**3GPP TSG-RAN WG2 Meeting #116-e R2-211xxxx**

**Electronic Meeting, November 1 – 12, 2021**

**Agenda item:** 8.11.1

**Source:** InterDigital Inc.

**Title:** Email discussion report on [AT116-e][624][POS] 36.305 and 38.305 CRs for GNSS positioning integrity (InterDigital)

**Document for:**  Discussion

# 1. Introduction

This document summarizes the following email discussion:

* [AT116-e][624][POS] 36.305 and 38.305 CRs for GNSS positioning integrity (InterDigital)

Scope: Collect comments on the running CRs preparatory to endorsement.

Intended outcome: Updated CRs and report

Deadline: Tuesday 2021-11-09 0800 UTC

The discussion to be split in two phases:

**Phase 1**: To collect comments on the draft running CRs. The **deadline for Phase 1** of this email discussion is **Friday 2021-11-05, 11:59AM UTC.**

**Phase 2**: To review the updated version of the running CRs. The **deadline for Phase 2** of this email discussion is **Tuesday 2021-11-09, 08:00AM UTC**

The draft running CRs are attached with this email discussion.

Please provide the contact information in the following Table:

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| **Company** | **Point of contact** | **Email address** |
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# 2. Discussion

The scope of this email discussion is to discuss the Stage 2 description to be included in the running CRs for TS 38.305 and TS 36.305, in [1] and [2], respectively. The text proposal provided in the running CRs are based on the descriptions discussed during the [Post115-e][614][POS] email discussion [3]. The previously submitted running CRs (prior to start of RAN2#116-e meeting) are R2-2111012 [4] and R2-2111013 [5].

## 2.1 Definition of Positioning Integrity

This section is intended to handle the discussion on the definition of positioning integrity.

From the previous email discussion in [3], the need for including a definition was clarified. From the rapporteur’s understanding, it is important to have the definition since the meaning behind “positioning integrity” should be clear in the specification. It was also discussed in [3], that the definition of positioning integrity may include aspects related to “measure of trust of in accuracy of position related data” and “the ability to send alert/warnings indication”. In light of the discussions, the definition of positioning integrity is revised from that provided in the previously submitted running CRs R2-2111012 [4] and R2-2111013 [5].

The revised definition of positioning integrity is proposed as follows:

**Positioning integrity:** A measure of the trust in the accuracy of the position-related data and the ability to provide timely warnings based on assistance data provided by the network

This definition is proposed to be included in both TS 38.305 and TS 36.305, under clause 3.1. The draft CRs containing the above definition are attached with this email discussion and provided in [1] and [2].

Q1: Do you agree with the revised definition of positioning integrity to be included in TS 38.305 and TS 36.305 as shown above? If you do not agree with the revised definition, please provide your suggested changes in the comments section.

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Summary of companies’ views

## 2.2 General description on GNSS Positioning Integrity

This section is intended to handle the discussion on the TP for general description on positioning integrity for GNSS based on descriptions discussed in previous email discussion [3].

The description proposed to be included under clause 8.1.1 (GNSS positioning methods: General) of TS 38.305 is as follows:

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| When GNSS is designed to inter-work with the NG-RAN, the network assists the UE GNSS receiver to improve the performance in several respects. These performance improvements will:  ……  - allow the UE to compute and report its positioning integrity results (i.e. metrics that characterize the trust in the accuracy of its position estimate); the UE can use the integrity requirements and assistance data obtained via NG-RAN, together with its own measurements, to compute its positioning integrity results  ……  The assistance data signalled to the UE can be broadly classified into:  …….  *-    data providing means for positioning integrity results calculation* |

The description proposed to be included under clause 8.1.1 (GNSS positioning methods: General) of TS 36.305 is as follows:

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| When GNSS is designed to inter-work with the E-UTRAN, the network assists the UE GNSS receiver to improve the performance in several respects. These performance improvements will:  ……  - allow the UE to compute and report its positioning integrity results (i.e. metrics that characterize the trust in the accuracy of its position estimate); the UE can use the integrity requirements and assistance data obtained via E-UTRAN, together with its own measurements, to compute its positioning integrity results  …..  The assistance data signalled to the UE can be broadly classified into:  ……  *-    data providing means for positioning integrity results calculation* |

Q2: Do you agree with the TP on general description of positioning integrity for GNSS to be included in TS 38.305 and TS 36.305 as shown above? If you do not agree with the TP, please provide your suggested changes in the comments section.

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Summary of companies’ views

## 2.3 Supporting GNSS positioning integrity with LPP

This section is intended to handle the discussion on the TP for supporting GNSS positioning integrity with LPP based on descriptions discussed in previous email discussion [3].

The descriptions proposed to be included under clauses 8.1.3.1, 8.1.3.2 and 8.1.3.3 (Assisted-GNSS Positioning Procedures) of TS 38.305 are as follows:

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| 8.1.3 Assisted-GNSS Positioning Procedures  8.1.3.1 Capability Transfer Procedure  The Capability Transfer procedure for Assisted-GNSS positioning is described in clause 7.1.2.1.  The Capability Transfer procedure can be used to transfer capability information for positioning integrity.  8.1.3.2 Assistance Data Transfer Procedure  The purpose of this procedure is to enable the LMF to provide assistance data to the UE (e.g., as part of a positioning procedure) and the UE to request assistance data from the LMF (e.g., as part of a positioning procedure). In the case of high-accuracy GNSS positioning techniques (e.g., RTK), the LMF can provide unsolicited periodic assistance data to the UE and the UE can request periodic assistance data from the LMF.  The Assistance Data Transfer procedure can be used to transfer the assistance data for positioning integrity for UE-based mode.  **…..**  8.1.3.3 Location Information Transfer Procedure  The purpose of this procedure is to enable the LMF to request position measurements or location estimate from the UE, or to enable the UE to provide location measurements to the LMF for position calculation.  The Location Information Transfer procedure can be used to transfer integrity requirements and integrity results for positioning integrity for UE-based mode. |

The description proposed to be included under clauses 8.1.3.1, 8.1.3.2 and 8.1.3.3 (Assisted-GNSS Positioning Procedures) of TS 36.305 are as follows:

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| 8.1.3 Assisted-GNSS Positioning Procedures  8.1.3.1 Capability Transfer Procedure  The Capability Transfer procedure for Assisted-GNSS positioning is described in clause 7.1.2.1.  The Capability Transfer procedure can be used to transfer capability information for positioning integrity.  8.1.3.1.1 Void  8.1.3.2 Assistance Data Transfer Procedure  The purpose of this procedure is to enable the E-SMLC to provide assistance data to the UE (e.g., as part of a positioning procedure) and the UE to request assistance data from the E-SMLC (e.g., as part of a positioning procedure or for autonomous self location (i.e., UE determines its own location)). In the case of high-accuracy GNSS positioning techniques (e.g., RTK), the E-SMLC can provide unsolicited periodic assistance data to the UE and the UE can request periodic assistance data from the E-SMLC.  The Assistance Data Transfer procedure can be used to transfer the assistance data for positioning integrity for UE-based mode.  …..  8.1.3.3 Location Information Transfer Procedure  The purpose of this procedure is to enable the E-SMLC to request position measurements or location estimate from the UE, or to enable the UE to provide location measurements to the E-SMLC for position calculation (e.g., in case of basic self location where the UE requests its own location).  The Location Information Transfer procedure can be used to transfer integrity requirements and integrity results for positioning integrity for UE-based mode. |

Q3: Do you agree with the TP on supporting GNSS positioning integrity with LPP to be included in TS 38.305 and TS 36.305 as shown above? If you do not agree with the TP, please provide your suggested changes in the comments section.

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Summary of companies’ views

# 3 Summary

The following is the summary containing the rapporteur’s views derived from the discussion above:

# 4 Reference

1. R2-211xxx, Running CR of 38.305 GNSS Positioning Integrity (InterDigital, Inc), Nov 2021
2. R2-211xxx, Running CR of 36.305 GNSS Positioning Integrity (InterDigital, Inc), Nov 2021
3. R2-2110997, Email discussion report on [614][POS] GNSS Positioning Integrity Stage 2 CR (InterDigital)
4. R2-2111012 Running CR of 38.305 for GNSS Positioning Integrity (InterDigital, Inc), Nov 2021
5. R2-2111013 Running CR of 36.305 for GNSS Positioning Integrity (InterDigital, Inc), Nov 2021
6. 3GPP TR 38.305 NG Radio Access Network (NG-RAN); Stage 2 functional specification of User Equipment (UE) positioning in NG-RAN (Release 16), v2.0.0 Mar 2021
7. 3GPP TR 36.305 Stage 2 functional specification of User Equipment (UE) positioning in E-UTRAN (Release 16), v16.6.0 September 2021