3GPP TSG RAN WG2 Meeting #116-e R2-210xxxx

**Electronic meeting, 1st -12th November 2021**

**Agenda item:** 8.11.1

**Source:** Intel Corporation

**Title:** Report of offline discussion [AT116-e][623][POS] 38.305 CR for RAT-dependent positioning (Intel)

**Document for:**  Discussion and decision

# Introduction

This is the report of following offline discussion:

* [AT116-e][623][POS] 38.305 CR for RAT-dependent positioning (Intel)

Scope: Collect comments on the running CR preparatory to endorsement.

Intended outcome: Updated CR and report

Deadline: Tuesday 2021-11-09 0800 UTC

Rapporteur would like to split the discussion in two phases:

**Phase 1**: To collect comment on the draft running CR in R2-2109674; The **deadline for this 1st phase** of email discussion is **Friday 2021-11-05 1000 UTC (comments) .**

**Phase 2**: To check the updated version before the final deadline Tuesday 2021-11-09 0800 UTC

# Annex: companies’ point of contact

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| **Company** | **Point of contact** | **Email address** |
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# Phase 1 to collect comments on the draft running CR

The changes on Scheduled location time, storing capability in AMF are captured in section 5.4.4, 7.3.2, 7.3.3 and 7.3.4;

**Companies are invited to provide your comments on the changes shown in the running CR on Latency reduction;**

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| **Company’s name** | **Comments, if any** |
| vivo | - If no impact on section 7.3.4 is foreseen, the Editor’s Note can be removed.  - NRPPA->NRPPa in section 7.3.2, 7.3.3 |
| Apple | Some editorial corrections to the PRU text  “A Positioning Reference Unit (PRU) at a known location can perform positioning measurements (e.g., RSTD, RSRP, UE Rx-Tx Time Difference measurements, etc.) and report these measurements to a location server. In addition, the PRU can transmit SRS to enable TRPs to measure and report UL positioning measurements (e.g., RTOA, UL-AoA, gNB Rx-Tx Time Difference, etc.) from PRUs at known locations. The PRU measurements can be compared by a location server with the measurements expected at the known PRU location to determine correction terms for other nearby target devices. The DL- and/or UL location measurements for other target devices can then be corrected based on the previously determined correction terms.  From a location server perspective, the PRU functionality is realized by a UE with known location.” |
| Qualcomm | **5.4.4:**  Editorial:  "The LMF may interact with the AMF to support the provision of UE positioning capability to the AMF as described in greater detail in TS 23.273 [35]."  **7.3.2:**  **Step 2:** If a scheduled location time is provided in step 1, the LMF may not only provide assistance data to the UE "ahead of time". It may also provide a request location information, or measurement gaps, etc. "ahead of time". The meaning of "ahead of time" is also not clear. The same general sentence as in Step 3 can also be used here:  "If a scheduled location time is provided in step 1, the LMF may schedule location measurements to occur at or near to the scheduled location time."  This is a quite high-level procedure description anyway; no need to mention specific message names, etc.  **Step 3:** "via NRPPA MESREUEMENT REQUEST message" is not correct. An LMF may equally request UL E-CID measurements "ahead of time" or request SRS "ahead of time" etc. The same general sentence as for Step 2 above can be used:  "If a scheduled location time is provided in step 1, the LMF may schedule location measurements to occur at or near to the scheduled location time."  **7.3.3:**  Same comments as above |
| ZTE | 7.3.2  Step 2: If a scheduled location time is provided in step 1, the LMF may provide assistance data ahead of time and schedule location measurements to the UE via LPP RequestLocationInforamtion message at or near to the scheduled location time.  step 3: If scheduled location time is provided in step 1, the LMF may schedule location measurements to the NG-RAN via NRPPa MESREUEMENT REQUEST message at or near to the scheduled location time.  Same comments for 7.3.3 |
| Lenovo, Motorola Mobility | 7.3.2  Also share the view that “ahead of time” in Step 2 is not clear and therefore suggested rewording as follows: “If a scheduled location time is provided in step 1, the LMF may ~~provide assistance data to the UE ahead of time and~~ schedule location measurements ~~by the UE via LPP RequestLocationInforamtion message~~ to occur at or near to the scheduled location time via the LPP RequestLocationInformation message”  7.3.3  Same comment as above |

The changes on positioning in RRC\_INACTIVE are captured in section 5.2;

**Companies are invited to provide your comments on the changes shown in the running CR on positioning in RRC\_INACTIVE;**

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| **Company’s name** | **Comments, if any** |
| vivo | The following note is not entirely correct. E.g., the UL E-CID procedure in RRC\_INACTIVE is not supported as UE cannot send RRC measurement report during RRC\_INACTIVE.   |  | | --- | | NOTE: The positioning procedures between a UE and network for UEs in RRC\_CONNECTED state are also applied for UEs in RRC\_INACTIVE state using SDT. | |
| Apple | The note language can be improved as follows: “NOTE: The positioning procedures between a UE and the network for UEs in RRC\_CONNECTED state also apply for UEs in RRC\_INACTIVE state using SDT.” |
| Qualcomm | This NOTE is at a wrong place and seems also not correct. Section 5.2/Figure 5.2-1 shows the location service support by NG-RAN. As can be seen from the Figure, the positioning procedures between a UE and network are always instigated by an LMF. Therefore, SDT is not possible. The only UE triggered step is the MO-LR at Step 1c, but this is a location request and not a "positioning procedure".  RRC\_INACTIVE should be captured under 6.4 and 6.5. We only agreed that LPP and LCS messages can be transported in RRC\_INACTIVE with SDT. This affects section 6.4.2 and 6.5.2. For LCS messages, a new subsection should be added. But since there is no agreement on how to capture RRC\_INACTIVE in Stage 2 yet, an Editor's Note would be more appropriate at this stage.  In addition, the capability of just LPP/PDU message transport in RRC\_INACTIVE with SDT does not enable "positioning in RRC\_INACTIVE state". The individual steps for a positioning procedure need to be arranged such that positioning is indeed possible while the UE is in RRC\_INACTIVE. |
| ZTE | In 5.2, the note is better moved to the end of Fig 5.2-1 and those steps. We support adding a note in section 5.2, 6.4.2, 6.5.2, 6.5.3 for RRC\_INACTIVE, respectively. The note wording:  NOTE: The above positioning procedures between a UE and network for UEs in RRC\_CONNECTED state are also applied for UEs in RRC\_INACTIVE state using SDT. |
| Lenovo, Motorola Mobility | The NOTE does not seem to be appropriate for this Section and can be removed. |
| Ericsson | Abbreviation of SDT can also be added.  Further should we send RAN2 agreements and stage 2 formulation to SA2 so they capture it in their specification?  End to end details are captured in SA2 spec. So, it should be same also here. |

The changes on On-Demand PRS transmission are captured in section 7.x;

**Companies are invited to provide your comments on the changes shown in the running CR on On-Demand PRS transmission;**

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| **Company’s name** | **Comments, if any** |
| vivo | For step 6, It is not agreed that LMF can provide the updated PRS configuration used for PRS transmission via posSI to the UE. We prefer not to support this solution which may cause very frequent system information update.  Therefore, we propose to remove it in the CR.  LMF provides the updated PRS configuration used for PRS transmission via LPP Provide Assistance Data message ~~or posSI~~ to the UE. |
| Qualcomm | **Step 3:**  "the LMF may obtain assistance information, e.g. UE measurements".  The use of "assistance information" is confusing and should be deleted, since "assistance information" is usually meant to be Assistance Data. In this case it's UE measurements.  **Step 4:**  "If the LMF determines to perform on-demand PRS request,.." is not needed, since this is all what the Figure is about/shows anyhow.  **Step 5:**  "…if the request from the LMF is accepted." Is not needed, since the Figure shows the successful outcome only. I assume there will be the usual individual NRPPa message description in other sections with Request/Response/Failure.  **Step 6:**  "LMF provides the updated PRS configuration used for PRS transmission via LPP Provide Assistance Data message or posSI to the UE."  What does "or posSI" mean here? How would an LMF decide on LPP vs. posSI without knowing the UE capability for posSI? In addition, a LPP Request Assistance Data normally always results in a LPP Provide Assistance Data.  **NOTE 1** is already described at Step 3, no need to repeat.  **NOTE 2:**  The same Note is also applicable for LMF initiated on-demand PRS request. I.e., it is up to network (TRP) implementation to follow (accept/reject/ignore) on receiving LMF-initiated On-Demand PRS requests. |
| Nokia | In general, the UE-initiated on-demand PRS option is explicitly shown/described in the figure and steps where the steps are marked clearly as “In case of UE-initiated...” but the LMF-initiated on-demand PRS case is not that explicit. In our paper R2-2110956 we have a proposal 2 suggesting updates to make the LMF-initiated case also very explicit. We propose that these changes are also taken in to account in the baseline to be endorsed. Leave out proposal 1 for now as this is new and can be discussed online. |
| ZTE | Step 3 modification: The LMF determines the need for PRS transmission or change to PRS transmission characteristics. In case of LMF-initiated On-demand PRS, the LMF may obtain UE measurements, e.g. (ECID) SSB/CSI-RS RSRP measurements or (DL-AoD) DL-PRS RSRP measurements prior to step 3.  In this case note 1 is not needed.  In addition, we wonder if there is a need to separate UE-initiated and LMF-initiated on-demand PRS request procedures. If so there will be no ‘in case of UE-initiated on-demand PRS request’ or ’in case on LMF-initiated on-demand PRS request’ |
| Ericsson | Agree with Nokia we can have a step as below as mentioned in R2-2110956 and Note1 can be removed.  2b. In case of LMF-initiated on-demand PRS, the LMF may obtain measurements from the UE using some existing positioning methods to assist step 3 e.g., the LMF may obtain SSB/CSI-RS RSRP measurements (NR-ECID) or DL-PRS RSRP measurements (DL-AoD). |

The changes on PRU are captured in section 3.2 and 5.4.x;

**Companies are invited to provide your comments on the changes shown in the running CR on PRU;**

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| **Company’s name** | **Comments, if any** |
| vivo | More FFS are needed.  - FFS how to provide PRU location coordinates to the LMF.  - FFS how to enable the LMF to be aware of the PRU. |
| Qualcomm | Agree with vivo above.  - FFS PRU registration at LMF and management of PRUs |
| Nokia | We prefer that any changes to PRU section wait until we finish the email discussion [AT116-e][615]. These additional FFS can be added at the time we capture the decisions from outcome of [AT116-e][615]. |
| ZTE | Agree with Nokia |
| Lenovo, Motorola Mobility | Editorial correction:  “In addition, the PRU can transmit SRS to enable TRPs to measure and report UL positioning measurements from PRUs at a known location (e.g., RTOA, UL-AoA, gNB Rx-Tx Time Difference, etc.)”  Share Vivo’s FFS points with a minor addition:  - FFS how to provide PRU location coordinates and ensure accuracy/validity of the provided PRU location coordinates to the LMF. |
| Ericsson | Agree with Nokia |

# Summary report and proposals

# Reference

1. R2-2109673 Email discussion report on [609][POS] RAT-dependent stage 2 CR (Intel) Intel Corporation
2. R2-2109674 Email discussion [609] Running 38.305 CR for Positioning WI on RAT dependent positioning methods Intel Corporation draftCR Rel-17 38.305 16.6.0 B