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3GPP TSG RAN Rel-19 workshop **RWS-230088**

Taipei, June 15 - June 16, 2023

Agenda Item:	**5**
Source:	**Spreadtrum Communications**
Title:	**Views on Integrated Sensing and Communication in Rel-19**
Document for:	**Discussion and decision**

Background

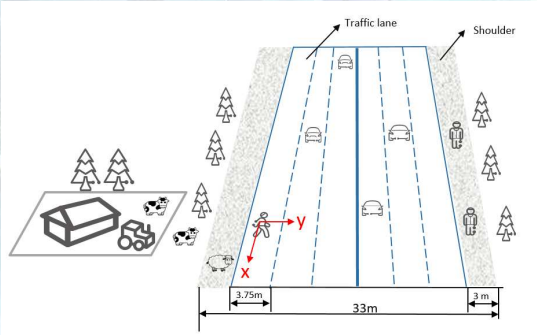
- **3GPP SA1 is working on the identification of use cases and KPIs for ISAC**
- **The identified use cases are captured in TR 22.837**

Index	Use Case	Index	Use Case
1	Intruder detection in smart home	17	Health monitoring at home
2	Pedestrian/animal intrusion detection on a highway	18	Service continuity of unobtrusive health monitoring
3	Rainfall monitoring	19	Sensor Groups
4	Transparent Sensing Use Case	20	Sensing for Parking Space Determination
5	Sensing for flooding in smart cities	21	Seamless XR streaming
6	Intruder detection in surroundings of smart home	22	UAVs/vehicles/pedestrians detection near Smart Grid equipment
7	Sensing for railway intrusion detection	23	AMR collision avoidance in smart factories
8	Sensing Assisted Automotive Maneuvering and Navigation	24	Roaming for sensing service of sports monitoring
9	AGV detection and tracking in factories	25	Immersive experience based on sensing
10	UAV flight trajectory tracing	26	Accurate sensing for automotive maneuvering and navigation service
11	Sensing at crossroads with/without obstacle	27	Public safety search and rescue or apprehend
12	Network assisted sensing to avoid UAV collision	28	Vehicles Sensing for ADAS
13	Sensing for UAV intrusion detection	29	Gesture Recognition for Application Navigation and Immersive Interaction
14	Sensing for tourist spot traffic management	30	Sensing for automotive maneuvering and navigation service when not served by RAN
15	Contactless sleep monitoring service	31	Blind spot detection
16	Protection of Sensing Information	32	Integrated sensing and positioning in factory hall

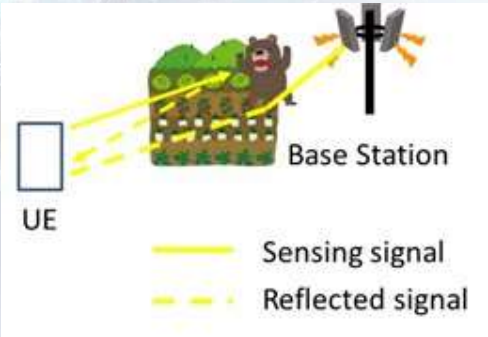
Typical use cases

- **Typical use cases for further study in Rel-19**
  - ✓ UAV: sensing for flight trajectory tracing, collision avoidance, intrusion detection
  - ✓ Smart traffic: sensing in highway, railway, crossroads, parking space
  - ✓ Smart home: intruder detection, health monitoring

UAV



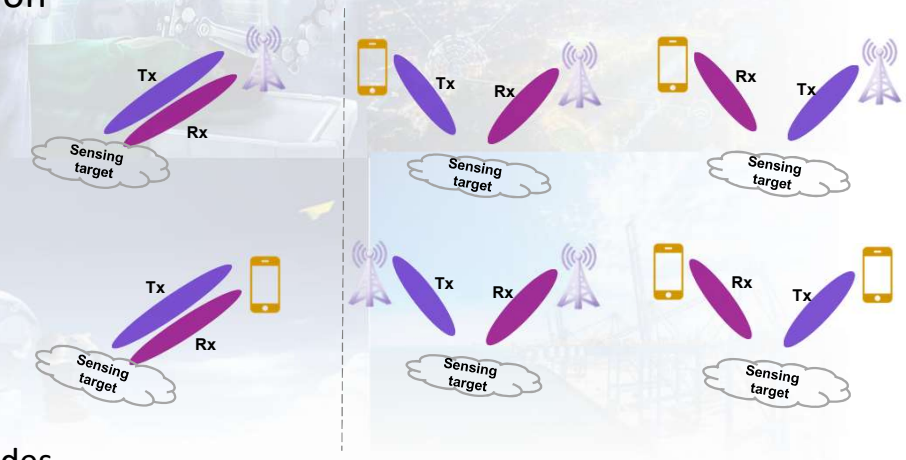
Smart traffic



Smart home

General objective

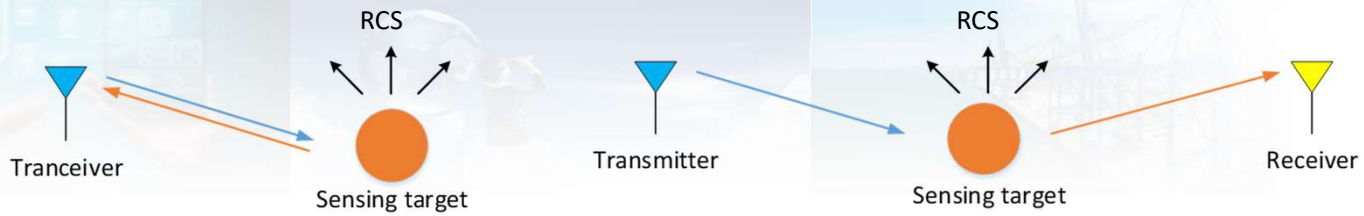
- **Justification**
  - Channel model specified in TR 38.901 has been widely used for NR communication evaluation.
  - The existing channel model cannot be directly used for sensing evaluation due to lack of modeling of sensing target.
  - Channel modeling for sensing is dependent on sensing modes.
- **General objective**
  - ➢ Study on channel modeling enhancement for sensing based on TR 38.901[RAN1]
    - ✓ Large scale fading including RCS of the sensing target
    - ✓ Small scale fading
      - ◆ Modeling of sensing path
      - ◆ Modeling of interference path from the environment
    - ✓ Study whether/how to ensure spatial consistency
    - ✓ Strive to define a unified channel model for varies sensing modes



Mono-static sensing **Bi-static sensing**

Appendix

- **Large scale fading**
  - Pathloss considering distance from transmitter to sensing target and distance from sensing target to receiver
    - ✓ Pathloss calculation can be based on TR 38.901
  - Radar Cross Section (RCS) of the target is modeled as additional large scale fading parameter
    - ✓ Randomly generated based on specific distribution, e.g. Uniform distribution, Gaussian distribution,…

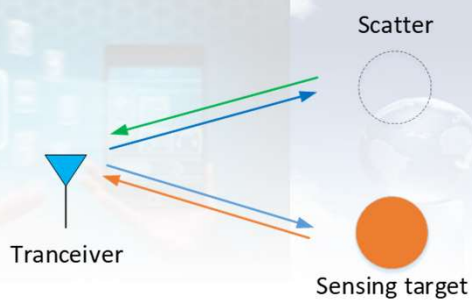


Mono-static sensing

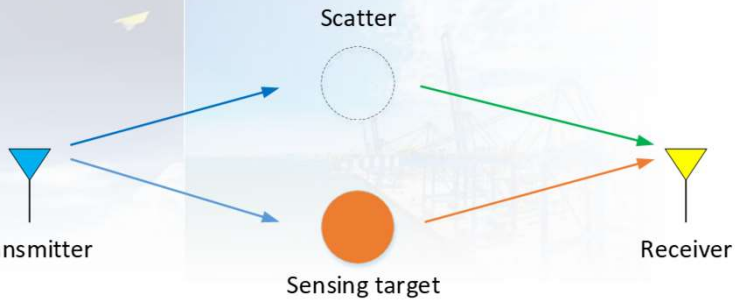
Bi-static sensing

Appendix

- **Small scale fading for single-hop assumption**
  - Step 1: Generate delay/power/angles of each cluster between **transmitter** and **receiver** according to TR 38.901.
    - ✓ For mono-static sensing: The angles are symmetrical.
  - Step 2: Calculate delay/power/angles of sensing cluster between **transmitter** and **sensing target** and between **sensing target** and **receiver** according to the location of sensing target.
  - Step 3: Replace one cluster with the sensing cluster.
  - Further steps are according to TR 38.901.



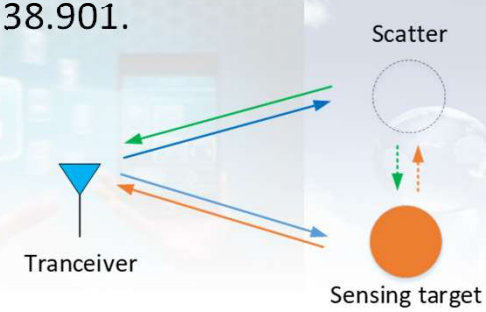
Mono-static sensing



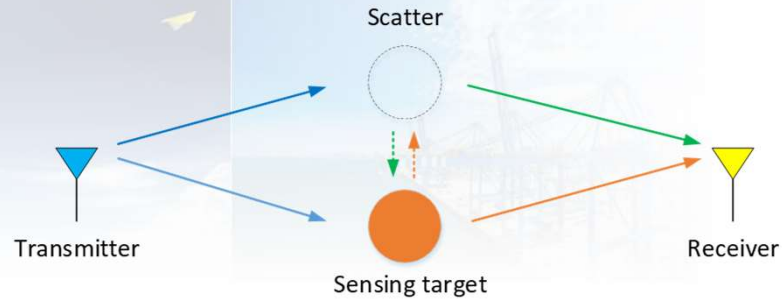
Bi-static sensing

Appendix

- **Small scale fading for multi-hop assumption**
  - Step 1: Generate delay/power/angles of each cluster between **transmitter** and **sensing target** according to TR 38.901.
  - Step 2: Identify the locations of scatters according to departure angles and delays.
  - Step 3: Calculate delay/power/angles of each cluster between **sensing target** and **receiver** including clusters that passing through the identified scatters.
    - ✓ For mono-static sensing: The reflection clusters are the same as the forward clusters.
  - Step 4: Perform random coupling of the generated clusters and calculated clusters.
  - Further steps are according to TR 38.901.



Mono-static sensing



Bi-static sensing

Thanks

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