop mode 2 signalling message

FSM <sub>ph</sub>	Phase difference between antennas (radians)
000	π
001	-3π/4
011	-π/2
010	-π/4
110	0
111	$\pi/4$
101	π/2
100	3π/4

To obtain the best performance, progressive updating is performed at both the UE and the UTRAN Access point. The UE procedure shown below is an example of how to determine FSM at UE. Different implementation is allowed. Every slot time, the UE may refine its choice of FSM, from the set of weights allowed given the previously transmitted bits of the FSM. This is shown in figure 5, where, in this figure  $b_i$  (0 < i < 3) are the bits of the FSM (from table 10 and table 11) from the MSB to the LSB and m=0, 1, 2, 3 (the end of frame adjustment given subclause 7.3.1 is not shown here).

At the beginning of a FSM to be transmitted, the UE chooses the best FSM out of the 16 possibilities. Then the UE starts sending the FSM bits from the MSB to the LSB in the portion of FBI field of the uplink DPCCH during 4 (FSM message length) slots. Within the transmission of the FSM the UE refines its choice of FSM. This is defined in the following:

define the 4 bits of FSM, which are transmitted from slot number k to k+3, as {b<sub>3</sub>(k) b<sub>2</sub>(k+1) b<sub>1</sub>(k+2) b<sub>0</sub>(k+3)}, where k=0, 4, 8, 12. Define also the estimated received power criteria defined in Equation 1 for a given FSM as *P* ({x<sub>3</sub>, x<sub>2</sub> x<sub>1</sub> x<sub>0</sub>}), where { x<sub>3</sub> x<sub>2</sub> x<sub>1</sub> x<sub>0</sub> } is one of the 16 possible FSMs which defines an applied phase and power offset according to table 10 and table 11. The b<sub>i</sub>() and x<sub>i</sub> are 0 or 1.

The bits transmitted during the m'th FSM of the frame, where m=0,1,2,3, are then given by:

 $b_3(4m)=X_3$  from the { $X_3 X_2 X_1 X_0$ } which maximises *P* ({ $x_3 x_2 x_1 x_0$ }) over all  $x_3, x_2, x_1, x_0$  (16 possible combinations);

 $b_2(4m+1)=X_2$  from the { $b_3(4m) X_2 X_1 X_0$ } which maximises *P* ({ $b_3(4m) x_2 x_1 x_0$ }) over all  $x_2,x_1,x_0$  (8 possible combinations);

 $b_1(4m+2)=X_1$  from the { $b_3(4m)$   $b_2(4m+1)$   $X_1$   $X_0$ } which maximises *P* ({ $b_3(4m)$   $b_2(4m+1)$   $x_1$   $x_0$ }) over all  $x_1, x_0$  (4 possible combinations);

 $b_0(4m+3)=X_0$  from the { $b_3(4m) b_2(4m+1) b_1(4m+2) X_0$ } which maximises  $P({b_3(4m) b_2(4m+1) b_1(4m+2) x_0})$  over  $x_0$  (2 possible combinations).



#### Figure 5: Progressive Refinement at the UE for closed loop mode 2

Every slot time the UTRAN constructs the FSM from the most recently received bits for each position in the word and applies the phase and amplitude (derived from power) as defined by table 10 and table 11. More precisely, the UTRAN operation can be explained as follows. The UTRAN maintains a register  $\mathbf{z} = \{z_3 \ z_2 \ z_1 \ z_0\}$ , which is updated every slot time according to  $z_i = b_i(ns)$  (i=0:3, ns=0:14). Every slot time the contents of register  $\mathbf{z}$  are used to determine the phase and power adjustments as defined by table 10 and table 11, with FSM<sub>ph</sub> =  $\{z_3 \ z_2 \ z_1\}$  and FSM<sub>po</sub>= $z_0$ .

Special procedures for initialisation and end of frame processing are described below.

The weight vector,  $\underline{w}$ , is then calculated as:

$$\underline{w} = \begin{bmatrix} \sqrt{power\_ant1} \\ \sqrt{power\_ant2} \exp(j \ phase\_diff) \end{bmatrix}$$
(9)

### 7.3.1 Mode 2 end of frame adjustment

The FSM must be wholly contained within a frame. To achieve this an adjustment is made to the last FSM in the frame where the UE only sends the FSM<sub>ph</sub> subfield, and the UTRAN takes the power bit  $FSM_{po}$  of the previous FSM.

### 7.3.2 Mode 2 normal initialisation

For the first frame of transmission using closed loop mode 2, the operation is as follows.

The UE starts sending the FSM message from slot 0 in the normal way. The UE may refine its choice of FSM in slots 1 to 3 from the set of weights allowed given the previously transmitted bits of the FSM.

Before the first FSM message is received and during the reception of the first three FSM bits, the UTRAN Access Point shall initialise its transmissions as follows. The power in both antennas is set to 0.5. The phase offset applied between the antennas is updated according to the number and value of  $FSM_{ph}$  bits received as given in table 12.

FSM <sub>ph</sub>	Phase difference between antennas (radians)
	$\pi$ (normal initialisation)
	or held from previous setting (compressed mode recovery)
0	π
1	0
00-	π
01-	-π/2
11-	0
10-	π/2
000	π
001	-3π/4
011	-π/2
010	-π/4
110	0
111	$\pi/4$
101	π/2
100	3π/4

Table 12: FSM <sub>pt</sub>	h normal initialisation for closed lo	op mode 2
-----------------------------	---------------------------------------	-----------

This operation applies in both the soft handover and non soft handover cases.

# 7.3.3 Mode 2 operation during compressed mode

#### 7.3.3.1 Downlink in compressed mode and uplink in normal mode

When the downlink is in compressed mode and the uplink is in normal mode, the closed loop mode 2 functions are described below.

When the UE is not listening to the CPICH from antennas 1 and 2 during the idle downlink slots, the UE sends the last FSM bits calculated before entering in the compressed mode.

For recovery after compressed mode, UTRAN Access Point sets the power in both antennas to 0.5 until a  $FSM_{po}$  bit is received. Until the first  $FSM_{ph}$  bit is received and acted upon, UTRAN uses the phase offset, which was applied before the transmission interruption (table 12).

Normal initialisation of  $FSM_{ph}$  (table 12) occurs if the uplink signalling information resumes at the beginning of a FSM period (that is if signalling resumes in slots 0,4,8,12).

If the uplink signalling does not resume at the beginning of a FSM period, the following operation is performed. In each of the remaining slots of the partial FSM period, and for the first slot of the next full FSM period, the UE sends the first (i.e. MSB) bit of the FSM<sub>ph</sub> message, and at the UTRAN access point the phase offset applied between the antennas is updated according to the number and value of FSM<sub>ph</sub> bits received as given in table 13. Initialisation then continues with the transmission by the UE of the remaining FSM<sub>ph</sub> bits and the UTRAN operation according to table 12.

Table 13: FSM <sub>ph</sub> subfie	Id of closed loop mode	2 in compressed mode	recovery period
------------------------------------	------------------------	----------------------	-----------------

FSM <sub>ph</sub>	Phase difference between antennas (radians)
-	held from previous setting
0	π
1	0

#### 7.3.3.2 Both downlink and uplink in compressed mode

During both downlink and uplink compressed mode, the UTRAN and the UE performs the functions of recovery after compressed mode as described in the previous subclause 7.3.3.1.

# 7.3.4 Mode 2 initialisation during compressed mode

When closed loop mode 2 is initialised during the downlink transmission gap of compressed mode there are slots for which no FSM bit is calculated and no previous sent FSM bit is available.

In this case, if the UE is required to send feedback in the uplink, the FB command to the UTRAN shall be '0'.

The UTRAN and the UE perform the functions of recovery after the downlink transmission gap as described in the previous subclause 7.3.3.1. If no previous phase setting is available, UTRAN shall use the phase offset  $\pi$ , until the first FSM<sub>ph</sub> bit is received and acted upon.

		CHANGE	E REQU	EST			CR-F0III-V3
ж	25.214 CI	R 184	<sup>⊯</sup> rev 1	# Current	version:	3.6.0	ж
For <u>HELP</u> on us	sing this form, s	see bottom of thi	s page or loc	ok at the pop-up	o text over	the ¥ syn	nbols.
Proposed change a	affects: มี (	U)SIM ME	E/UE X Ra	adio Access Ne	twork X	Core Ne	twork
Title: ೫	Correction of	IPDL burst para	meters				
Source: ೫	TSG RAN WO	G1					
Work item code: %	TEI			Dat	te: ೫ 15.	May 2001	l
Category: ೫	F			Releas	se:	9	
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Reason for change	: X In the curr 256 is mis mode.	rent definition of ssing. This could	some IPDL I lead to wror	purst mode para og starting point	ameters th is of the bu	e scaling ursts in IPI	factor of DL burst
Summary of chang	e: # Correction	n in the definition	of the IPDL	burst mode pa	rameters.		
Consequences if not approved:	ж Wrong ca	Iculation of starti	ng points of	IPDL bursts.			
Clauses affected:	¥ <mark>8.2; 8.3</mark>						
Other specs Affected:	#   Other     Test s     O&M	core specification pecifications Specifications	ons X				
Other comments:	ж						

#### How to create CRs using this form:

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3) With "track changes" disabled, paste the entire CR form (use CTRL-A to select it) into the specification just in front of the clause containing the first piece of changed text. Delete those parts of the specification which are not relevant to the change request.

# 8.2 Parameters of IPDL

The following parameters are signalled to the UE via higher layers:

IP_Status:	This is a logic value that indicates if the idle periods are arranged in continuous or burst mode.
IP_Spacing:	The number of 10 ms radio frames between the start of a radio frame that contains an idle period and the next radio frame that contains an idle period. Note that there is at most one idle period in a radio frame.
IP_Length:	The length of the idle periods, expressed in symbols of the CPICH.
IP_Offset:	A cell specific offset that can be used to synchronise idle periods from different sectors within a Node B.
Seed:	Seed for the pseudo random number generator.
Additionally in the case of	burst mode operation the following parameters are also communicated to the UE.
Burst_Start:	<u>Specifies the start of the first burst of idle periods. 256×Burst_Start is</u> <u>T</u> the SFN where the first burst of idle periods starts.
Burst_Length:	The number of idle periods in a burst of idle periods.
Burst_Freq:	Specifies the time between the start of a burst and the start of the next burst. 256×Burst_Freq is <u>T</u> the number of radio frames of the primary CPICH between the start of a burst and the start of the next burst.

# 8.3 Calculation of idle period position

In burst mode, the first burst starts in the radio frame with SFN =  $256 \times Burst\_Start$ . The *n*:th burst starts in the radio frame with SFN =  $256 \times Burst\_Start + n \times 256 \times Burst\_Freq$ . The sequence of bursts according to this formula continues up to and including the radio frame with SFN = 4095. At the start of the radio frame with SFN = 0, the burst sequence is terminated (no idle periods are generated) and at SFN =  $256 \times Burst\_Start$  the burst sequence is restarted with the first burst followed by the second burst etc., as described above.

Continuous mode is equivalent to burst mode, with only one burst spanning the whole SFN cycle of 4096 radio frames, this burst starting in the radio frame with SFN = 0.

Assume that IP\_Position(x) is the position of idle period number x within a burst, where x = 1, 2, ..., and IP\_Position(x) is measured in number of CPICH symbols from the start of the first radio frame of the burst.

The positions of the idle periods within each burst are then given by the following equation:

 $IP_Position(x) = (x \times IP_Spacing \times 150) + (rand(x \mod 64) \mod (150 - IP_Length)) + IP_Offset;$ 

where rand(n) is a pseudo random generator defined as follows:

rand(0) = Seed;

 $rand(n) = (106 \times rand(n-1) + 1283) modulo 6075, n = 1, 2, 3, ....$ 

Note that *x* is reset to x = 1 for the first idle period in every burst.

Figure 6 below illustrates the idle periods for the burst mode case.



			CH	ANGE	RE	QUE	ST				CR-Form-V4
ж	25.2	2 <mark>14</mark> (	CR <mark>18</mark>	5	ж re	× _	ж	Current vers	sion:	3.6.0	ж
For <u>HELP</u> on us	sing th	is form	, see bott	om of this	s page	or look	at the	e pop-up text	t over t	he	nbols.
Proposed change a	affects	: #	(U)SIM	ME	UE X	Rad	lio Ac	cess Networ	k X	Core Ne	twork
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Source: #	TSG	RAN \	WG1								
Work item code: #	TEI							<i>Date:</i>	200	1-05-25	
Category: ₩	F Use <u>or</u> F A B C D Detaile be four	ne of the (correction) (correction) (additute) (function) (cditon)	e following ction) sponds to ion of featu ional modific inations of GPP <u>TR 21</u>	categories a correctio ire), ication of f ation) the above .900.	s: In in an feature) catego	<i>earlier r</i> e ries can	elease	Release: % Use <u>one</u> of 2 R96 R97 R98 R99 REL-4 REL-5	R99 (GSM (Relea (Relea (Relea (Relea (Relea (Relea	lowing rele Phase 2) ase 1996) ase 1997) ase 1998) ase 1999) ase 4) ase 5)	eases:
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Other comments:	ж										

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- 3) With "track changes" disabled, paste the entire CR form (use CTRL-A to select it) into the specification just in front of the clause containing the first piece of changed text. Delete those parts of the specification which are not relevant to the change request

#### 5.2.1.3 Power control in compressed mode

The aim of downlink power control in uplink or/and downlink compressed mode is to recover as fast as possible a signal-to-interference ratio (SIR) close to the target SIR after each transmission gap.

The UE behaviour is the same in compressed mode as in normal mode, described in subclause 5.2.1.2.

In compressed mode, compressed frames may occur in either the uplink or the downlink or both. In compressed frames, the transmission of downlink DPDCH(s) and DPCCH shall be stopped during transmission gaps.

The power of the DPCCH and DPDCH in the first slot after the transmission gap should be set to the same value as in the slot just before the transmission gap.

In every slot during compressed mode except during downlink transmission gaps, UTRAN shall estimate the *k*:th TPC command and adjust the current downlink power P(k-1) [dB] to a new power P(k) [dB] according to the following formula:

 $P(k) = P(k - 1) + P_{TPC}(k) + P_{SIR}(k) + P_{bal}(k),$ 

where  $P_{TPC}(k)$  is the k:th power adjustment due to the inner loop power control,  $P_{SIR}(k)$  is the k-th power adjustment due to the downlink target SIR variation, and  $P_{bal}(k)$  [dB] is a correction according to the downlink power control procedure for balancing radio link powers towards a common reference power. The power balancing procedure and control of the procedure is described in [6].

Due to transmission gaps in uplink compressed frames, there may be missing TPC commands in the uplink. If no uplink TPC command is received,  $P_{TPC}(k)$  derived by the Node B shall be set to zero. Otherwise,  $P_{TPC}(k)$  is calculated the same way as in normal mode (see sub-clause 5.2.1.2.2) but with a step size  $\Delta_{STEP}$  instead of  $\Delta_{TPC}$ .

The power control step size  $\Delta_{\text{STEP}} = \Delta_{\text{RP-TPC}}$  during RPL slots after each transmission gap and  $\Delta_{\text{STEP}} = \Delta_{\text{TPC}}$  otherwise, where:

- RPL is the recovery period length and is expressed as a number of slots. RPL is equal to the minimum value out of the transmission gap length and 7 slots. If a transmission gap is scheduled to start before RPL slots have elapsed, then the recovery period shall end at the start of the gap, and the value of RPL shall be reduced accordingly.
- $\Delta_{\text{RP-TPC}}$  is called the recovery power control step size and is expressed in dB.  $\Delta_{\text{RP-TPC}}$  is equal to the minimum value of 3 dB and  $2\Delta_{\text{TPC}}$ .

The power offset  $P_{SIR}(k) = \delta P_{curr} - \delta P_{prev}$ , where  $\delta P_{curr}$  and  $\delta P_{prev}$  are respectively the value of  $\delta P$  in the current slot and the most recently transmitted slot and  $\delta P$  is computed as follows:

 $\delta P = max (\Delta P1\_compression, ..., \Delta Pn\_compression) + \Delta P1\_coding + \Delta P2\_coding$ 

where n is the number of different TTI lengths amongst TTIs of all TrChs of the CCTrCh, where  $\Delta P1\_coding$  and  $\Delta P2\_coding$  are computed from uplink parameters DeltaSIR1, DeltaSIR2, DeltaSIRafter1, DeltaSIRafter2 signaled by higher layers as:

- $\Delta P1_{coding} = DeltaSIR1$  if the start of the first transmission gap in the transmission gap pattern is within the current frame.
- $\Delta$ Plcoding = DeltaSIRafter1 if the current frame just follows a frame containing the start of the first transmission gap in the transmission gap pattern.
- $\Delta P2\_coding = DeltaSIR2$  if the start of the second transmission gap in the transmission gap pattern is within the current frame.
- $\Delta P2\_coding = DeltaSIRafter2$  if the current frame just follows a frame containing the start of the second transmission gap in the transmission gap pattern.
- $\Delta P1$ \_coding = 0 dB and  $\Delta P2$ \_coding = 0 dB in all other cases.

and  $\Delta Pi$ \_compression is defined by :

- $\Delta Pi_compression = 3 dB$  for downlink frames compressed by reducing the spreading factor by 2.
- $\Delta Pi\_compression = 10 \log (15*F_i / (15*F_i TGL_i))$  if there is a transmission gap created by puncturing method within the current TTI of length  $F_i$  frames, where TGL<sub>i</sub> is the gap length in number of slots (either from one gap or a sum of gaps) in the current TTI of length  $F_i$  frames.
- $\Delta Pi$ \_compression = 0 dB in all other cases.

In case several compressed mode patterns are used simultaneously, a  $\delta P$  offset is computed for each compressed mode pattern and the sum of all  $\delta P$  offsets is applied to the frame.

For all time slots except those in transmissions gaps, the average power of transmitted DPDCH symbols over one timeslot shall not exceed Maximum\_DL\_Power (dB) by more than  $P_{SIR}$ , nor shall it be below Minimum\_DL\_Power (dB). Transmitted DPDCH symbol means here a complex QPSK symbol before spreading which does not contain DTX. Maximum\_DL\_Power (dB) and Minimum\_DL\_Power (dB) are power limits for one channelisation code, relative to the primary CPICH power [6].

	CHANGE REQUEST
ж	<b>25.214</b> CR <b>186 *</b> rev <b>- *</b> Current version: <b>4.0.0 *</b>
For <u>HELP</u> on us	sing this form, see bottom of this page or look at the pop-up text over the $st$ symbols.
Proposed change a	ffects: 第 (U)SIM ME/UE X Radio Access Network X Core Network
Title: ೫	DL maximum power level in compressed mode
Source: ೫	TSG RAN WG1
Work item code: ೫	TEI4 Date: # 2001-05-25
Category: ₩	ARelease: %REL-4Use one of the following categories:Use one of the following releases:F (correction)2A (corresponds to a correction in an earlier release)R96B (addition of feature),R97C (functional modification of feature)R98D (editorial modification)R99D (editorial modification)R99D tetailed explanations of the above categories canREL-4be found in 3GPP TR 21.900.REL-5
Reason for change.	: # DL maximum power level is not specified for compressed mode when an additional power offset Psir is used.
Summary of change	e: # It is clarified that the DL maximum power level (used by the RNC for admission control) can be exceeded with Psir in frames where an additional power offset Psir is to be applied due to compressed mode.
Consequences if not approved:	RNC does not know how to set the maximum downlink power for radio links that do or do not use compressed mode. Frames where the additional power offset Psir is needed would be lost.
Clauses affected:	₩ <mark>5.2.1.3</mark>
Other specs affected:	<b>%</b> Other core specifications <b>%</b> Test specifications       O&M Specifications
Other comments:	¥

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The UE behaviour is the same in compressed mode as in normal mode, described in subclause 5.2.1.2.

In compressed mode, compressed frames may occur in either the uplink or the downlink or both. In compressed frames, the transmission of downlink DPDCH(s) and DPCCH shall be stopped during transmission gaps.

The power of the DPCCH and DPDCH in the first slot after the transmission gap should be set to the same value as in the slot just before the transmission gap.

In every slot during compressed mode except during downlink transmission gaps, UTRAN shall estimate the *k*:th TPC command and adjust the current downlink power P(k-1) [dB] to a new power P(k) [dB] according to the following formula:

 $P(k) = P(k - 1) + P_{TPC}(k) + P_{SIR}(k) + P_{bal}(k),$ 

where  $P_{TPC}(k)$  is the k:th power adjustment due to the inner loop power control,  $P_{SIR}(k)$  is the k-th power adjustment due to the downlink target SIR variation, and  $P_{bal}(k)$  [dB] is a correction according to the downlink power control procedure for balancing radio link powers towards a common reference power. The power balancing procedure and control of the procedure is described in [6].

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The power control step size  $\Delta_{\text{STEP}} = \Delta_{\text{RP-TPC}}$  during RPL slots after each transmission gap and  $\Delta_{\text{STEP}} = \Delta_{\text{TPC}}$  otherwise, where:

- RPL is the recovery period length and is expressed as a number of slots. RPL is equal to the minimum value out of the transmission gap length and 7 slots. If a transmission gap is scheduled to start before RPL slots have elapsed, then the recovery period shall end at the start of the gap, and the value of RPL shall be reduced accordingly.
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 $\delta P = max (\Delta P1\_compression, ..., \Delta Pn\_compression) + \Delta P1\_coding + \Delta P2\_coding$ 

where n is the number of different TTI lengths amongst TTIs of all TrChs of the CCTrCh, where  $\Delta P1\_coding$  and  $\Delta P2\_coding$  are computed from uplink parameters DeltaSIR1, DeltaSIR2, DeltaSIRafter1, DeltaSIRafter2 signaled by higher layers as:

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- $\Delta P2\_coding = DeltaSIRafter2$  if the current frame just follows a frame containing the start of the second transmission gap in the transmission gap pattern.
- $\Delta P1$ \_coding = 0 dB and  $\Delta P2$ \_coding = 0 dB in all other cases.

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- $\Delta Pi_compression = 3 dB$  for downlink frames compressed by reducing the spreading factor by 2.
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