PL distribution, model=normal, pNom=-40.0 dB
Actual PL Normal(μ=45.0,σ=8.7)
Actual PL RV
UE est PL RV, tol= 6 dB
pdf
path loss (dB)
0
0.01
0.02
0.03
0.04
0.05
0
20
40
60
80

Distribution of pOut targets, algo=pathLossEst
actual
step 1
step 2
step 3
step 4
step 5
step 6
step 7
0
0.02
0.04
0.06
0.08
0.1
-20
-10
0
10
20

Power control error per step
step 1 STD=6.9 dB
step 2 STD=7.3 dB
step 3 STD=3.6 dB
step 4 STD=4.9 dB
step 5 STD=4.1 dB
step 6 STD=4.4 dB
step 7 STD=4.2 dB
0
0.02
0.04
0.06
0.08
0.1
0.12
0.14
-15
-10
-5
0
5
10
15

Convergence of TPC, olReq=baseline, clReq=baseline
Over all power levels
over p <= pInt
over p > pInt
Expanded TPC error
TPC step index
5
10
15
2
4
6
8
10